

Effects of a Large Amount of Artificial Patterns for On-line Handwritten Japanese Character Recognition

Bin Chen[†], Bilan Zhu^{††}, Masaki Nakagawa^{††}

[†], ^{††}Tokyo University of Agriculture and Technology 2-24-16 Naka-cho, Koganei-shi, Tokyo, Japan
E-mail: [†]5001034305@st.tuat.ac.jp ^{††}{zhubilan, nakagawa}@cc.tuat.ac.jp

Abstract This paper describes effects of a large amount of artificial patterns to train an on-line handwritten Japanese character recognizer. We need a huge amount of pattern samples to train recognizers to achieve high recognition performance for on-line handwritten character recognition. However, the existing pattern samples are not enough. We construct distortion models to generate a large amount of artificial patterns and apply these artificial patterns to train a character recognizer. In experiments using the TUAT Kuchibue database, applying the generated artificial patterns to train the character recognizer has improved the character recognition accuracy remarkably. This method has improved the recognition rate to all the character groups and achieves 95.87% recognition rate for Kanji.

Key words online handwriting recognition, artificial patterns, distortion model

1. Introduction

Researches of on-line handwritten Japanese character recognition are all the while pursuing high recognition performance which can be accepted by users of real applications [1]. No matter which classifier we select, a great number of training samples are always demanded to obtain a better parameter set of a recognizer due to the fact that there are various writing habits and styles, though it is time consuming and costly to prepare a large database. Namely, samples for classifier training are limited.

To solve this problem, several works are proposed by transforming character patterns and produce artificial patterns. Ha et al [2] deform a character pattern image according to deformation models to produce pattern variations for off-line handwritten numeral recognition. Leung et al [3] generate a huge number of virtual training samples artificially for off-line handwritten Chinese characters recognition which demonstrates remarkable effectiveness.

In this paper, we extend the method of character shape transformation and use an effective distortion model to generate a great deal of artificial patterns, with which we train a handwritten Japanese character classifier and compare the results with the recognizer trained without artificial characters. Experimental results on the TUAT Kuchibue and Nakayosi databases [4, 5] demonstrate the superiority of our proposed method.

The rest of this paper is organized as follows: Section 2 gives an overview of our proposed method. Section 3 details

the transformation model and Section 4 presents the experimental results. Section 5 draws our concluding remarks.

2. Overview

Our approach is based on the modeling of the rules of writing beautifully and human writing habits.

One key idea of the transformation approach is to conform to the rules of writing beautifully. As far as calligraphy is concerned, characters should be written by following several type of transformation. Fig. 1 shows examples of transformation and the print type.



Fig 1 Handwritten style (upper) and printed style (lower)

In addition, we can get inspiration from casual writing habits as shown in Fig 2. Some people failed to write beautifully because their habits. In fact, we often face with these transformations in daily life.

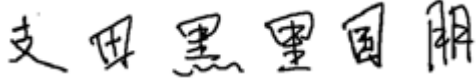


Fig 2. Real handwritten samples

To simulate these styles of transformations, we construct 6 distortion models. In the following section we will detail the proposed transformation models.

3. Distortion models

The trajectories of on-line handwritten character patterns are distorted with the six models included four basic and two combined models. Basic models are composed of rotation, shear, shrink and perspective; combined models consist of shrink with rotation and perspective with rotation. The six distortion models are given in the following.

The rotation model is given in Eq.1.

$$\begin{cases} x' = x \cos\theta - y \sin\theta \\ y' = x \sin\theta + y \cos\theta \end{cases} \quad (1)$$

Where (x', y') indicates the new coordinate transformed by the rotation model. θ denotes the angle of rotation.

The shear model can be divided into two types in X-direction and in Y-direction according to the direction of shearing. Shear model in X-direction and that in Y-direction are given in Eq.2 and Eq.3 respectively.

$$\begin{cases} x' = x + y \tan\theta \\ y' = y \end{cases} \quad (2)$$

$$\begin{cases} x' = x \\ y' = x \tan\theta + y \end{cases} \quad (3)$$

Where (x', y') is the new coordinate transformed by the shear model. θ denotes the angle of shear.

The shrink model is also divided into two types in X-direction and in Y-direction according to the direction of shrinking. Shrink model in X-direction and that in Y-direction are shown in Eq.4 and Eq.5 respectively.

$$\begin{cases} x' = x \\ y' = y \left(\sin(\pi/2 - \theta) - ((x \sin \theta)/100) \right) \end{cases} \quad (4)$$

$$\begin{cases} x' = x \left(\sin(\pi/2 - \theta) - ((y \sin \theta)/100) \right) \\ y' = y \end{cases} \quad (5)$$

(x', y') denotes the new coordinate produced by the shrink model. θ is indicator of changing degree.

The definition of the perspective model is similar to the shrink model, except the transformation function of the perspective model. The perspective model in X-direction and that in Y-direction are given in the Eq.6 and Eq.7, respectively.

$$\begin{cases} x' = 2/3 \left(x + 50 \cos(4\theta * ((x - 50)/100)) \right) \\ y' = 2/3 y \left(\sin(\pi/2 - \theta) - ((x \sin \theta)/100) \right) \end{cases} \quad (6)$$

$$\begin{cases} x' = 2/3 x \left(\sin(\pi/2 - \theta) - ((x \sin \theta)/100) \right) \\ y' = 2/3 \left(y + 50 \cos(4\theta * ((y - 50)/100)) \right) \end{cases} \quad (7)$$

Where (x', y') indicates the new coordinate transformed by the perspective model. θ denotes an indicator of changing degree.

The shrink with rotation model consists of two phases. First we do the shrink transformation according to the shrink model; further, we realize the rotation transformation based on the result produced from the first phase. Because of the same process with shrink, the perspective with rotation model is not discussed here.

The trajectories of training samples are distorted with the above functions, which greatly enlarges the size of the training set.

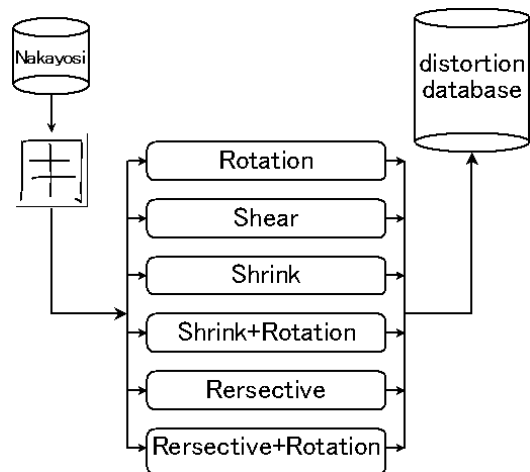


Fig 3. Flowchart of transformation

For the rotation model and shear model, θ denotes the rotation angle and the shear angle, respectively. For the shrink model and perspective model, θ is an indicator of changing degree.

The flowchart of the transformation process is shown in Fig 3.

With the above-mentioned six transformation models, the number of pattern samples in the database is enlarged from 20 to 160 times. For the rotation, we obtain artificial samples 20 times and 40 times by changing θ from -10 degree to 10 degree within every 1 degree step and within every 0.5 degree step, respectively. Similarly, for the shear in X-direction we can also enlarge the database 20 times and 40 times by changing the angle θ from -10 degree to 10 degree within every 1 degree step and within every 0.5 degree step, respectively. For the shear in Y-direction, we apply the same method to enlarge database 20 times and 40 times. So, we can totally enlarge the database 40 times and 80 times by the shear model. Like the shear model, both the shrink and perspective models can also extend the database 40 times and 80 times by changing θ from -10 degree to 10 degree within every 1 degree step and within every 0.5 degree step, respectively. For the shrink with rotation model, we change θ from -10 degree to 10 degree within every 1 degree step and within every 0.5 degree step, and for each θ we transform each sample by the shrink model firstly, and then rotate it by two rotation degrees θ and $-\theta$. Hence we totally enlarge the database 80 times and 160 times. The process of perspective with rotation is the same as the shrink with rotation model and we obtain the same amount of enlargement.

4. Experiments

To compare the performance of classifier training with and without artificial patterns, we experiment on the TUAT HANDS Nakayosi and Kuchibue database of online handwritten Japanese characters [5]. The Kuchibue database contains the handwritten samples of 120 writers, 11962 patterns per writer covering 3356 character classes. There are 11951 patterns for 3345 classes per writer. The Nakayosi database contains the samples of 163 writers, 10403 patterns covering 4438 classes per writer [4, 5]. The details of databases are shown in Table 1.

Table 1. Details of Kuchibue and Nakayosi

	Kuchibue	Nakayosi
Number fo writers	120	163
Number of classes	3,356	4,438
Numberof patterns	1,435,440	1,695,689

The Nakayosi database is used to generate artificial patterns and to train the character classifier, and the Kuchibue database is used for testing. The on-line characters recognizer adopts a linear-chain MRF model with weighting parameters optimized

by CRFs to recognize character patterns [6].

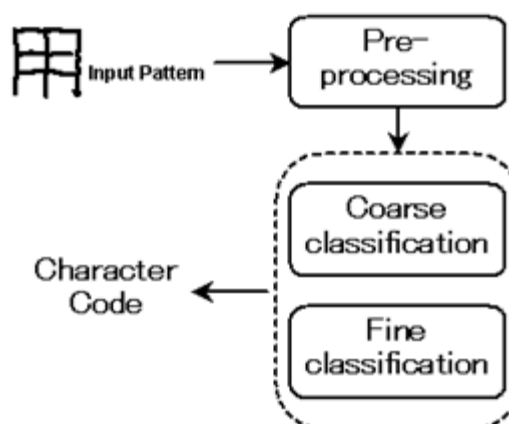


Fig 4. Flowchart of online recognizer

Table 2. Transformation methods

Model mark	Model info	Enlarge ratio	Interval degree
DM(1,20,1)	Rotation	20.00	1.00
DM(1,40,0.5)	Rotation	40.00	0.50
DM(2,40,1)	Shear	40.00	1.00
DM(2,80,0.5)	Shear	80.00	0.50
DM(3,40,1)	Shrink	40.00	1.00
DM(3,80,0.5)	Shrink	80.00	0.50
DM(4,40,1)	Perspective	40.00	1.00
DM(4,80,0.5)	Perspective	80.00	0.50
DM(5,80,1)	Shrink+Rotation	80.00	1.00
DM(5,160,0.5)	Shrink+Rotation	160.00	0.50
DM(6,80,1)	Perspective+Rotation	80.00	1.00
DM(6,160,0.5)	Perspective+Rotation	160.00	0.50

The Japanese character set consists of different types of characters: symbols, numerals, upper case English, lower case English, upper case Greek, lower case Greek, hiraganas, katakanas and Kanji characters of Chinese origin. With the above 9 character sub-sets, we get the overall performance on Kuchibue database.

In order to describe this experiment clearly, we use a transformation function with three variables $DM(m, t, \Delta)$ to show the transformation method. The first parameter m is the ID of distortion model, the second parameter t is the effect of enlargement, and the third parameter Δ is interval degree. For example, $DM(1,20,1)$ denotes a transformation method that applies the rotation model to enlarge the Nakayosi database to 20 times by changing θ from -10 degree to 10 degree within

every 1 degree step.

For parameter Δ we try two values 0.5 and 1. Therefore, we get two groups of θ .

$$\theta = \pm 1, \pm 2, \dots, \pm 10. (\Delta=1)$$

$$\theta = \pm 0.5, \pm 1, \dots, \pm 9.5, \pm 10. (\Delta=0.5)$$

Consequently, we test the twelve transformation methods as shown in Table 2.

Fig 5 illustrates some transformations of a character pattern with maximum distortion degree.

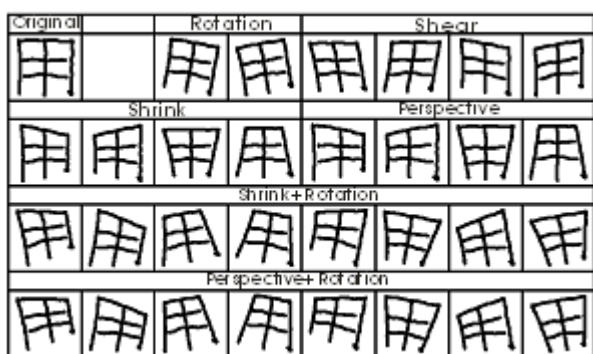


Fig 5. Illustration of transformations

In training the recognizer, the samples were processed iteratively for ten cycles. The system was implemented in MS Visual C++ 2008 with 64 bit compiler, on 64bit Windows7 and tested on two PCs. One is Intel Dual Core2 Quad Q9550 CPU with 6GB memory, and another is Intel Xeon W5590 CPU with 24GB memory. The recognition results are shown in Table 3. We can see that the recognition accuracy has been improved by training the recognizer by diversified patterns compared to the baseline classifier without using them. It shows also that enlarging the database simply by change interval degree cannot produce higher recognition rate.

Tabel 3. Recognition rate for each character sub-set

	Symbol	Numeral	Upper English	Lower English	Upper greek	Lower greek	Hira gana	Kata kana	Kanji
Original	71.73	98.20	96.92	94.23	79.75	91.33	85.39	83.01	94.84
DM(1,20,1)	73.05	98.30	97.62	94.65	84.75	92.71	85.77	83.50	95.64
DM(1,40,0.5)	72.95	98.30	97.69	94.81	82.50	92.13	85.81	83.69	95.22
DM(2,40,1)	73.14	98.50	97.54	94.76	83.75	92.38	85.72	83.65	95.65
DM(2,80,0.5)	72.91	98.60	97.65	94.96	83.25	92.42	85.73	83.31	95.59
DM(3,40,1)	73.23	98.60	97.88	94.81	83.00	92.79	85.54	83.22	95.55
DM(3,80,0.5)	72.74	98.50	97.81	94.62	83.75	92.79	85.55	83.10	95.49
DM(4,40,1)	73.41	98.30	97.73	95.19	84.25	92.79	85.96	83.86	95.72
DM(4,80,0.5)	73.01	98.10	97.73	94.88	84.50	92.83	85.71	83.57	95.66
DM(5,80,1)	73.74	98.10	97.19	95.07	84.75	93.42	85.18	83.43	95.75
DM(5,160,0.5)	73.83	98.50	97.35	94.92	85.25	93.08	85.92	83.52	95.70
DM(5,80,1)	74.26	98.20	97.42	95.12	85.75	93.63	85.86	83.59	95.87
DM(5,160,0.5)	74.03	98.40	97.58	95.00	86.50	93.33	86.17	83.83	95.81

The most important result is the recognition accuracy is

improved from 94.84% to 95.87% for Kanji characters in Kuchibue database.

5. Conclusion

We have presented an effective approach to enhance the accuracy of online handwriting Japanese recognition by using transformed training samples generated with 6 distortion models. With experiments on 9 character sub-sets of Kuchibue database, the recognition accuracies are improved for most of the sub-sets and models, which demonstrates the effectiveness of our approach. With this approach we have improved recognition accuracies without taking more time in recognition process.

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