

## ON THE DYNAMICAL SINGLE-PARTICLE BASIS IN LARGE AMPLITUDE COLLECTIVE MOTIONS

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We aim at describing large amplitude collective nuclear motion in a dynamical single-particle basis which is the most reasonable approximation to the time-dependent single-particle Schrödinger equation

$$i\hbar \frac{\partial}{\partial t} \psi_\alpha = h(x, q) \psi_\alpha \quad (1)$$

Eq. (1) usually is solved within the adiabatic representation  $|\phi_n\rangle$

$$h_0(x, q) |\phi_n(x, q)\rangle = \epsilon_n(q) |\phi_n(x, q)\rangle \quad (2)$$

which, however, is only applicable for small collective velocities  $\dot{q}$  and if no quasicrossings of the adiabatic levels  $\epsilon_n(q)$  occur.<sup>1)</sup> For somewhat larger collective velocities  $\dot{q}$ , i.e. within the range of collective kinetic energy per nucleon of

$$\frac{1}{20} \text{ MeV} \leq E_{\text{coll}}/A \ll 40 \text{ MeV}, \quad (3)$$

a diabatic basis<sup>2)</sup> is more physical because in the vicinity of quasicrossings it includes jump probabilities close to 1 in a nonperturbative way. Assuming  $q(t)$  to be a given function of time, eq. (1) can be cast into the form

$$[h_0(x, q) - i\hbar \frac{\partial}{\partial q}] \tilde{\psi}_\alpha(q) = 0, \quad (4)$$

which allows further interesting approximations with respect to a static basis.

For small  $\dot{q}$  an optimal representation of  $\tilde{\psi}_\alpha(q)$  is given by

$$|\tilde{\psi}_\alpha\rangle = \sum_n C_{\alpha n} |\phi_n\rangle, \quad (5)$$

where the coefficients  $C_{\alpha n}$  are determined by the eigenvalue equation

$$\sum_n \langle \phi_n | h_0 - i\hbar \frac{\partial}{\partial q} | \phi_n \rangle C_{\alpha n} = E_\alpha C_{\alpha n} \quad (6)$$

and meet the limiting conditions

$$\lim_{\dot{q} \rightarrow 0} C_{\alpha n} = \delta_{\alpha n} \quad (7a)$$

$$\lim_{\dot{q} \rightarrow 0} \frac{\partial C_{\alpha n}}{\partial \dot{q}} = \lim_{\dot{q} \rightarrow 0} \left\{ \frac{\partial a_{\alpha n}}{\partial \dot{q}} \dot{q} + \sigma(\dot{q}^2) \right\} = 0 \quad (7b)$$

with  $a_{\alpha n} = \frac{\partial C_{\alpha n}}{\partial \dot{q}}$ .

Returning to the initial value problem (1) and expanding

$$|\psi_\alpha\rangle = \sum_n d_{\alpha n} |\tilde{\psi}_n\rangle e^{-i/\hbar \int_0^t E_n(t') dt'} \quad (8)$$

we obtain

$$\dot{d}_{\alpha n} = -\dot{q}^2 \sum_\gamma d_{\alpha \gamma} \left( \sum_n C_{\beta n} \frac{\partial a_{\beta n}}{\partial \dot{q}} \right) e^{-i/\hbar \int_0^t (E_\gamma - E_n) dt'}, \quad (9)$$

which is an improvement of the cranking model (CM) because the time evolution of the expansion coefficients is proportional to  $\dot{q}^2$  (instead of  $\dot{q}$  in the CM).

For collective velocities within the range (3) the adiabatic s.p. wavefunctions  $\phi_n(q)$  in eqs. (5,6) should be replaced by the diabatic s.p. wavefunctions  $X_n(q)$ <sup>2)</sup> and the s.p. Hamiltonian  $h_0$  by a diabatic Hamiltonian  $h = h_0 + h'$  in order to account for jump probabilities close to 1 in the neighborhood of quasicrossings.

Eq. (9) again holds in this case except an extra term proportional to matrix elements of  $h'$ .

For the collective degree of quadrupole deformation eq. (6) can be solved analytically in the deformed harmonic oscillator model<sup>3)</sup>, which is well suited for a study of diabatic motion because  $\hbar \dot{q} \ll \hbar \omega$  in this case, i.e.

$$h_0 = i\hbar \dot{q} \frac{\partial}{\partial q} = \sum_{i=x,y,z} \hbar \omega_i (b_i^\dagger b_i + \frac{1}{2}) \quad (10)$$

with

$$\omega_i = \omega_i \sqrt{1 - \xi_i^2} \quad (i = x, y, z) \quad (11)$$

$$\xi_i^2 = \left( \frac{K_i \dot{q}}{2\omega_i} \right)^2, \quad K_x = K_y = \frac{1}{2\dot{q}}, \quad K_z = \frac{1}{\dot{q}},$$

$$q = \frac{u_0}{\alpha_z}$$

and

$$\tilde{\psi}_n = N_n e^{-(\alpha_x^2 x^2 + \alpha_y^2 y^2 + \alpha_z^2 z^2)} e^{-i/\hbar W_n(x, y, z; \dot{q})} \cdot \bar{W}_n(x, y, z) \quad (12)$$

with  $\alpha_i^2 = \frac{m\omega_i}{\hbar}$ .

In eq. (12)  $\bar{W}_n$  is a polynomial of order  $n$  with complex coefficients and does not contain significant phases as a function of  $\dot{q}$ ,  $\ddot{q}$ , .... The essential phase is given by the velocity potential

$$\Phi(x, y, z) = \frac{\dot{q}}{2} (x^2 + y^2 - 2z^2) \quad (13)$$

and implies incompressible irrotational flow. The mass parameter for quadrupole motion

$$B(q, \dot{q}) = \frac{\hbar}{\dot{q}} \sum_{i=x,y,z} \frac{K_i^2 N_i}{\alpha_i} \quad (14)$$

with

$$N_i = \sum_{j=1}^A \langle |b_i^\dagger b_i + \frac{1}{2}| \rangle_j \quad (15)$$

reduces to the cranking formula for  $\dot{q} = 0$ . For large velocity  $\dot{q}$  and extreme oblate deformation (small  $q$ ) the quantities  $\xi_i^2$  become comparable to 1 and  $B(q, \dot{q})$  increases significantly. The variations of  $B(q, \dot{q})$  with respect to  $q$  and  $\dot{q}$  in the diabatic approximation (i.e.  $N_i \neq N_i(q, \dot{q})$ ) are demonstrated in Fig. 1 via the ratio of  $B(q, \dot{q})$  with the cranking mass parameter  $B_{\text{CM}}$ .

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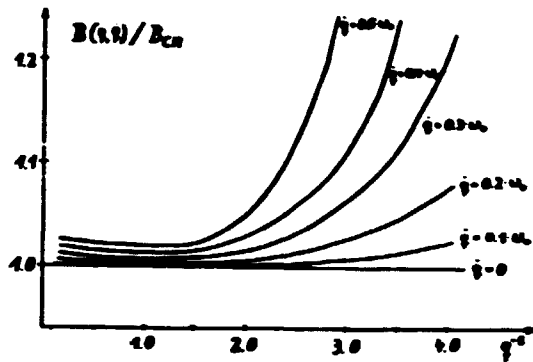


Fig. 1

For reasonable deformations  $0.4 \leq 1/q = u_z/u_0 \leq 1.5$  the deviation between  $B(q, \dot{q})$  and the cranking mass is less than 3% up to collective velocities  $\dot{q} \sim R$  which are half of the typical s.p. velocity  $u_0 \sim R$  ( $R =$  nuclear radius). This demonstrates that the cranking mass with respect to diabatic s.p. motion does not cause problems in case of nuclear deformation.

## References:

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