KAERI/TR-2583/2003

Structural Review of In-Vessel Fuel Transfer Equipment in large size LMR



2003 "

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(Structural Review of In-Vessel Fuel Transfer Equipment in large size LMR)



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ABSTRACT

In case the power of KALIMER is increased by the large size, the structural concept of In-Vessel Fuel Transfer Equipment was suggested and reviewed. The core size is expanded due to increasing of the electric power 150 MWe to 600 MWe. The size of rotating plug and the method of the fuel transfer were evaluated by assuming the increased core size. Also, among the various evaluated concepts two concepts were selected and the marginal length of the arm for the pantograph type IVTM was analysed.

The model configuration of IVTM is fully extended condition of the pantograph arm. In this condition, the loads considered are the weight of the core assembly, self weight and reaction force for the withdrawal of the core assembly. The structural analysis of IVTM was carried out by the finite element analysis using ANSYS code. The stress and deformation were calculated to the the refueling and seismic loads for the section variation of the components considered as the design parameters of IVTM.





16	1.
17	2.
	3.
	4.
(Grapple/ 0.2 m x 0.2 m)30	5.
(Grapple/ 0.3 m x 0.3 m)30	6.

20
21
22
22
23
24
25
27
29
31
32
33

19. OBE	(grapple/0.2x0.2, link/ 0.2x01)
20. SSE	(grapple/0.2x0.2, link/ 0.2x0.1, 1.82m)
21. SSE	(grapple/0.2x0.2, link/ 0.2x0.1, 1.82m)37
22. SSE	(grapple/0.2x0.2, link/ 0.2x0.1, 2.74m)38
23. SSE	(grapple/0.2x0.2, link/ 0.2x0.1, 2.74m)
24. SSE	(grapple/0.2x0.2, link/ 0.2x0.2)40
25. SSE	(grapple/0.2x0.2, link/ 0.2x0.2)41
26. SSE	(grapple/0.3x0.3, link/ 0.3x0.2)42
27. SSE	(grapple/0.3x0.3, link/ 0.3x0.2)43





(In-Vessel Fuel Transfer Equipment)

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가

A-Frame type

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MDP (Modular Double Pool) . . 325MWe . A-, , Frame type 가 . A-Frame type 가 가 가 가 containment dome Phenix, Superphenix SAFR(Sodium Advanced Fast Reactor) . 가 가 . 가 가 가 가 가 가 가 . 0 가 Pantograph arm Offset arm . 1 . 2.1.2

> 가, A-Frame type, . KALIMER-150

cover



2. CRD(Control Rod Drive)

- 3.
- 4.
- 5. CRD
- 6.





(3) 2 , 1 offset arm

offset arm









Interface

.

[3].

,

,

	():			20		
	():		30		
-						6	
. IVTM	tube						
. Telesc	opic tube						
. Pantog	raph arm						
. Grappl	e						
. Grappl	e finger						
. Grappl	e head				1		
-					T	receptacle	,
-					thermal	striping	
-			X				
		/					
		/	telesco	opic tube			
			tel	escopic tube			
		,			,		
-							
-			,	,			
				\sim			
-							

3.1.2

-

KALIMER-150

가 가

(1)







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ANSYS

가 1.82m 2.74m 가 1.82m . 18 ~ 21 18 19 OBE . link . 가 90MPa 17mm . 133MPa 20 21 SSE 119MPa 20mm SSE . 22 ~ 25 가 2.74m 22 가 1.82m 23 . 가 link 40mm 가 가 186MPa 2.74m • main tube, link, grapple . Grapple 0.2m x 0.2m 0.3m x 0.3m main tube link 5 6 가 . 5 Grapple 0.2m x 0.2m link . 0.2m x 0.2m 가 0.2m x 0.1m 103~106MPa 29~19mm . 24 25 link 0.2m x 0.2m 가 . 6 가 0.3m x 0.3m link 0.3m x 0.2m 가 . 26 27 link 0.3m x 0.3m 7 가 . 가 가 link .



가

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	(MWe)	(m)	(m)
KALIMER	150	3.44	2.74 w/ IVTM
		1	
EFR	1490	8.2	7.2
SuperPhenix	1440	8.0	11.2
PFBR	500	4.96	6.93
LMFBR	1000	5.4	8.69
ALMR	155	2.4	2.74 w/ IVTM



2.						
1	3,					SNR-
	1					300(Russia)
						CRBRP
						(U.S.A.)
2	2,					JOYO
	2	, straight pull		가		(Japan)
		machines				DFR(UK)
3	2 ,	,	1			EFR
	Offset		1	가		
	Arm ,		T			
4	1 ,	\sim	UIS		10	MONJU
	UIS,				/	(Japan)
	Offset Arm ,	10	UIS	가		
5	1 ,					KALIMER
	X		N			PRISM
						PFR
6	2 ,	straight pull	UIS			
	UIS, 1	machines			,	
			UIS	가		

-

	3.			
			(m)	
1	3	,	11.3	
2	22	,	8.68	
3	2	, Offset Arm ,	7	*
4	1 Arm	, Offset , UIS	6.5	5.5 m
5	1	,	6.4	
6	2 UIS,	, ,	8.4	
	-			•



1.3 ,1



2.2



3.2 , Offset Arm



5.2	,	Offset Arm	3
5.2	,	Offset Arm	3











11.





Λ		
-	•	

Load	Ground ZPA(g)	Equivalent Static Inertial Load(g)			
Event		Horizontal	Vertical		
OBE	0.25	0.25	0.625		
SSE	0.50	0.5	1.25		

5	
Э	•

(Grapple : 0.2 m x 0.2 m)

Main Tube Link		0.3 m	0.4 m	0.5 m	0.6 m	
	(mm)	40	33	31	31	
0.2 m x 0.1 m	(MPa)	186	187	188	188	* Grapple 기
	(mm)	29	22	20	19	0.2 m x 0.2 m
0.2 m x 0.2 m	(MPa)	103	105	105	106	

6.			(Grapple $: 0.3 \text{ m x } 0.3 \text{ m}$)			
Main Tube Link		0.3 m	0.4 m	0.5 m	0.6 m	
0.2 m x 0.1 m	(mm)	45	37	35	34	
	(MPa)	222	225	226	226	* Grapple フト
0.3 m x 0.2 m	(mm)	27	19	16	15	0.3 m x 0.3 m
	(MPa)	118	70	70	71	



15.



16.

17. IVTM

18. OBE

(grapple/0.2x0.2, link/ 0.2x0.1)

(grapple/0.2x0.2, link/ 0.2x0.1)

19. OBE

(grapple/0.2x0.2, link/ 0.2x0.1, 1.82m)

20. SSE

(grapple/0.2x0.2, link/ 0.2x0.1, 1.82m)

(grapple/0.2x0.2, link/ 0.2x0.1, 2.74m)

22. SSE

(grapple/0.2x0.2, link/ 0.2x0.1, 2.74m)

23. SSE

(grapple/0.2x0.2, link/ 0.2x0.2)

24. SSE

(grapple/0.2x0.2, link/ 0.2x0.2)

25. SSE

(grapple/0.3x0.3, link/ 0.3x0.2)

26. SSE

(grapple/0.3x0.3, link/ 0.3x0.2)

27. SSE

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Abstract (15-2	20 L	ines)							
In case the In-Vessel Fu expanded due rotating plug increased con selected and t The model this condition reaction force was carried deformation variation of th	pow el 7 e to and ce si he n con a, the for out were	ver of KA Fransfer increas d the m ize. Also narginal 1 figuration e loads c the with by the e calcula componen	ALIMER is increase Equipment was ing of the elect ethod of the fu- o, among the v length of the arm n of IVTM is ful onsidered are the ndrawal of the c finite element ated to the the ts considered as	eased by s sugges ric powe uel trans arious ev n for the ly extend the weight core asset analysis refuelin the desig	the large size, ted and revie or 150 MWe to offer were evaluated conce- pantograph typ ded condition of t of the core a mbly. The stru- using ANSY og and seisming n parameters of	the struct wed. The 600 M luated by epts two be IVTM of the par ssembly, lectural an S code. c loads of IVTM.	etural ne co We. 7 y ass con was ntogra self nalysi The for	concept of ore size is The size of suming the cepts were analysed. aph arm. In weight and is of IVTM stress and the section	

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