Atlas Of Paths: a Formal Ontology of Historical Pathways in Italy^{*}

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Abstract. The *Atlas of Paths* project has two main goals: (i) the creation and implementation of an ontology network representing information contained in the MiBACT's *Atlante dei Cammini d'Italia* and defining the concept of path; (ii) the design of a prototype for a modular software platform allowing the production of the *Atlante* Linked Open Data as foreseen in its ontological formalization.

Keywords: Formal Ontology · Atlas of Paths · Cultural Heritage.

1 Introduction

The project Atlas of Paths (AoP) aims at creating and implementing a network of ontologies for representing Atlante dei Cammini d'Italia (Atlante in short), a collection of Italian paths that, from north to south, cross the country promoting a new tourist dimension. This initiative, funded by the MiBACT, is promoting a slow and green mobility infrastructure, which offers the opportunity to travel throughout Italy on foot, by bike or even on horseback. To become part of the Atlante, a path must satisfy eleven criteria³, defined by a MiBACT Committee, related to a path physical and administrative features. Those paths not meeting all the criteria are called "Paths in progress". Currently, the Atlante includes only 44 out of 116 proposed paths.

The AoP ontology is part of the *OntoPiA* ontology network⁴, as one of the result of the *Italian Digital & Analytics Framework* $(DAF)^5$, a project intended

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^{**} Route ontology was designed in collaboration with Dr. Giorgia Lodi, consultant for the Agency for Digital Italy (AgID): giorgia.lodi@agid.gov.it.

³ https://www.turismo.politicheagricole.it/en/home-cammini-ditalia/ atlas-of-paths/

⁴ https://github.com/italia/daf-ontologie-vocabolari-controllati

⁵ https://teamdigitale.governo.it/en/projects/daf.htm

2 L. Asprino et al.

to improve the interoperability between Italian public administrations by defining a shared conceptualization of data and promoting the adoption of Open Data. For modeling AoP we benefit from reusing some ontological modules from *OntoPiA*, namely: L0, which defines top-level concepts (e.g. Event, Object etc.); CVL, as the ontology on addresses and places; POI, on points of interests; ACCO, on accommodation facilities; TI, on the temporal dimension of concepts; MU, on the measurement units.

2 Methodology

How to describe a Path? This theoretical question summarizes 25 competency questions (CQs) - a common tool for defining modeling requirements to be satisfied by a ontology [3] - that guided the design of AoP ontology. Following the eXtreme Design method [1], we used CQs as a support to recognize potential Ontology Design Patterns [2] to be reused. Our CQs has been elicited from both the documentation available from the Atlante and for each path therein collected.

The CQs led us to design two networked ontological modules: (i) Route⁶, which is a general conceptualization for supporting the domain ontology; (ii) Atlas of Paths⁷, which defines more specific concepts imported by the supporting ontology.

2.1 Route Ontological Module

Taking into account the modelling of *Semantic Trajectories* [4], which applies to the scenarios of personal travel and wildlife monitoring, in **Route** ontological module we define general concepts that are shared by all routes (e.g. their stages) and associated to a possible trip plan.

The class :Route is defined as an intersection of LO:Sequence, which represents a sequence of ordered objects, and LO:Description, which represents socially constructed objects (i.e. texts, values, categories, relationships, contexts) used to describe something else in a structured way. In addition, an instance of :Route can be connected by means of CLV:hasGeometry to an instance of CLV:Geometry, which provides the possibility of georeferencing a spatial object through CLV:lat (latitude) and CLV:long (longitude). The object property (op) :crosses allows to connect a :Route to any object having a spatial representation, so that it is possible to assert that a pathway crosses a certain area.

The class :Stage represents the elements of a :Route. Stages ordering of a route allows to identify the direct successor and predecessor of a stage through LO:directlyFollows and LO:directlyPrecedes. Georeferencing can also be associated with a stage by reusing the CLV module.

The class :TripPlan represents a travel plan for a specific route by means of :hasRoute. It is modeled by associating a certain trip time with the traveled route through :hasEstimatedDuration. In addition, a trip plan can be split into sub-trip plans through :hasSubTripPlan.

⁶ https://w3id.org/italia/onto/Route

⁷ https://w3id.org/italia/onto/AtlasOfPaths

2.2 Atlas of Paths Ontological Module

The concepts defined in the Route module are specialized in AoP, as depicted in Figure 1.

The class :Pathway, defined as a subclass of Route:Route, describes a pathway in its physical meaning. E.g., since a path to be included in the *Atlante* must be paved in asphalt for a maximum of 40% of its total length, the :QuantifiedPathwayPaving represents the n-ary relation able to quantify the MU:maxPercentage of a :Pathway (op :forPathway) with a specific :Paving (op :withPaving), represented as the instance :asphalt. In Manchester Syntax:

:Pathway subClassOf inverse(:forPathway)

only ((:withPaving value :asphalt) and (MU:maxPercentage exactly 1 xsd:double[<"40.0"8sd:double])).</pre>

The class :PathStage, a subClassOf Route:Stage, is associated with :SupportService, representing any walker support services, defined by :hasService Type. A path stage is also associated with some POI:PointOfInterest, e.g. hotel facilities, represented by ACCO:Accommodation, and catering activities, represented by :Restaurant.

The class :PathPlan, a subClassOf Route:TripPlan, is a n-ary relation with three arguments: (i) :TravelingMethod which can be either on foot, on horseback, or by bicycle; (ii) TI:TemporalEntity, which specifies which period of the year is most suitable for planning the journey, and linked to a :PathPlan by means of :bestWhen.

The class :Path is the main and peculiar one of the *Atlante* domain. A :Path can be associated with one or more :Pathway, through Route:hasRoute. In addition, its sub-properties Route:hasPreRoute, Route:hasAltRoute and Route:hasDeviation allow to associate a :Path to a :Pathway so that it can be identified as the main path, an alternative or a deviation, respectively. These arguments contribute to strongly define the concept of :Path, which implies the possibility of choosing at each :PathStage to change the :Pathway.

2.3 Linked Open Data Production

We designed a modular software platform⁸ for supporting data-entry by users proposing new Italian paths to be evaluated by the MiBACT Committee. This platform prototype provides a series of input forms that guide users in filling the necessary information to describe a path as foreseen in its ontological formalization. It has been implemented according to the *Model-View-Controller* pattern. The use of this pattern allows to implement: (i) the *Model* as the ontologies themselves; (ii) the *View* as the input forms; (iii) the *Controller* as a software module (implemented in PHP) to generate a pipeline of input forms based on the logical representation defined in the ontology.

⁸ http://wit.istc.cnr.it/atlas-of-paths/upload-form.html



Fig. 1. Atlas of Paths visualization provided by WebVOWL.

3 Conclusion and Future Work

The AoP project has brought the following results: (a) a formal ontology defining the concept of path; (b) a prototype for a modular software platform to perform a LOD production consistent with the AoP ontology.

In addition to the progressive LOD production by means of the data-entry, it will be possible to link AoP with other datasets already available as LOD, such as Cultural-ON⁹, ArCo¹⁰ and FOOD¹¹ representing Italian assets of cultural heritage and food products in those areas that are crossed by a given path.

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⁹ http://dati.beniculturali.it/cis/

¹⁰ https://w3id.org/arco

¹¹ http://etna.istc.cnr.it/food/