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$Z_N^{\otimes n-1}$ broken model

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Abstract

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Using the ψ -vectors method for the Belavin elliptic R matrix we obtain the A_{n-1} generalization of the Kashiwara-Miwa model.

Аннотация

С.М.Сергеев. Диумерная статистическая модель с нарушенной $Z_N^{g,n-1}$ инвариантностью: Препринт ИФВЭ 92-7. — Протвина, 1992. — 4 с., библиогр.: 6.

Используя метод ψ -векторов для эллиптической R -матрицы Белавина мы получаем A_{n-1} обобщение модели Кашивары-Мивы.

This work is inspired by the $Z_N^{\otimes n-1}$ generalization of the chiral Potts model (the BKMS model) [1]. In the limit $K_{n\theta} = 1$ this model becomes the A_{n-1} generalization of the Fateev–Zamolodchikov model [2]. The latest one admits the elliptic deformation [3]. It is natural to look for an elliptic extension of the limit of BKMS model, using the method, developed in [1], for the elliptic ψ -vectors [4] of the Belavin R -matrix [5].

Hereafter we shall borrow the notations for algebra structures from [4]. Let ε_μ be a basis of R^n . Denote

$$\hat{\mu} = \varepsilon_\mu - \varepsilon, \quad \varepsilon = \sum_{\mu=0}^{n-1} \varepsilon_\mu$$

Let

$$a = \sum_{\mu=0}^{n-1} a^\mu \varepsilon_\mu, \quad a^\mu \in C$$

$$a = a_0 + \zeta, \quad \sum_\mu a_0^\mu = 0, \quad a_0^\mu \in Z/n$$

So a_0 is a weight of A_{n-1} , ζ is arbitrary and fixes the class of a .

For the Belavin R -matrix [5]

$$R(z) = \sum_{\alpha+\beta=\gamma+\delta} R_{(\gamma-\alpha)}^{(\delta-\alpha)} E_{\gamma\alpha} \otimes E_{\delta\beta} \quad (1)$$

where

$$R_{(y)}^{(x)} = \frac{h(z)\theta^{(x-y)}(z+\lambda, r)}{\theta^{(x)}(z, r)\theta^{(-y)}(\lambda, r)}$$

$$h(z) = \frac{\prod_{j=0}^{n-1} \theta^{(j)}(z, r)}{\prod_{j=1}^{n-1} \theta^{(j)}(0, r)}$$

$$\theta^{(j)}(z, \tau) = \theta \left[\frac{1}{2} - \frac{j}{n} \right] (z, \tau)$$

there exist the ψ - vectors [4]

$$\psi_a^{(\mu)}(z)_\alpha = \psi_a^{(\mu)} \theta^{(\alpha)}(z - n\lambda a^\mu, \tau) \quad (2)$$

such that the following equation holds [4]:

$$\sum_{\gamma, \delta} R_{\alpha, \beta}^{\gamma, \delta} (z_1 - z_2) \psi_{a-\hat{\mu}}^{(\mu)}(z_1), \psi_a^{(\nu)}(z_2)_\delta = \\ = \sum_k W \left[\begin{array}{cc} a - \hat{\mu} & a - \hat{\nu} + \hat{k} \\ a & a + \hat{\nu} \end{array} \right] (z_1 - z_2) \psi_{a-\hat{\mu}+\hat{k}}^{(\mu+\nu-k)}(z_1)_\alpha \psi_{a-\hat{\mu}}^{(\nu)}(z_2)_\beta \quad (3)$$

Define the inverse vectors $\bar{\psi}_c^{(\mu)}(z)^\alpha$ by the relation:

$$\sum_{\alpha=0}^{n-1} \bar{\psi}_d^{(\mu)}(z)^\alpha \psi_d^{(\nu)}(z)_\alpha = \delta_{\mu\nu} \quad (4)$$

Now one has to distinguish the classes of face spins a . We shall write (a, ζ) instead of a .

Following [1] introduce the ϕ - vectors through the relations:

$$\phi_{a, \zeta}^{(\mu)}(z)_\alpha = \psi_{a, \zeta}^{(\mu)}(-n\lambda - z)_\alpha \quad (5)$$

$$\sum_\alpha \bar{\phi}_{a-\hat{\mu}, \zeta}^{(\mu)}(z)^\alpha \phi_{a-\hat{\nu}, \zeta}^{(\nu)}(z)_\alpha = \delta_{\mu\nu}$$

where constant numbers $\psi_a^{(\mu)}$ have to be chosen so that

$$W \left[\begin{array}{cc} a - \hat{\mu} & a - \hat{\nu} + \hat{k} \\ a & a + \hat{\nu} \end{array} \right] (z) = W \left[\begin{array}{cc} a - \hat{\mu} & a \\ a - \hat{\nu} + \hat{k} & a + \hat{\nu} \end{array} \right] (z) \quad (6)$$

Note, that the condition for

$$\mathcal{L}_{\alpha\beta} = \bar{\psi}_{a, \zeta}^{(\mu)}(z)^\alpha \psi_{a, \zeta}^{(\mu)}(z)_\beta \quad (7)$$

to be the \mathcal{L} - operator for (1) is $\zeta^\mu = \zeta^\mu + u$.

In the spirit of [1] we define W by the relation

$$W_{\zeta\zeta'}(a, b) \sum_\alpha \psi_{a, \zeta}^{(\mu)}(z)_\alpha \bar{\psi}_{b, \zeta'}^{(\nu)}(z)^\alpha = W_{\zeta\zeta'}(a + \hat{\mu}, b + \hat{\nu}) \sum_\alpha \bar{\phi}_{a, \zeta}^{(\mu)}(z)^\alpha \phi_{b, \zeta'}^{(\nu)}(z)_\alpha \quad (8)$$

The other equations for W follow from (8).

The conditions for W to be independent of z read

$$\begin{aligned}\zeta' &= \zeta + u, \quad \sigma(\zeta) = \zeta, \quad \sigma(\zeta') = \zeta - u \\ 2\lambda \sum_{\alpha} \zeta^{\alpha} &= t \frac{\tau}{n} + s + \lambda(n-1)\end{aligned}\tag{9}$$

We shall choose the simply solution to (9):

$$\zeta^{\alpha} = \frac{\alpha}{n}, \quad t = s = 0$$

In order to write down the solution to (8) denote

$$\begin{aligned}f_{\lambda}(z) &= f(\lambda z) \text{ for any } f(z) \\ h_{\lambda}(z) &= \theta_{\lambda}^{(0)}(z, \frac{\tau}{n}) \\ D(a) &= \prod_{\alpha < \beta} \frac{h_{\lambda}(a^{\alpha} - a^{\beta})}{h_{\lambda}(\zeta^{\alpha} - \zeta^{\beta})}\end{aligned}\tag{10}$$

The solution to (8) reads

$$\frac{W(a + \hat{\mu} - \hat{\nu}, b)}{W(a, b)} = \sqrt{\frac{D(a + \hat{\mu} - \hat{\nu})}{D(a)}} \prod_{\alpha} \frac{h_{\lambda}(a^{\mu} - b^{\alpha} - u)}{h_{\lambda}(a^{\nu} - b^{\alpha} - 1 - u)}\tag{11.a}$$

$$\frac{W(a, b + \hat{\nu} - \hat{\mu})}{W(a, b)} = \sqrt{\frac{D(b + \hat{\nu} - \hat{\mu})}{D(b)}} \prod_{\alpha} \frac{h_{\lambda}(b^{\mu} - a^{\alpha} + u)}{h_{\lambda}(b^{\nu} - a^{\alpha} + 1 + u)}\tag{11.b}$$

up to the gauge provides the cyclicity in the case

$$\lambda = \frac{p - p'\tau}{N}, \quad p \text{-a prime number}\tag{12}$$

The deformation of $K = 1$ BKMS model can be obtained when $\lambda = 1/N - \tau/n$. Note, that cases of complex λ can be obtained by modular transformation of real λ cases, so we choose $\lambda = 1/N$ without loss of generality.

The W -weights (11) obey the unitarity relation

$$\sum_{\{l\}} \frac{W_u(m, l) W_{-u}(l, k)}{W_u(0, 0) W_{-u}(0, 0)} = \delta_{mk} \Phi(u)$$

where

$$\Phi(u) = \frac{\theta_{\lambda}^{(0)}(nNu, N\tau') \prod_{k=0}^{n-1} \theta_{\lambda}^{(0)}(u + \frac{k}{n} - 1, \tau')^k \theta_{\lambda}^{(0)}(\frac{k}{n} + u, \tau')^{n-k}}{\theta_{\lambda}^{(0)}(nu, \tau')^n}\tag{13}$$

up to a constant factor, providing $\Phi(0) = 1$, $r' = \frac{r}{n}$. The function Φ is obtained for the subset of integer spins a : $a_0^{\mu} \in \mathbb{Z}$.

As it is shown by R.Kashaev (private communication, see also [6]), the Yang-Baxter equation for factorized S matrix, intertwining the \mathcal{L} operators (7), is equivalent to the Star-Star Relation

$$\begin{aligned} \frac{W_{q-q'}(m_3, m_2)}{W_{q-q'}(m_4, m_1)} \sum_p \frac{W_{q-p}(g, m_1) W_{p-q'}(m_4, g) W_{q'-p}(g, m_3)}{W_{q-p}(g, m_2)} = \\ \frac{W_{p-p'}(m_4, m_3)}{W_{p-p'}(m_1, m_2)} \sum_g \frac{W_{q-p}(m_3, g) W_{p-q}(g, m_2) W_{q'-p}(m_1, g)}{W_{q-p}(m_4, g)} \end{aligned} \quad (14)$$

that we have checked numerically together with the Yang-Baxter equation itself and found them true.

The most interesting feature of BKMS model is the equivalence to the generalization of $3-d$ Zamolodchikov model [7]. Unfortunately the elliptic deformation in sense of $3-d$ model includes interactions among all the spines along $1-d$ chain and seems to be nonlocal.

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