

# Schedule Management Framework for Cloud-based Future Automotive Software Systems

Licong Zhang<sup>1</sup>, Debayan Roy<sup>1</sup>, Philipp Mundhenk<sup>2</sup>, Samarjit Chakraborty<sup>1</sup>

<sup>1</sup> TU Munich, Germany

<sup>2</sup> TUM CREATE, Singapore

RTCSA 2016

Aug. 17, 2016, Daegu

# Overview

- **Problem**
  - Schedule synthesis for Ethernet-based time-triggered system
  - Online schedule generation and management for Plug-and-Play scenario

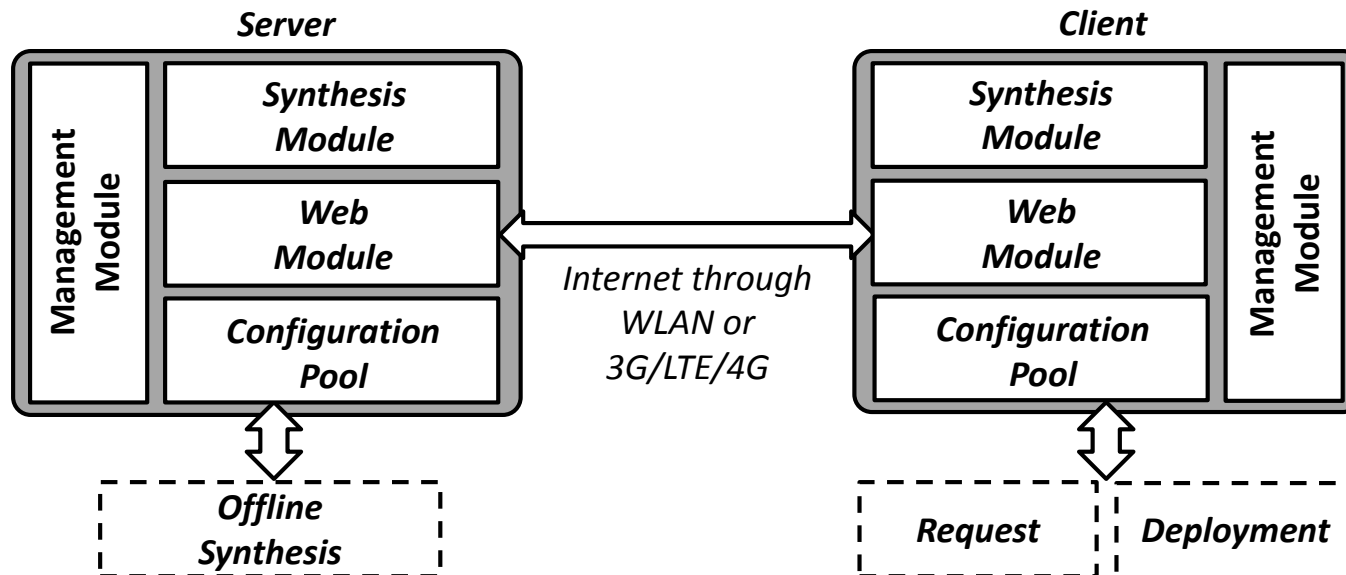
# Overview

- **Problem**

- Schedule synthesis for Ethernet-based time-triggered system
- Online schedule generation and management for Plug-and-Play scenario

- **Approach**

- Software framework for schedule management
- Utilization of both local computation and cloud-computing
- Four-stage scheduling strategy, online schedule synthesis, configuration pool



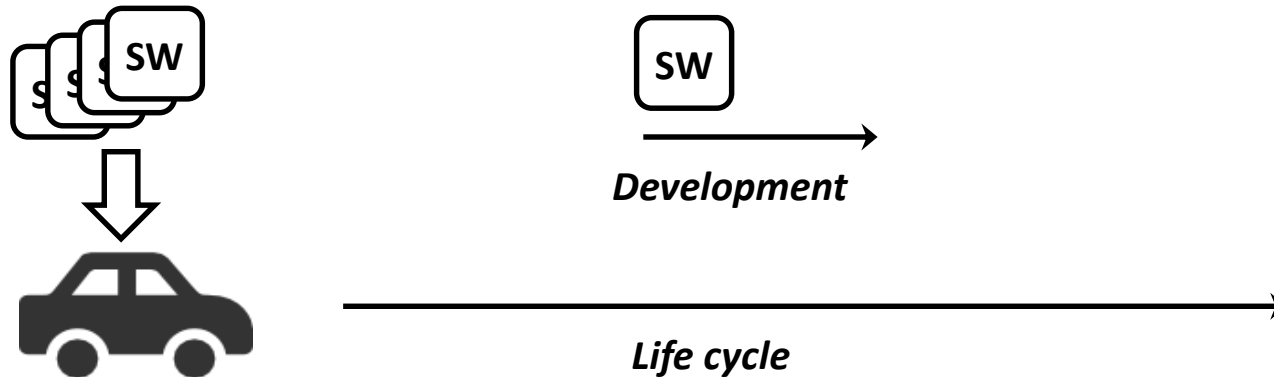
# Outline

- Motivation
- Background
- Problem Formulation
- Proposed Framework
- Experimental Results
- Concluding Remarks

# Motivation

- **Software update and installation after sales**

- Shift of innovation in automotive domain to Electrical/Electronics systems and software
- Development cycle of electronic system and software is much shorter than vehicle life cycle
- Increasingly more new software functions, e.g., in driver assistance, autonomous driving and infotainment domain

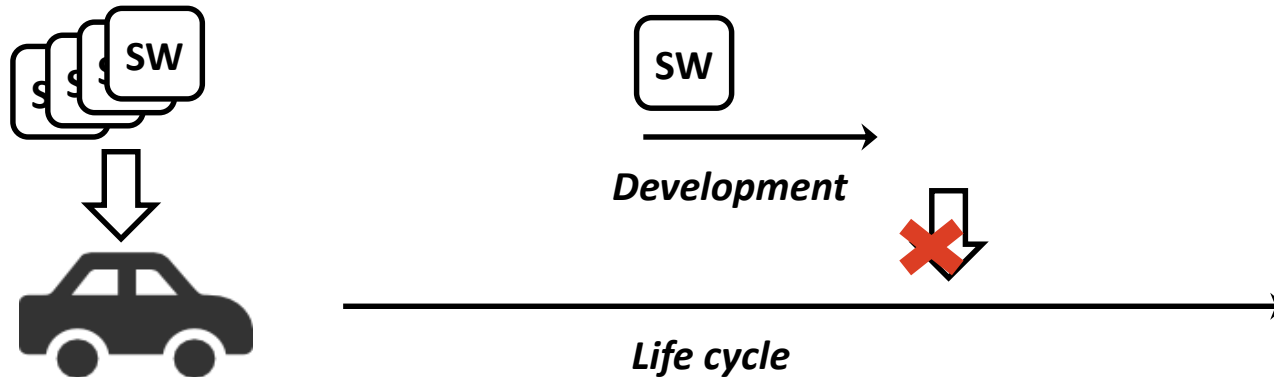


# Motivation

- **Software update and installation after sales**

- Shift of innovation in automotive domain to Electrical/Electronics systems and software
- Development cycle of electronic system and software is much shorter than vehicle life cycle
- Increasingly more new software functions, e.g., in driver assistance, autonomous driving and infotainment domain

➤ Functionality of a vehicle becomes ‚outdated‘ easily



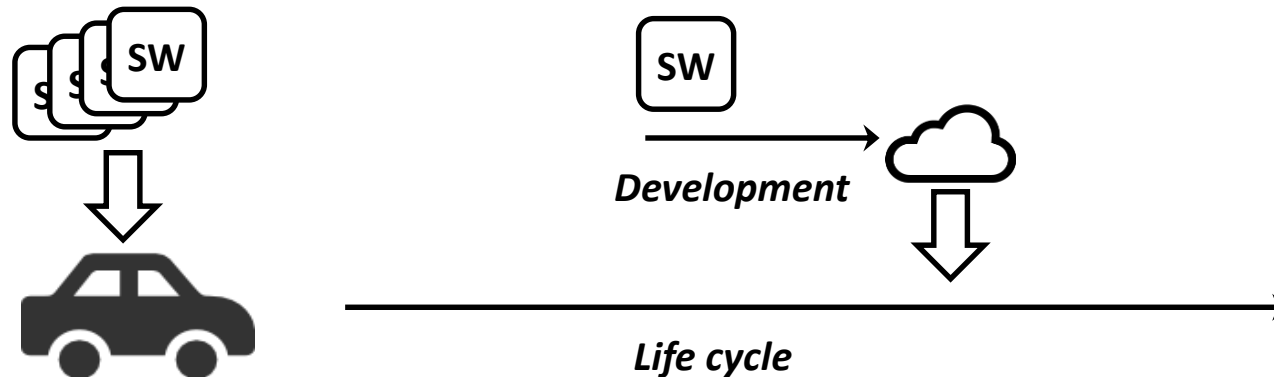
# Motivation

- **Software update and installation after sales**

- Shift of innovation in automotive domain to Electrical/Electronics systems and software
- Development cycle of electronic system and software is much shorter than vehicle life cycle
- Increasingly more new software functions, e.g., in driver assistance, autonomous driving and infotainment domain

➤ Functionality of a vehicle becomes ‚outdated‘ easily

- In the future it would advantageous for both car manufacturers and customers that
  - Software functions can be constantly updated
  - Newly developed software can be deployed after sales



# Motivation

- **Software update and installation after sales**
  - Shift of innovation in automotive domain to Electrical/Electronics systems and software
  - Development cycle of electronic system and software is much shorter than vehicle life cycle
  - Increasingly more new software functions, e.g., in driver assistance, autonomous driving and infotainment domain
  
- Functionality of a vehicle becomes ‚outdated‘ easily
  
- In the future it would be advantageous for both car manufacturers and customers that
  - Software functions can be constantly updated
  - Newly developed software can be deployed after sales
  
- **Cloud-based future automotive software systems**
  - Internet connection for cars
  - Vehicle is becoming increasingly autonomous
  
- Autonomous detection of driving condition and download software applications on demand



# Motivation

- **Plug-and-play of software applications**
  - Software applications can be installed or updated through storage devices (e.g., USB stick) or through cloud service

# Motivation

- **Plug-and-play of software applications**
  - Software applications can be installed or updated through storage devices (e.g., USB stick) or through cloud service
  
- **Challenges and issues to be addressed**
  - Supply chain – ECU with single independent function
  - ECU consolidation – ECUs are becoming computing platforms and multiple applications can be mapped on a single ECU

# Motivation

- **Plug-and-play of software applications**
  - Software applications can be installed or updated through storage devices (e.g., USB stick) or through cloud service
  
- **Challenges and issues to be addressed**
  - Supply chain – ECU with single independent function
  - ECU consolidation – ECUs are becoming computing platforms and multiple applications can be mapped on a single ECU
  
  - Deployment of software components – ECU software into single binary file
  - Related research works in developing operating systems and runtime environment to accommodate new software without flashing the whole ECU

# Motivation

- **Plug-and-play of software applications**
  - Software applications can be installed or updated through storage devices (e.g., USB stick) or through cloud service
  
- **Challenges and issues to be addressed**
  - Supply chain – ECU with single independent function
  - ECU consolidation – ECUs are becoming computing platforms and multiple applications can be mapped on a single ECU
  
  - Deployment of software components – ECU software into single binary file
  - Related research works in developing operating systems and runtime environment to accommodate new software without flashing the whole ECU
  
  - Reallocation of communication and computation resources
  - The problem to be addressed in this work

# Motivation

- **Resource reallocation**
  - Change of configuration for processor scheduling and network scheduling
  - Issues like schedule generation, schedule deployment and safe reconfiguration process need to be addressed

# Motivation

- **Resource reallocation**
  - Change of configuration for processor scheduling and network scheduling
  - Issues like schedule generation, schedule deployment and safe reconfiguration process need to be addressed
  
- This work focuses on the schedule generation and management problem

# Motivation

- **Resource reallocation**
  - Change of configuration for processor scheduling and network scheduling
  - Issues like schedule generation, schedule deployment and safe reconfiguration process need to be addressed
  
- This work focuses on the schedule generation and management problem
  
- **Time-triggered System**
  - Task and network transmission are triggered according to pre-calculated schedules
  - In the case of adding new applications or the update changes requirements, new schedule set needs to be calculated.

# Motivation

- **Resource reallocation**
  - Change of configuration for processor scheduling and network scheduling
  - Issues like schedule generation, schedule deployment and safe reconfiguration process need to be addressed

➤ This work focuses on the schedule generation and management problem
- **Time-triggered System**
  - Task and network transmission are triggered according to pre-calculated schedules
  - In the case of adding new applications or the update changes requirements, new schedule set needs to be calculated.
- **Requirements**
  - Obtain schedules online in relatively short time
  - As many as possible new applications can be accommodated
  - Facilitation of schedule reuse and minimization of disturbance to existing schedules



# Motivation

- **Related Works**
  - Schedule synthesis problem for Ethernet-based time-triggered systems [10,11,13,15,16]
  - Incremental scheduling [11,12]
  - Configuration and reconfiguration of time-triggered Ethernet networks [18,19]
  - Plug-and-Play in the automotive setting [2,3,5,6]

# Motivation

## ▪ **Related Works**

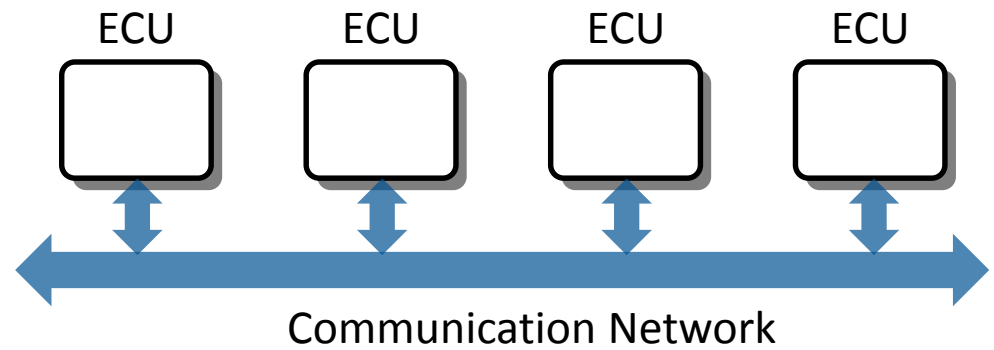
- Schedule synthesis problem for Ethernet-based time-triggered systems [10,11,13,15,16]
- Incremental scheduling [11,12]
- Configuration and reconfiguration of time-triggered Ethernet networks [18,19]
- Plug-and-Play in the automotive setting [2,3,5,6]

## ▪ **Contributions**

- Software framework for schedule generation and management for Plug-and-Play
- Online schedule synthesis based on a mixture of embedded and cloud computing
- Configuration pool for schedule reuse
- A four-stage scheduling strategy offering trade-off between chance of accommodating new applications and synthesis time and disturbance to existing schedules

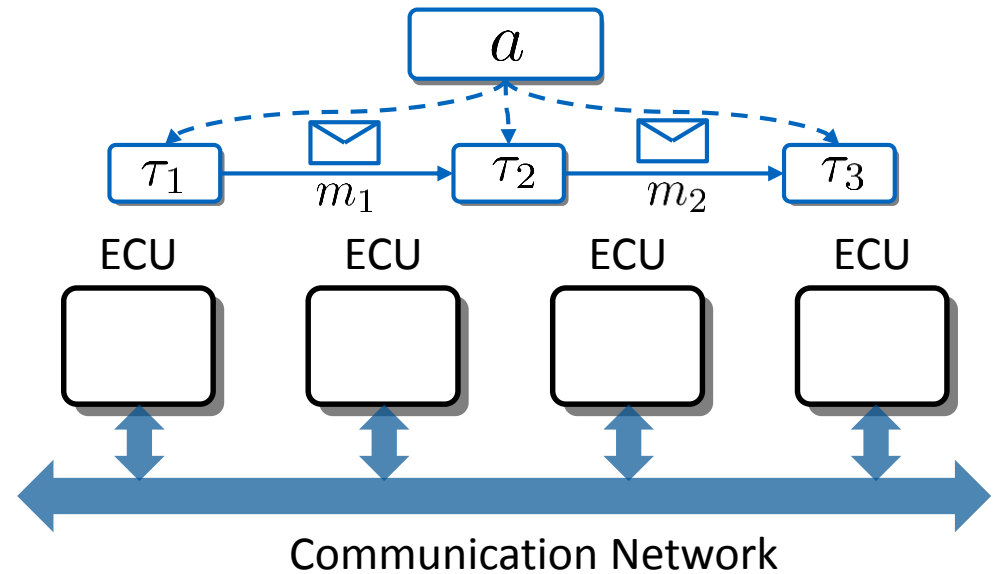
# Background

- **Distributed embedded systems**
  - Hardware architecture



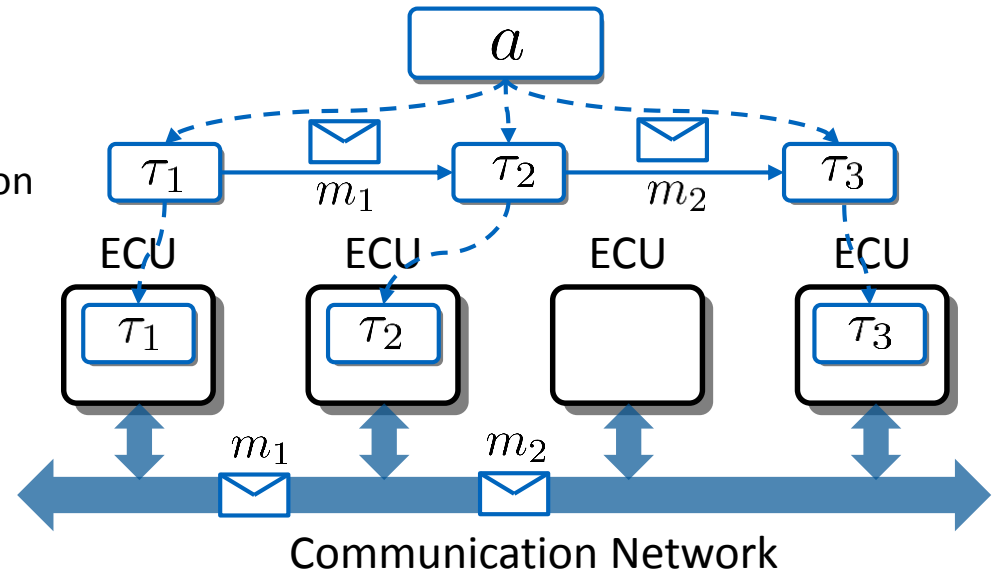
# Background

- **Distributed embedded systems**
  - Hardware architecture
  - Distributed applications



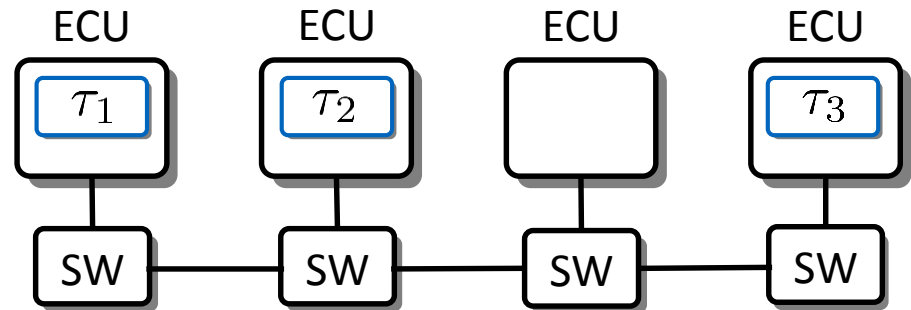
# Background

- **Distributed embedded systems**
  - Hardware architecture
  - Distributed applications
  - Task mapping / network communication



# Background

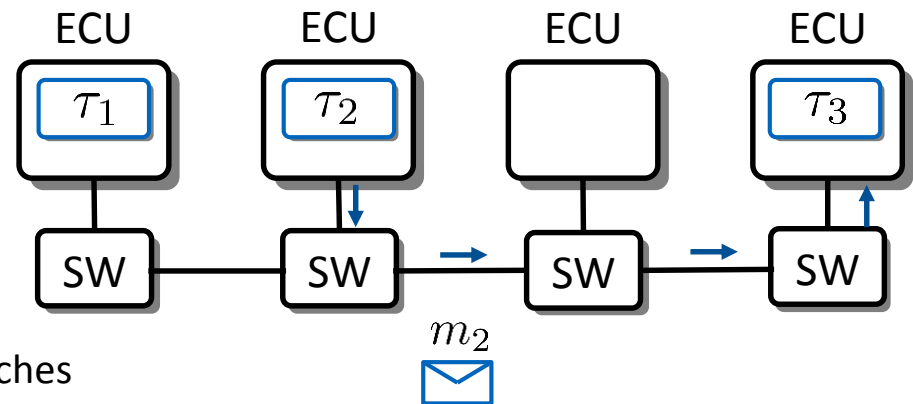
- **Distributed embedded systems**
  - Hardware architecture
  - Distributed applications
  - Task mapping / network communication



- **Switched Ethernet**
  - Processing units connected through switches
  - Commonly with full-duplex links

# Background

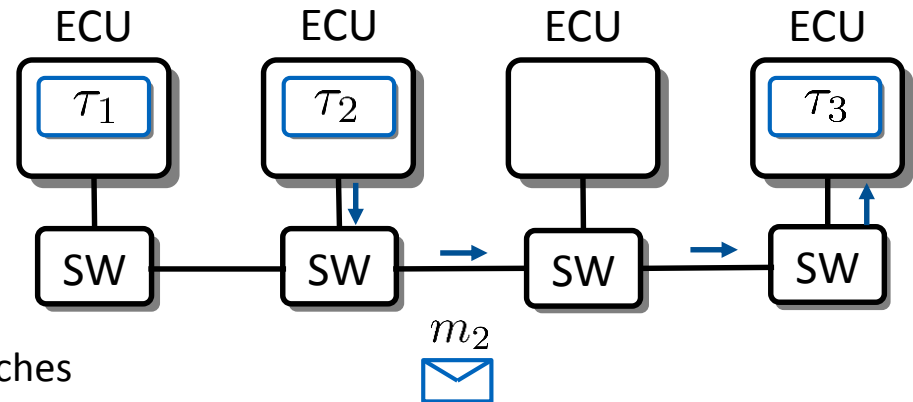
- **Distributed embedded systems**
  - Hardware architecture
  - Distributed applications
  - Task mapping / network communication



- **Switched Ethernet**
  - Processing units connected through switches
  - Commonly with full-duplex links
  - Ethernet frames forwarded switch by switch

# Background

- **Distributed embedded systems**
  - Hardware architecture
  - Distributed applications
  - Task mapping / network communication



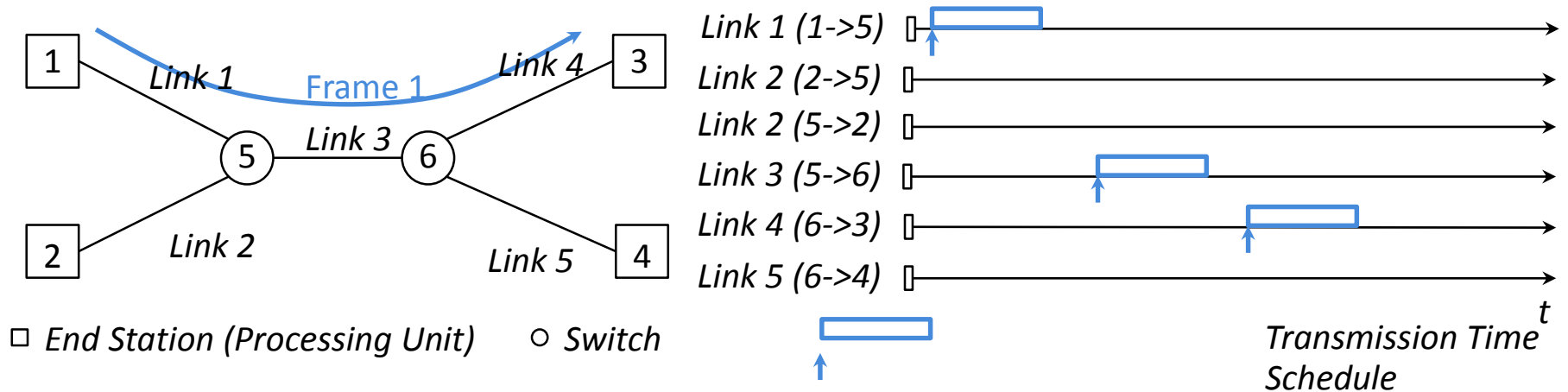
- **Switched Ethernet**
  - Processing units connected through switches
  - Commonly with full-duplex links
  - Ethernet frames forwarded switch by switch
- Queueing delay at each switch
  - Not deterministic
  - Can be relatively large



# Background

- Time-triggered Ethernet communication

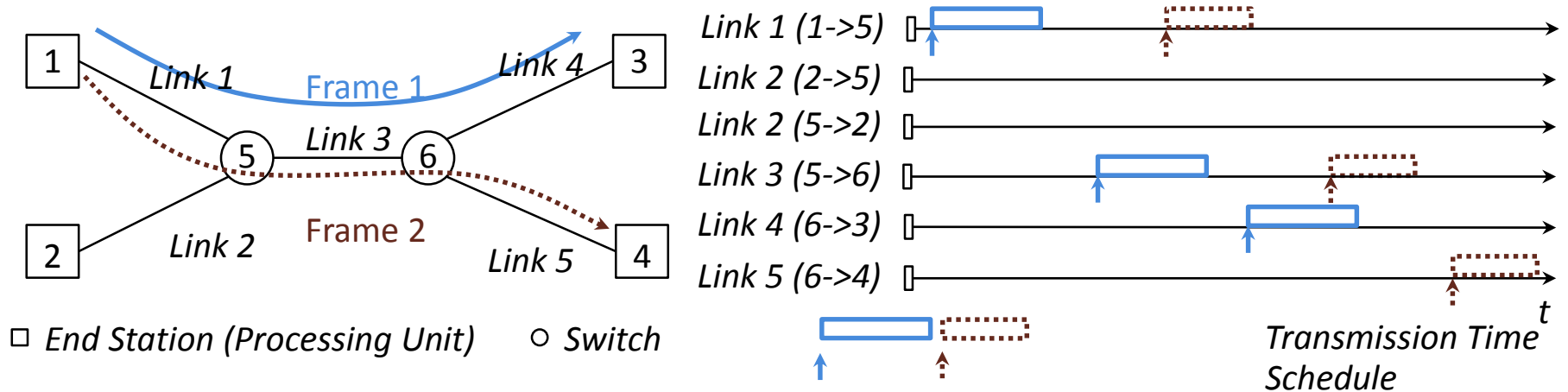
- Frames are scheduled to avoid queueing delay
- Frames transmission on each link according to static schedule



# Background

- Time-triggered Ethernet communication

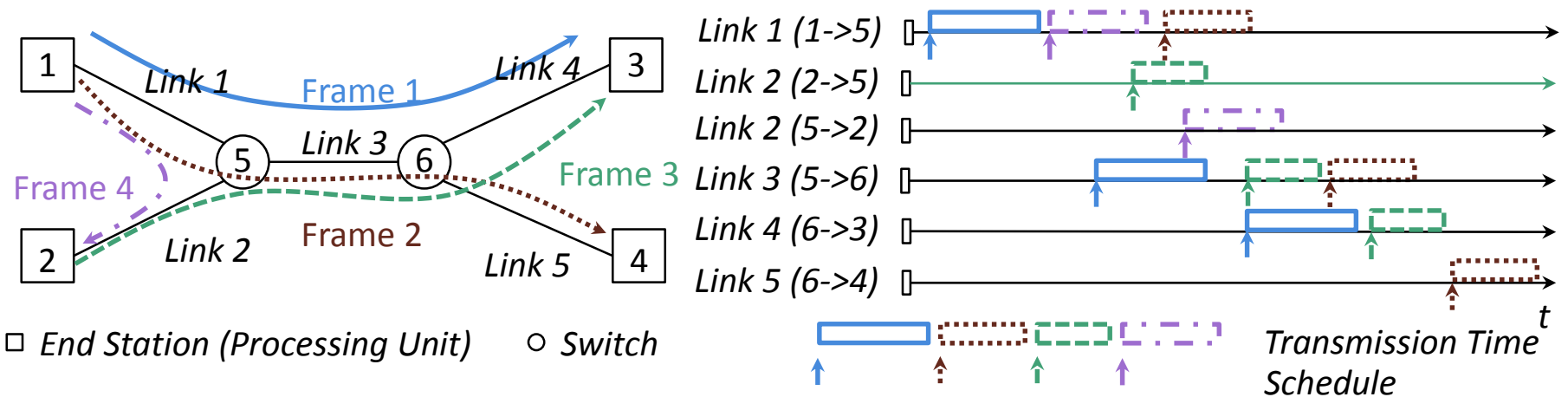
- Frames are scheduled to avoid queueing delay
- Frames transmission on each link according to static schedule



# Background

- Time-triggered Ethernet communication

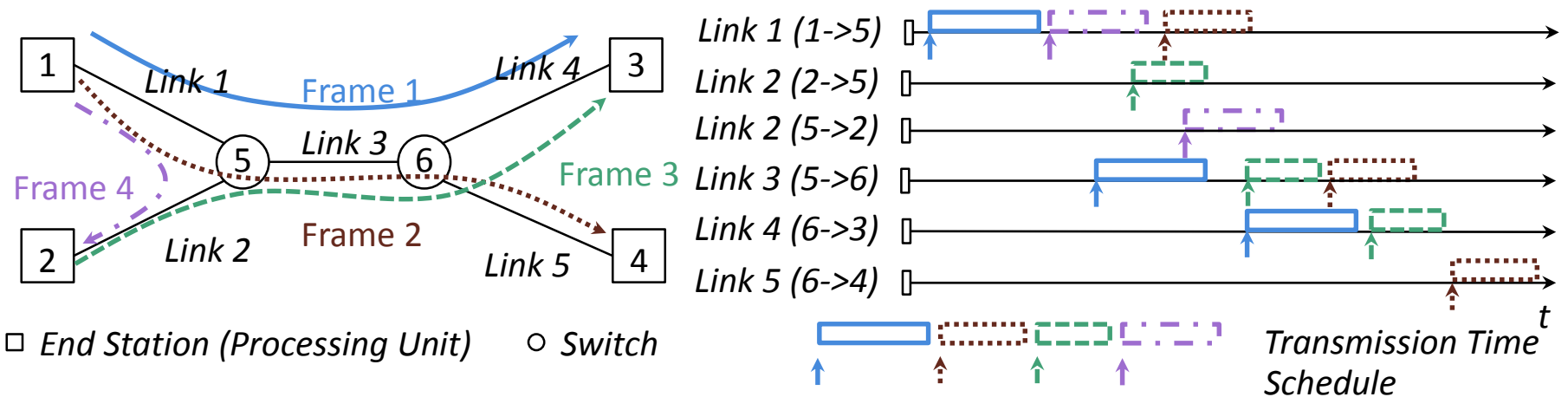
- Frames are scheduled to avoid queueing delay
- Frames transmission on each link according to static schedule



# Background

- Time-triggered Ethernet communication

- Frames are scheduled to avoid queueing delay
- Frames transmission on each link according to static schedule



- Ethernet-based time-triggered systems

- Processor: time-triggered non-preemptive task scheduling
- Network: time-triggered Ethernet communication

# Problem Formulation

- **The scheduling problem**

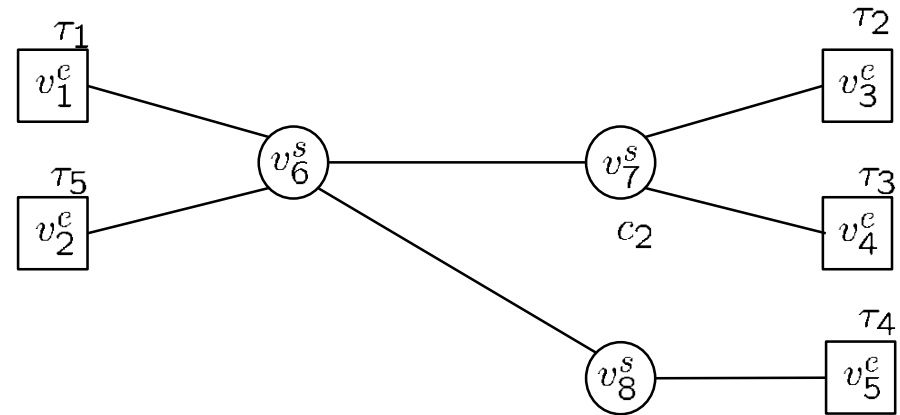
- Application task

$$\tau_i = \{ \tau_i.p, \tau_i.o, \tau_i.e \}$$

$\downarrow$   
*period*

$\downarrow$   
*offset*

$\downarrow$   
*WCET*



# Problem Formulation

- **The scheduling problem**

- Application task

$$\tau_i = \{ \tau_i.p, \tau_i.o, \tau_i.e \}$$

$\downarrow$   
*period*

$\downarrow$   
*offset*

$\downarrow$   
*WCET*

- Communication task

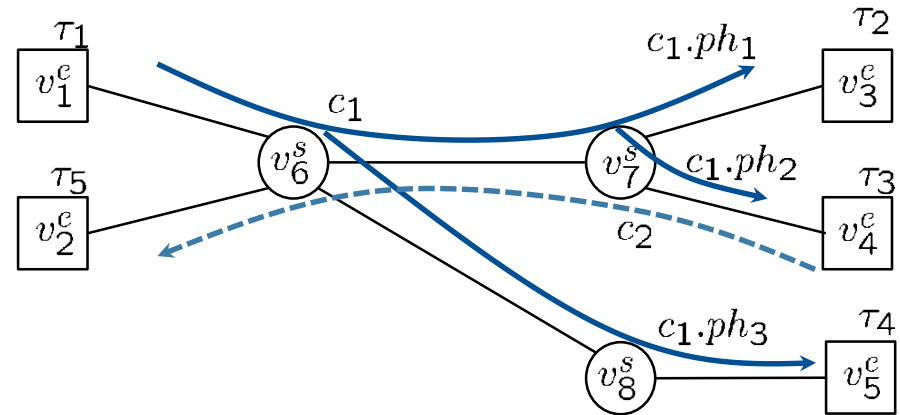
$$c_i = \{ f_i, c_i.tr, c_i.o, c_i.p \}$$

$\downarrow$   
*frame*  
*length*

$\downarrow$   
*path*  
*tree*

$\downarrow$   
*offsets*

$\downarrow$   
*period*



# Problem Formulation

- The scheduling problem

- Application task

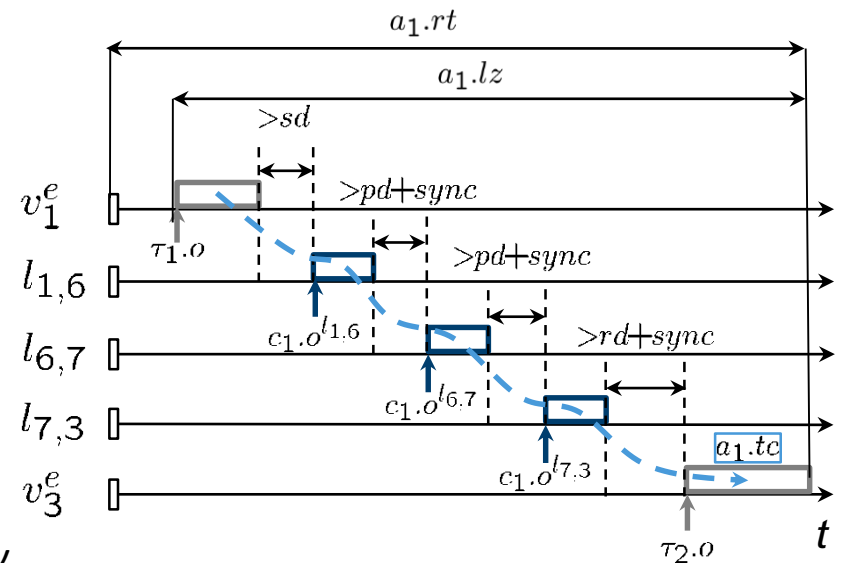
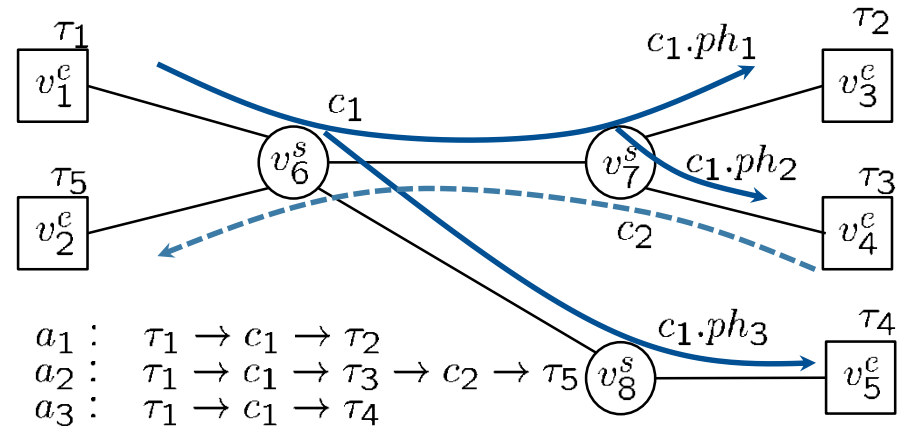
$$\tau_i = \left\{ \begin{array}{ccc} \tau_i.p & \tau_i.o & \tau_i.e \\ \downarrow & \downarrow & \downarrow \\ \text{period} & \text{offset} & \text{WCET} \end{array} \right\}$$

- Communication task

$$c_i = \left\{ \begin{array}{cccc} f_i & c_i.tr & c_i.o & c_i.p \\ \downarrow & \downarrow & \downarrow & \downarrow \\ \text{frame} & \text{path} & \text{offsets} & \text{period} \\ \text{length} & \text{tree} & & \end{array} \right\}$$

- Application

$$a_i = \left\{ \begin{array}{cccc} a_i.tc & a_i.p & a_i.rt & a_i.lz \\ \downarrow & \downarrow & \downarrow & \downarrow \\ \text{period} & \text{task} & \text{response} & \text{latency} \\ & \text{chain} & \text{time} & \end{array} \right\}$$



# Problem Formulation

- **The scheduling problem**
  - Hardware specific parameters  $hw.\omega$ 
    - System topology
    - Timing parameters including network bandwidth, synchronization precision, etc.
  - Application parameters  $A.\omega$ 
    - Task mapping, period, WCET
    - Communication frame length, path tree, latency and response time constraints
  - Application schedules  $A.o$ 
    - Task schedules and frame transmission schedules on each link



# Problem Formulation

- **The scheduling problem**
  - Hardware specific parameters  $hw.\omega$ 
    - System topology
    - Timing parameters including network bandwidth, synchronization precision, etc.
  - Application parameters  $A.\omega$ 
    - Task mapping, period, WCET
    - Communication frame length, path tree, latency and response time constraints
  - Application schedules  $A.o$ 
    - Task schedules and frame transmission schedules on each link
- **Approach**
  - Formulation of the problem in SMT or MIP problem and use solvers to obtain the schedules, as in [10,11,13,15,16]

# Problem Formulation

- **The schedule management problem**
  - Consider a system with  $hw.\omega$  and existing application set  $\mathcal{A}_o.\omega, \mathcal{A}_o.\mathbf{O}$
  - Obtain  $\mathcal{A}_n.\mathbf{O}$  for the new application set  $\mathcal{A}_n$  with  $\mathcal{A}_n.\omega$ , while addressing the requirements:
    - Obtain schedules in relatively short time
    - As many as possible new applications can be accommodated
    - Facilitation of schedule reuse and minimization of disturbance to existing schedules

# Problem Formulation

- **The schedule management problem**
  - Consider a system with  $hw.\omega$  and existing application set  $\mathcal{A}_o.\omega, \mathcal{A}_o.\mathbf{o}$
  - Obtain  $\mathcal{A}_n.\mathbf{o}$  for the new application set  $\mathcal{A}_n$  with  $\mathcal{A}_n.\omega$ , while addressing the requirements:
    - Obtain schedules in relatively short time
    - As many as possible new applications can be accommodated
    - Facilitation of schedule reuse and minimization of disturbance to existing schedules
  
- **Alternatives and Challenges**
  - Synthesize schedules offline for a specific application -> conflicts with existing schedules
  - Synthesize all possible schedule sets offline -> possibly a huge number combinations
  - Online schedule synthesis on-board -> long synthesis time due to limited computing power

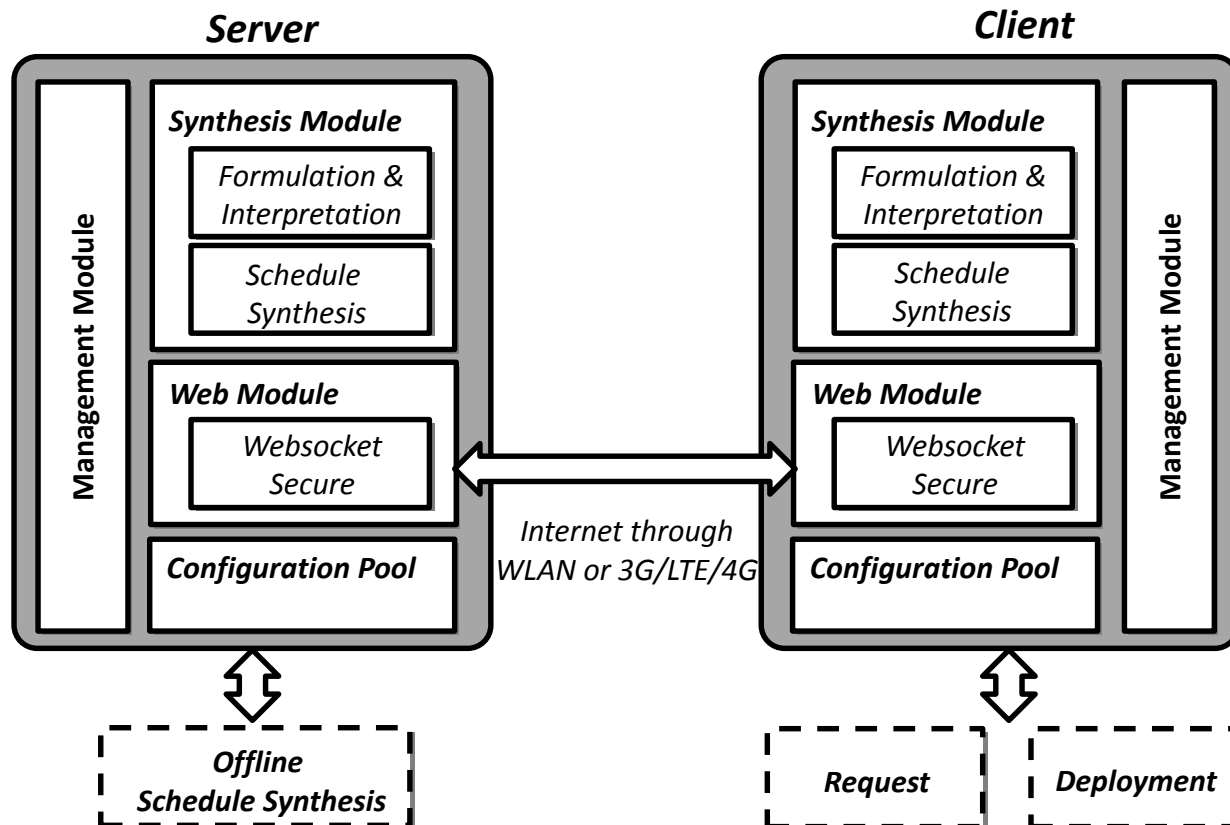
# Problem Formulation

- **The schedule management problem**
  - Consider a system with  $hw.\omega$  and existing application set  $\mathcal{A}_o.\omega, \mathcal{A}_o.\mathbf{O}$
  - Obtain  $\mathcal{A}_n.\mathbf{O}$  for the new application set  $\mathcal{A}_n$  with  $\mathcal{A}_n.\omega$ , while addressing the requirements:
    - Obtain schedules in relatively short time
    - As many as possible new applications can be accommodated
    - Facilitation of schedule reuse and minimization of disturbance to existing schedules
  
- **Alternatives and challenges**
  - Synthesize schedules offline for a specific application -> conflicts with existing schedules
  - Synthesize all possible schedule sets offline -> possibly a huge number combinations
  - Online schedule synthesis on-board -> long synthesis time due to limited computing power
  
- **Need of an online schedule management framework**

# Schedule Management Framework

- Overview

- Client-server architecture
- Utilization of both onboard processor and cloud-computing
- Components: Synthesis Module, Web Module, Configuration Pool, Management Module



# Schedule Management Framework

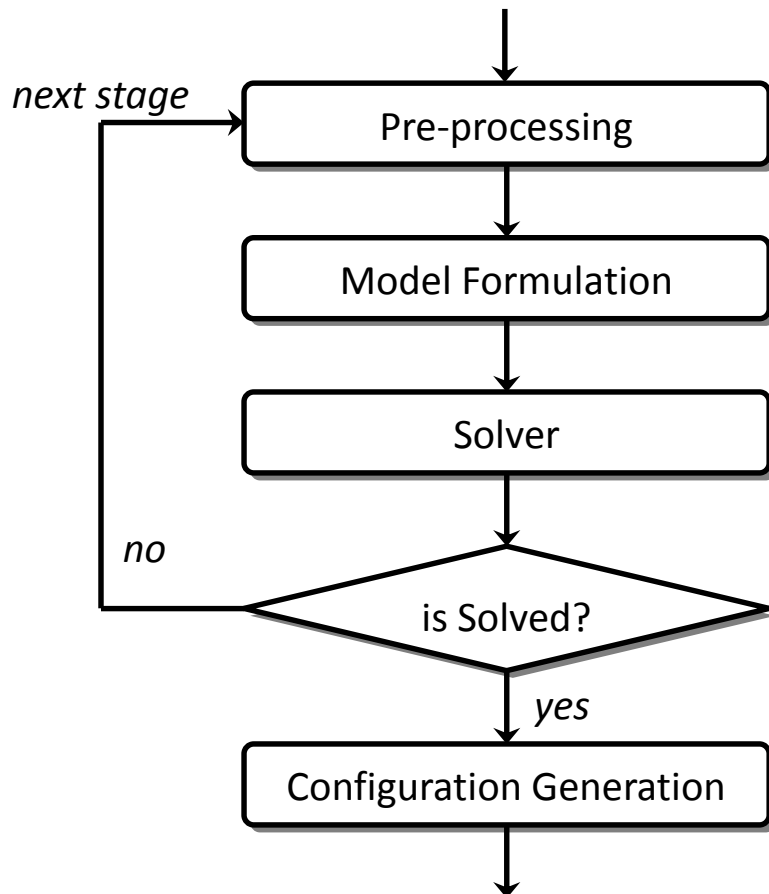
- **Configuration and request**
  - TICON
    - An XML format containing  $hw.\omega$ ,  $\mathcal{A}.\omega$  and  $\mathcal{A}.\mathbf{0}$
    - Configuration: all application schedules have valid values
    - Request: some application schedules are empty

# Schedule Management Framework

- **Configuration and request**
  - TICON
    - An XML format containing  $hw.\omega$ ,  $\mathcal{A}.\omega$  and  $\mathcal{A}.\mathbf{0}$
    - Configuration: all application schedules have valid values
    - Request: some application schedules are empty
  
- **Configuration Pool**
  - Can be managed through different metrics like frequency of reuse
  - Retrieve a configuration
    - If the application set of request matches exactly or is a subset of a configuration in pool, the configuration can be retrieved
    - In the case of a subset, schedules of other applications are removed
  - Update the configuration pool
    - Add a configuration if it is not in pool
    - If the new configuration is a superset of an existing one, it replaces the existing one
  - It facilitates schedule reuse for a single vehicle or between vehicles of the same variant and request based configuration management

# Schedule Management Framework

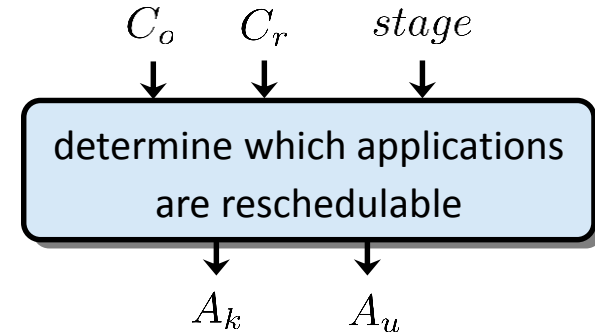
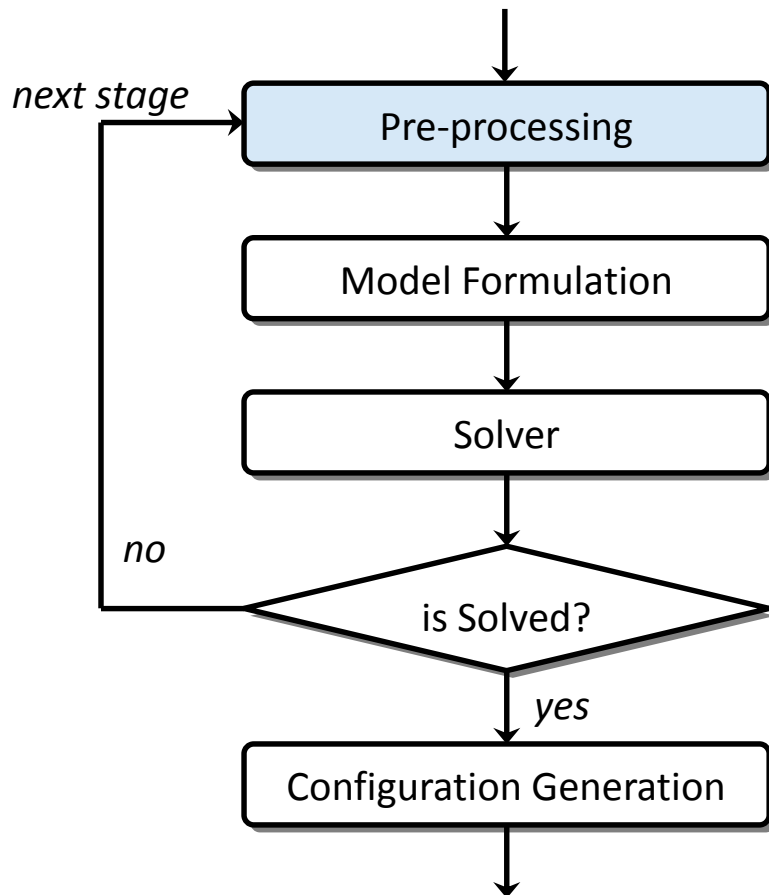
- Synthesis module





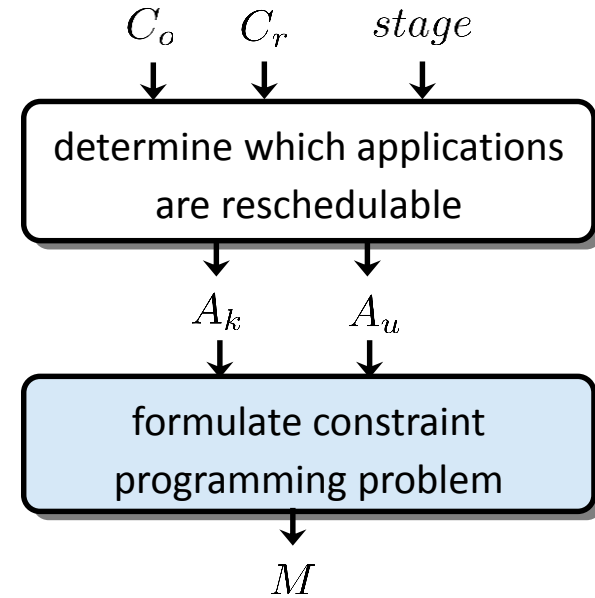
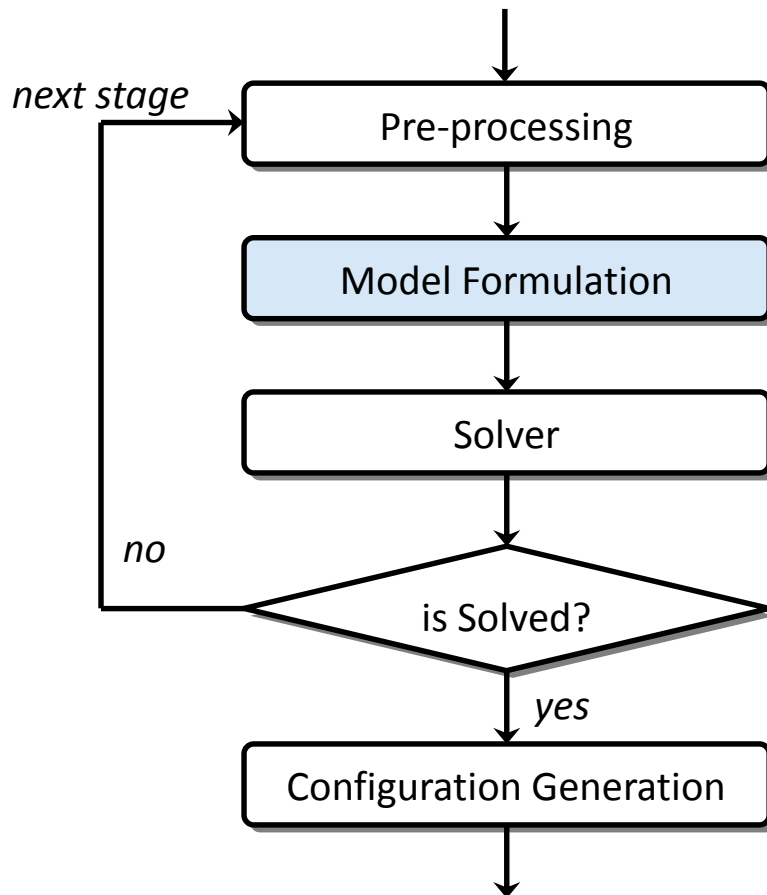
# Schedule Management Framework

- Synthesis module



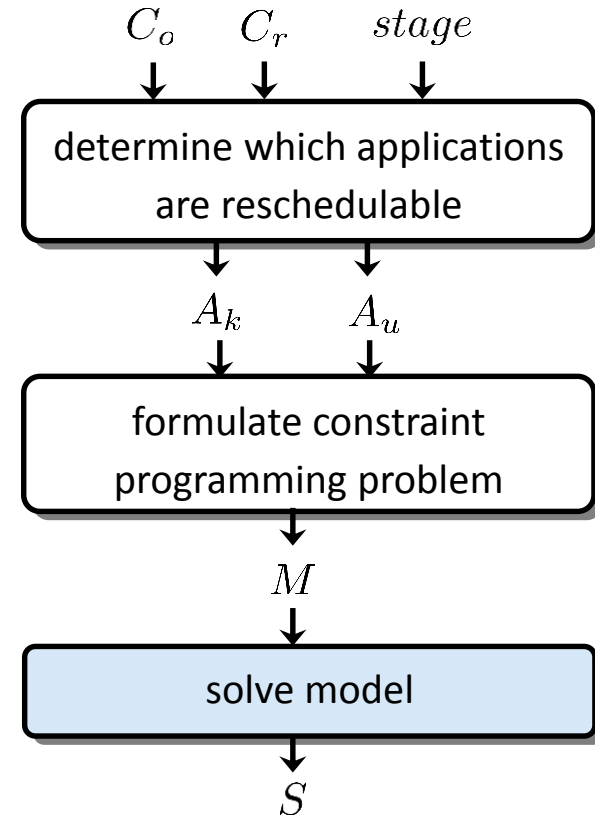
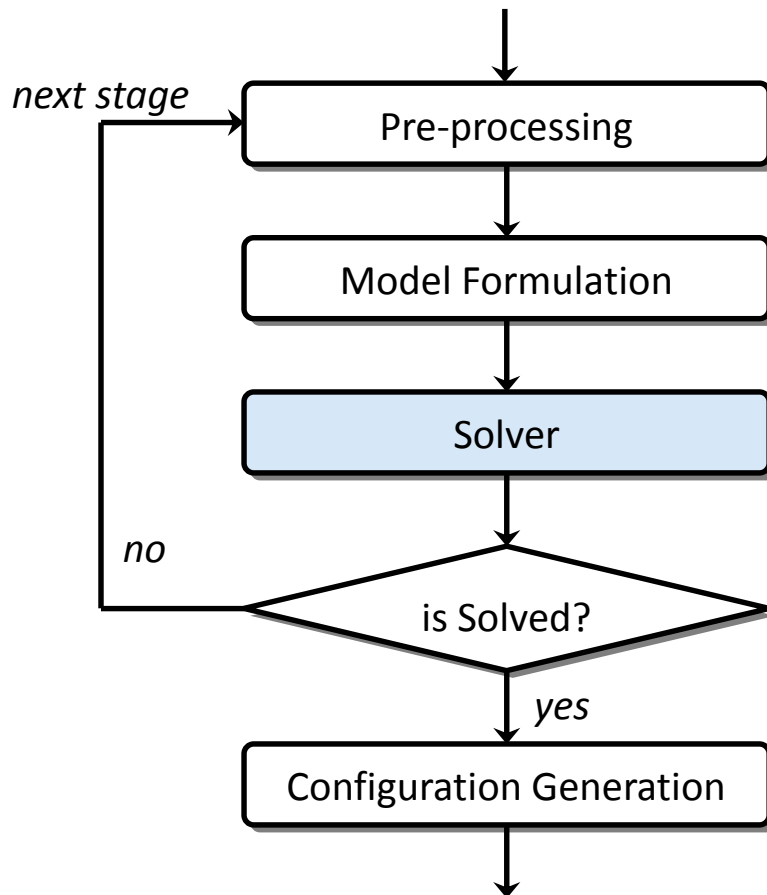
# Schedule Management Framework

- Synthesis module



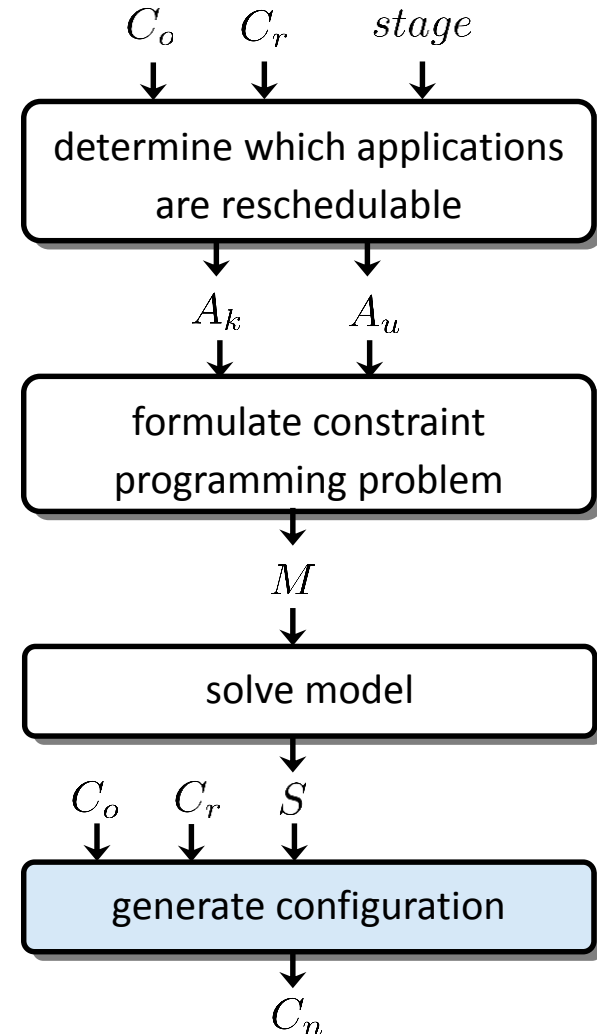
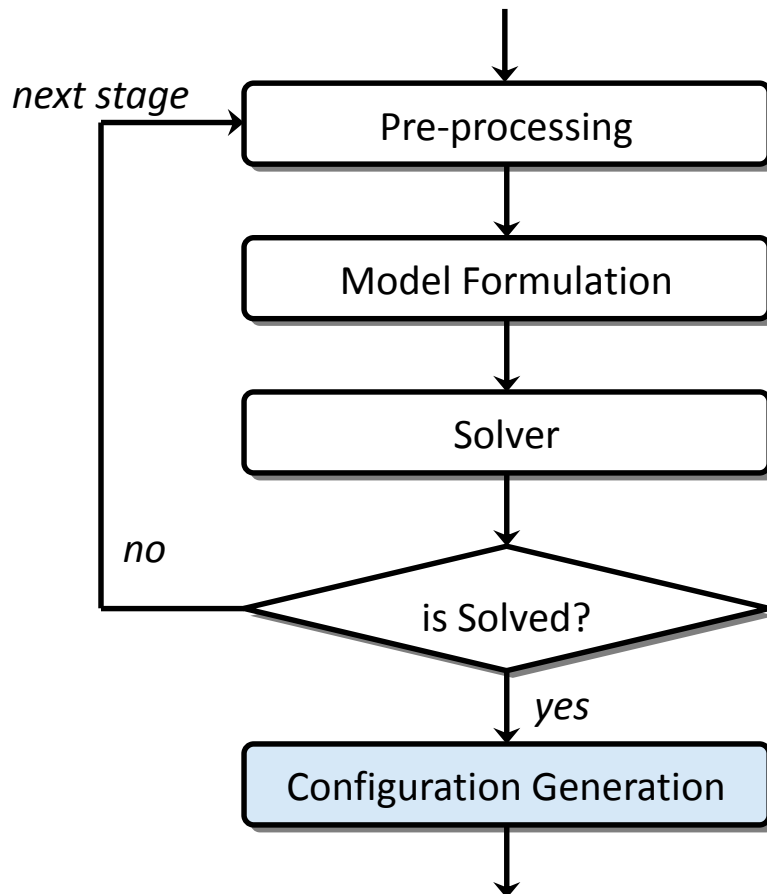
# Schedule Management Framework

- Synthesis module



# Schedule Management Framework

- Synthesis module



# Schedule Management Framework

- **Four-stage scheduling strategy**

- Stage 1 – Incremental scheduling

- None of the existing applications are rescheduled

$$\mathcal{A}_k = \mathcal{A}_o \cap \mathcal{A}_n, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

# Schedule Management Framework

- **Four-stage scheduling strategy**

- Stage 1 – Incremental scheduling

- None of the existing applications are rescheduled

$$\mathcal{A}_k = \mathcal{A}_o \cap \mathcal{A}_n, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

- Stage 2 – Rescheduling based on task conflict

- Reschedule existing applications with common tasks with new ones

$$\mathcal{A}_k = (\mathcal{A}_o \cap \mathcal{A}_n) \setminus \mathcal{A}_\tau, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

$$\mathcal{A}_\tau = \{a_i | a_i \in \mathcal{A}_o^a \cap \mathcal{A}_n^a \wedge \exists_{a_j \in \mathcal{A}_n^a \setminus \mathcal{A}_o^a} \exists_{\substack{\tau_k \in a_i.tc \\ \tau_l \in a_j.tc}} \tau_k = \tau_l\}$$

# Schedule Management Framework

- **Four-stage scheduling strategy**

- Stage 1 – Incremental scheduling

- None of the existing applications are rescheduled

$$\mathcal{A}_k = \mathcal{A}_o \cap \mathcal{A}_n, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

- Stage 2 – Rescheduling based on task conflict

- Reschedule existing applications with common tasks with new ones

$$\mathcal{A}_k = (\mathcal{A}_o \cap \mathcal{A}_n) \setminus \mathcal{A}_\tau, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

$$\mathcal{A}_\tau = \{a_i | a_i \in \mathcal{A}_o^a \cap \mathcal{A}_n^a \wedge \exists_{a_j \in \mathcal{A}_n^a \setminus \mathcal{A}_o^a} \exists_{\substack{\tau_k \in a_i.tc \\ \tau_l \in a_j.tc}} \tau_k = \tau_l\}$$

- Stage 3 – Rescheduling based on computation resource conflict

- Reschedule existing applications with tasks mapped on common ECU with new ones

$$\mathcal{A}_k = (\mathcal{A}_o \cap \mathcal{A}_n) \setminus \mathcal{A}_E, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

$$\mathcal{A}_E = \{a_i | a_i \in \mathcal{A}_o^a \cap \mathcal{A}_n^a \wedge \exists_{a_j \in \mathcal{A}_n^a \setminus \mathcal{A}_o^a} \exists_{\substack{\tau_k \in a_i.tc \\ \tau_l \in a_j.tc}} \tau_k.E = \tau_l.E\}$$

# Schedule Management Framework

- **Four-stage scheduling strategy**

- Stage 1 – Incremental scheduling

- None of the existing applications are rescheduled

$$\mathcal{A}_k = \mathcal{A}_o \cap \mathcal{A}_n, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

- Stage 2 – Rescheduling based on task conflict

- Reschedule existing applications with common tasks with new ones

$$\mathcal{A}_k = (\mathcal{A}_o \cap \mathcal{A}_n) \setminus \mathcal{A}_\tau, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

$$\mathcal{A}_\tau = \{a_i | a_i \in \mathcal{A}_o^a \cap \mathcal{A}_n^a \wedge \exists_{a_j \in \mathcal{A}_n^a \setminus \mathcal{A}_o^a} \exists_{\substack{\tau_k \in a_i.tc \\ \tau_l \in a_j.tc}} \tau_k = \tau_l\}$$

- Stage 3 – Rescheduling based on computation resource conflict

- Reschedule existing applications with tasks mapped on common ECU with new ones

$$\mathcal{A}_k = (\mathcal{A}_o \cap \mathcal{A}_n) \setminus \mathcal{A}_E, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

$$\mathcal{A}_E = \{a_i | a_i \in \mathcal{A}_o^a \cap \mathcal{A}_n^a \wedge \exists_{a_j \in \mathcal{A}_n^a \setminus \mathcal{A}_o^a} \exists_{\substack{\tau_k \in a_i.tc \\ \tau_l \in a_j.tc}} \tau_k.E = \tau_l.E\}$$

- Stage 4 – Complete rescheduling

- All existing applications are considered reschedulable

$$\mathcal{A}_k = \mathcal{A}^b, \mathcal{A}_n = \mathcal{A}_n^a$$



# Schedule Management Framework

## Four-stage scheduling strategy

- Stage 1 – Incremental scheduling

- None of the existing applications...

$$\mathcal{A}_k = \mathcal{A}_o \cap \mathcal{A}_n, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

- Stage 2 – Rescheduling based on task conflict

- Reschedule existing applications with common tasks with new ones

$$\mathcal{A}_k = (\mathcal{A}_o \cap \mathcal{A}_n) \setminus \mathcal{A}_\tau, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

$$\mathcal{A}_\tau = \{a_i | a_i \in \mathcal{A}_o^a \cap \mathcal{A}_n^a \wedge$$

$$\exists a_j \in \mathcal{A}_n^a \setminus \mathcal{A}_k^a \wedge \exists \tau_k \in a_i.tc \exists \tau_l \in a_j.tc$$

increasing

- Stage 3 – Rescheduling based on competition resource conflict

- Reschedule existing applications with tasks mapped on common CPU with new ones

$$\mathcal{A}_k = (\mathcal{A}_o \cap \mathcal{A}_n) \setminus \mathcal{A}_E, \mathcal{A}_u = \mathcal{A}_n \setminus \mathcal{A}_k$$

$$\mathcal{A}_E = \{a_i | a_i \in \mathcal{A}_o^a \cap \mathcal{A}_n^a \wedge$$

$$\exists a_j \in \mathcal{A}_n^a \setminus \mathcal{A}_k^a \wedge \exists \tau_k \in a_i.tc \exists \tau_l \in a_j.tc \wedge \tau_k.E = \tau_l.E\}$$

increasing

increasing

- Stage 4 – Complete rescheduling

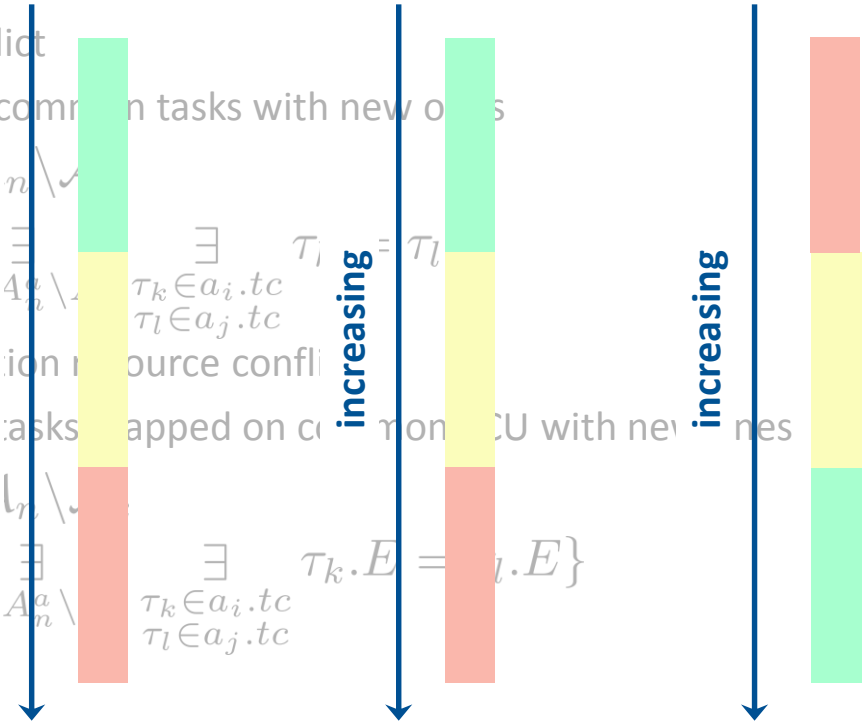
- All existing applications are considered reschedulable

$$\mathcal{A}_k = \mathcal{A}^b, \mathcal{A}_n = \mathcal{A}_n^a$$

Synthesis time in general

Disturbance to existing applications

New application accommodation



# Schedule Management Framework

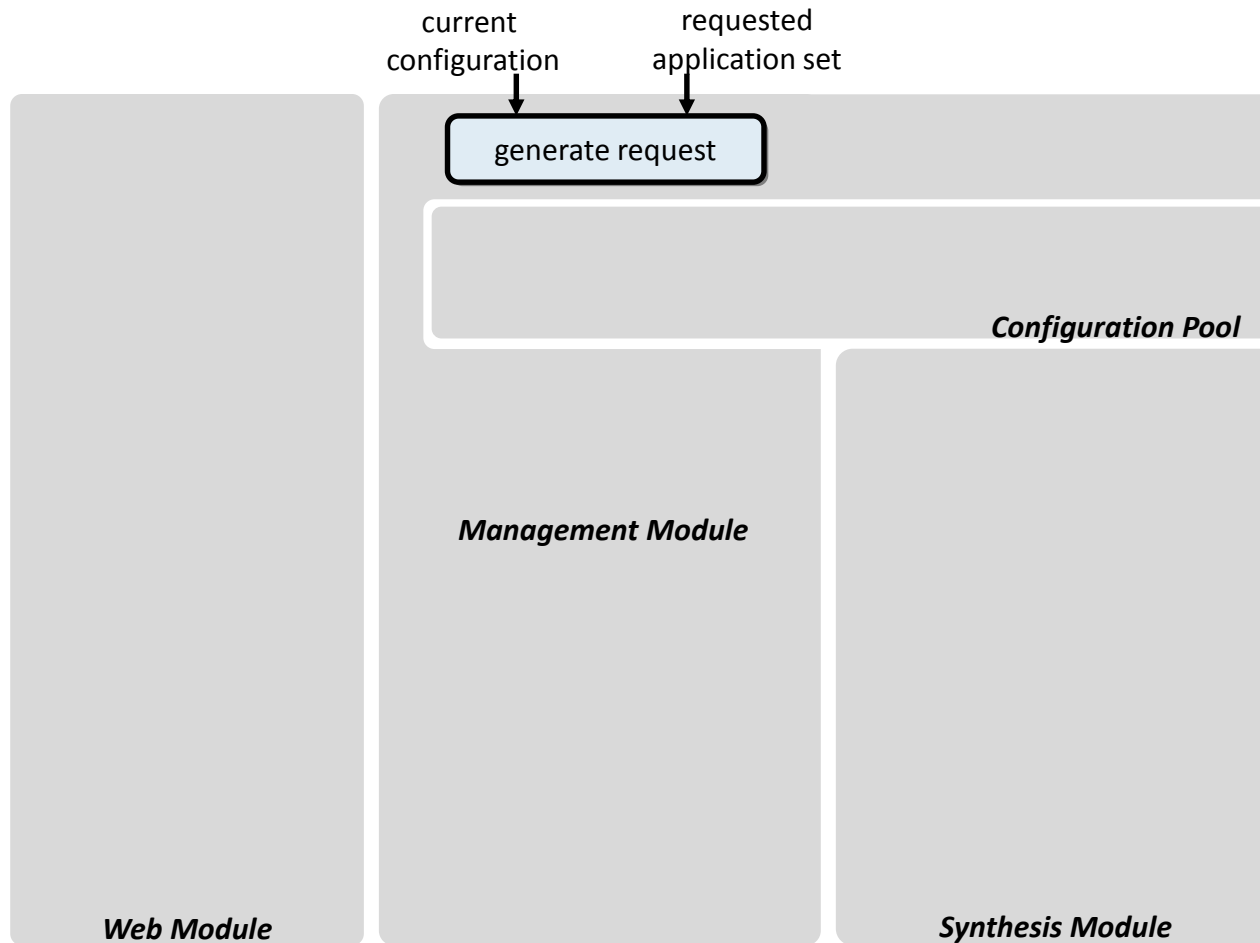
- **Web module**
  - Utilizes the WebSocket Secure
    - Full-duplex communication between client and server
    - SSL/TLS layer for secure communication

# Schedule Management Framework

- **Web module**
  - Utilizes the WebSocket Secure
    - Full-duplex communication between client and server
    - SSL/TLS layer for secure communication
  - Methods for client-server communication
    - Request
      - Client sends request file to server
    - Response
      - Server sends response to client: either a valid configuration or a request denial
    - Abort
      - Client informs the server to abort operation, when a local result is obtained first
    - Update
      - Client sends the new configuration to the server to update the configuration pool

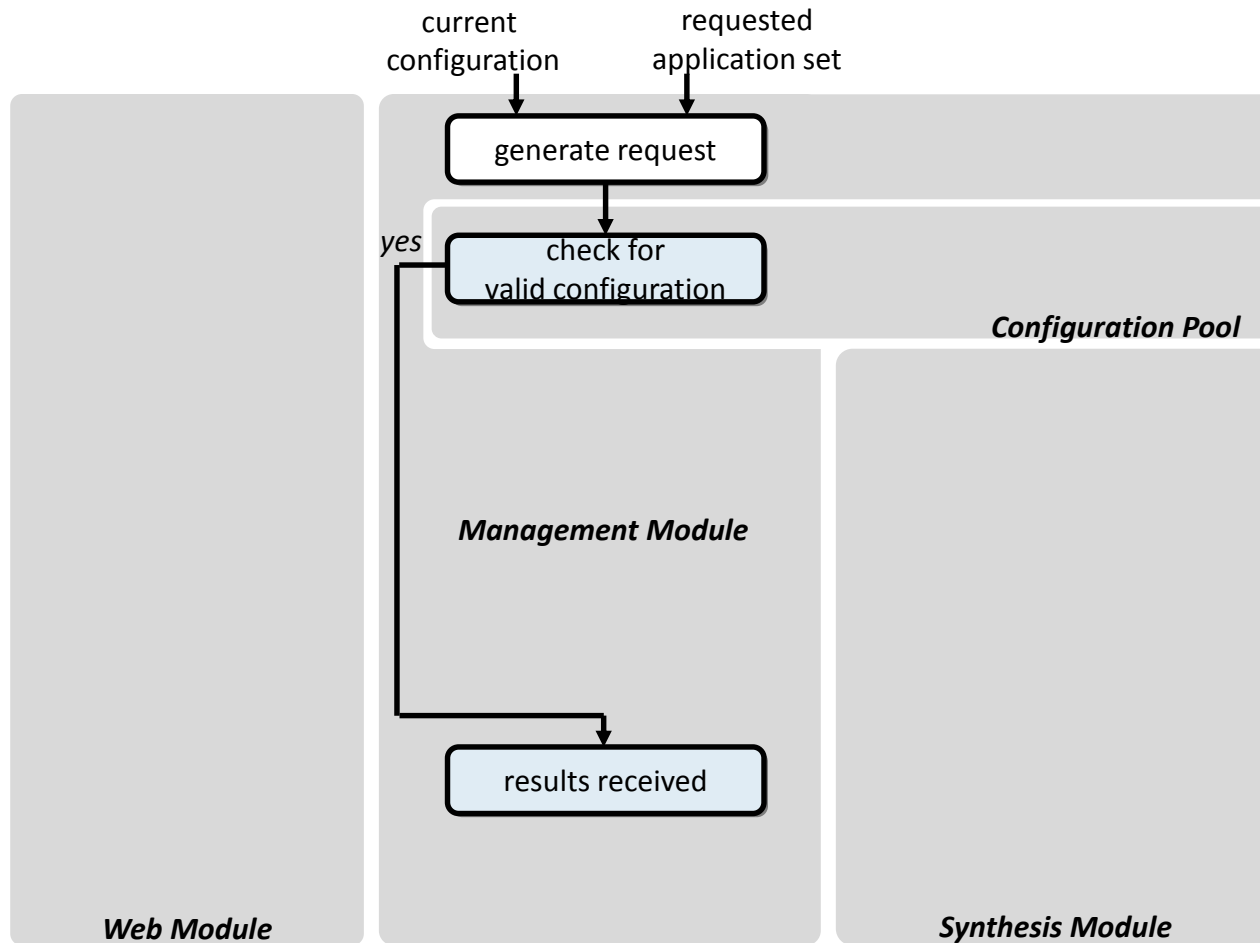
# Schedule Management Framework

- Management module – client side



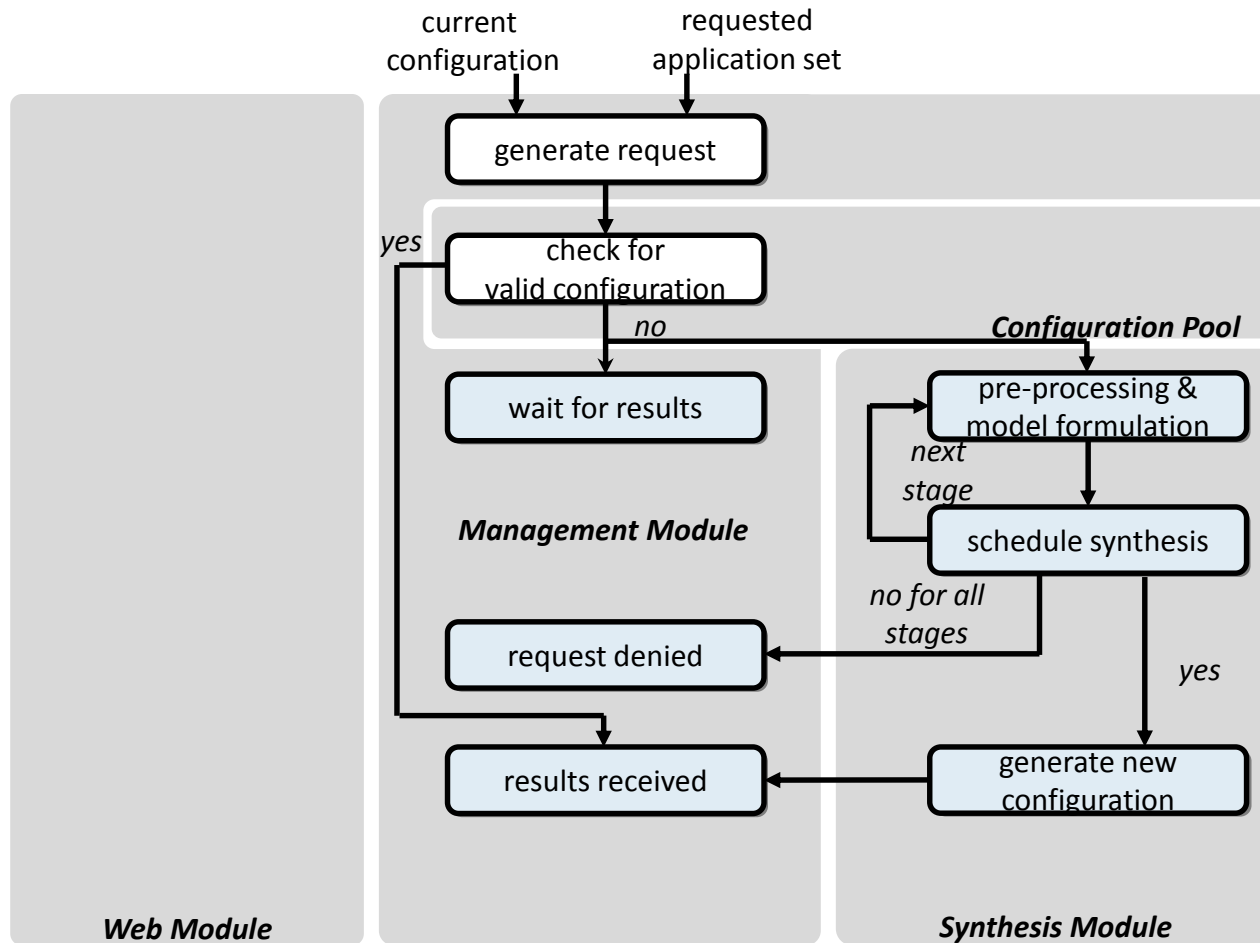
# Schedule Management Framework

- Management module – client side



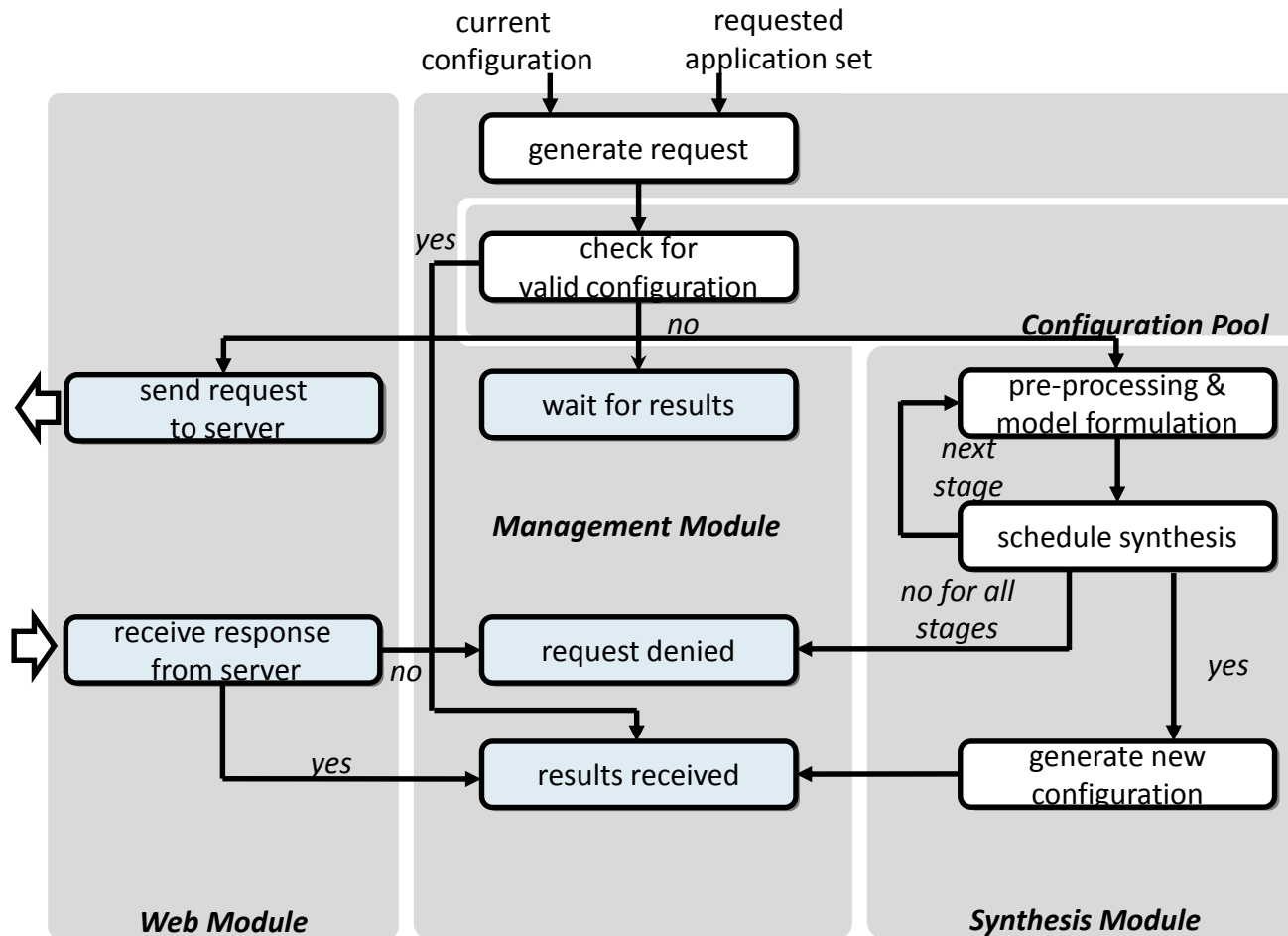
# Schedule Management Framework

- Management module – client side



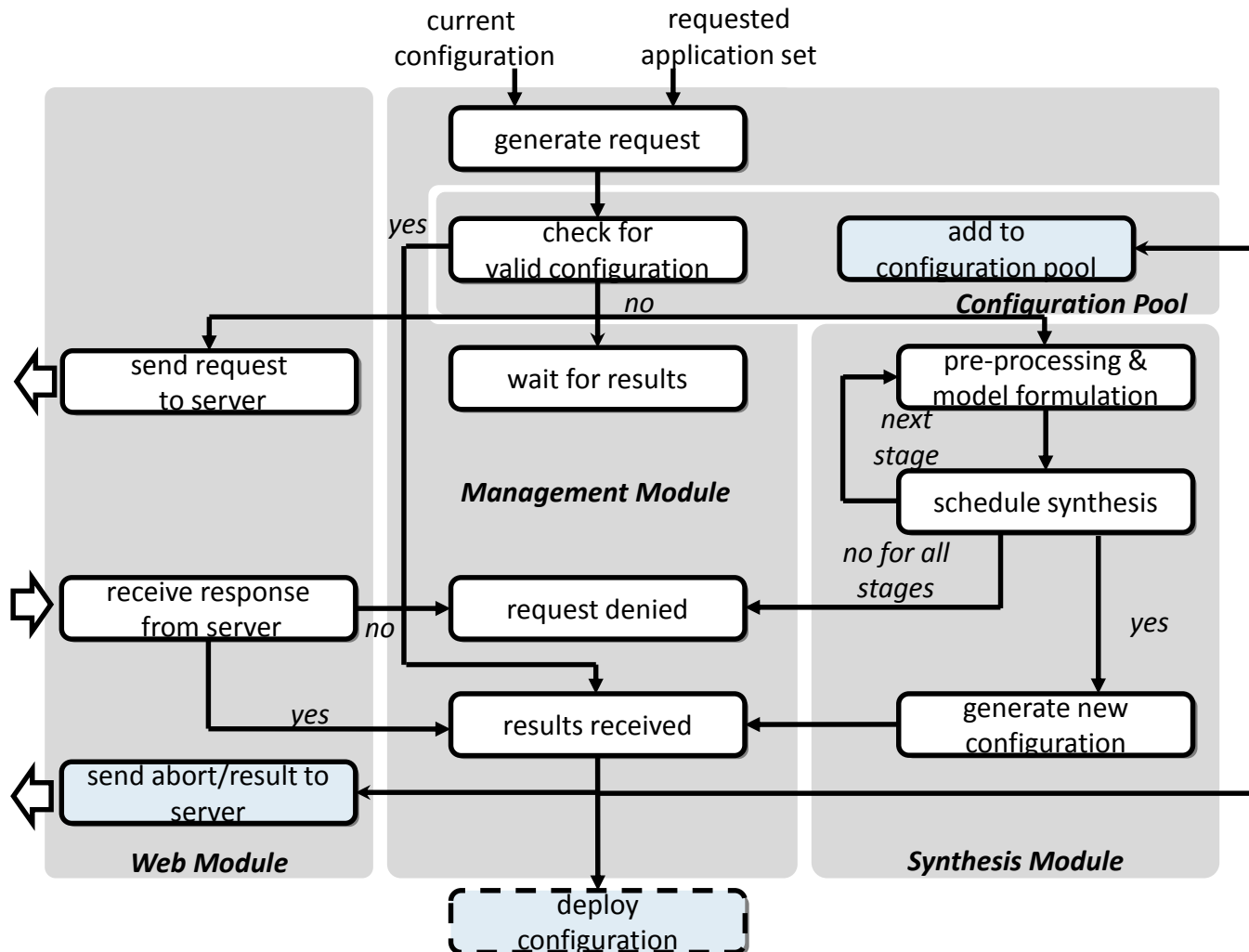
# Schedule Management Framework

- Management module – client side



# Schedule Management Framework

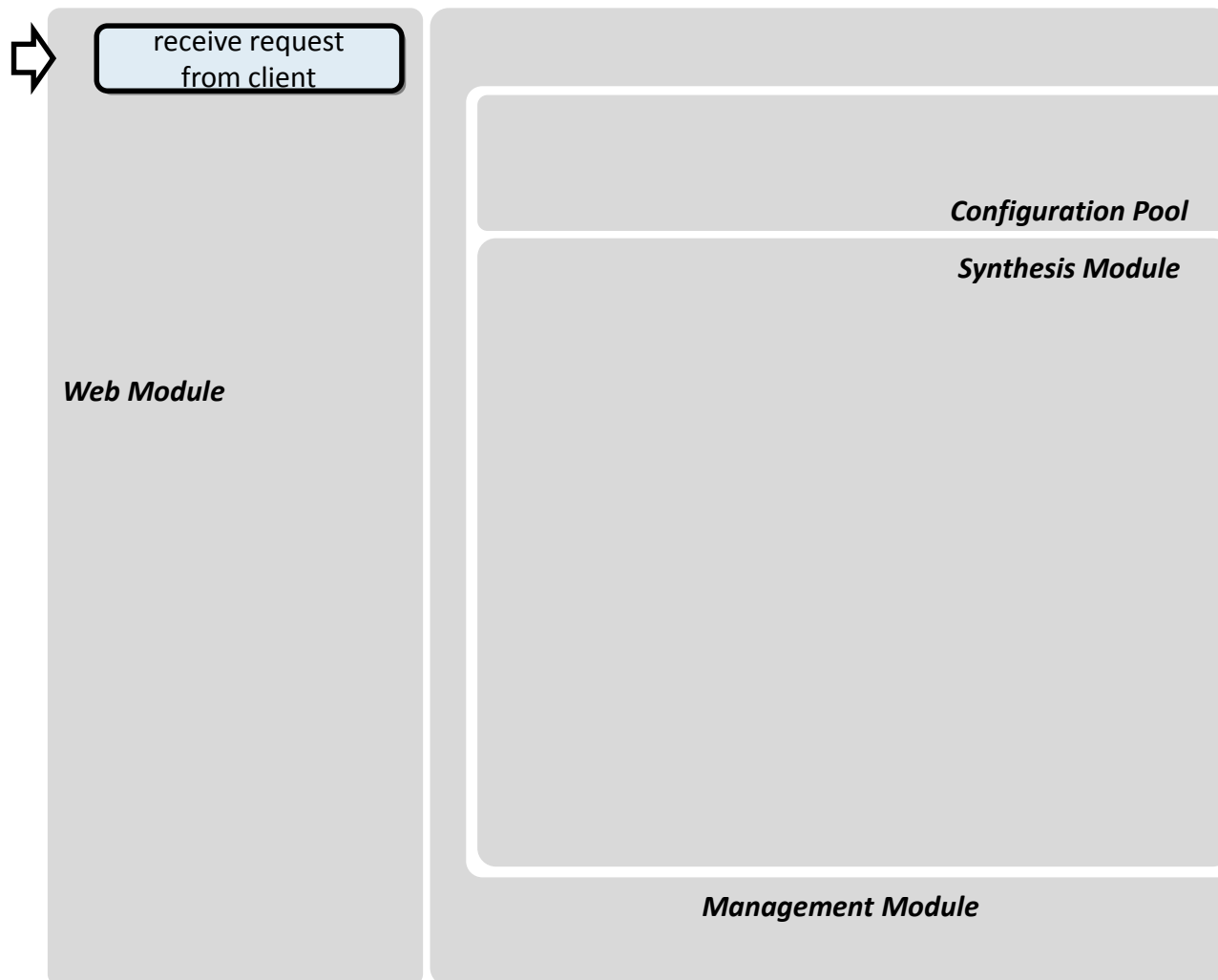
- Management module – client side





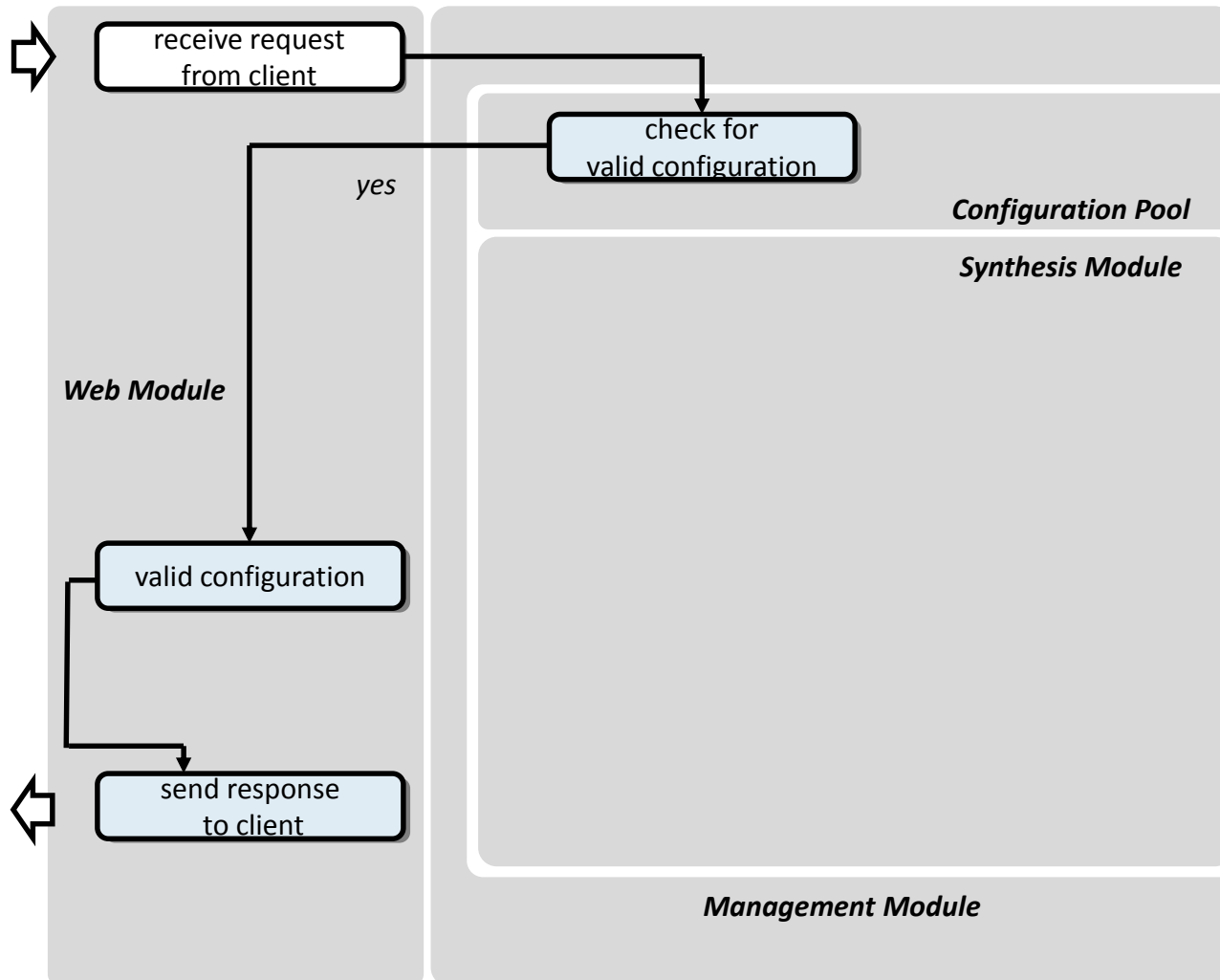
# Schedule Management Framework

- Management module –server side



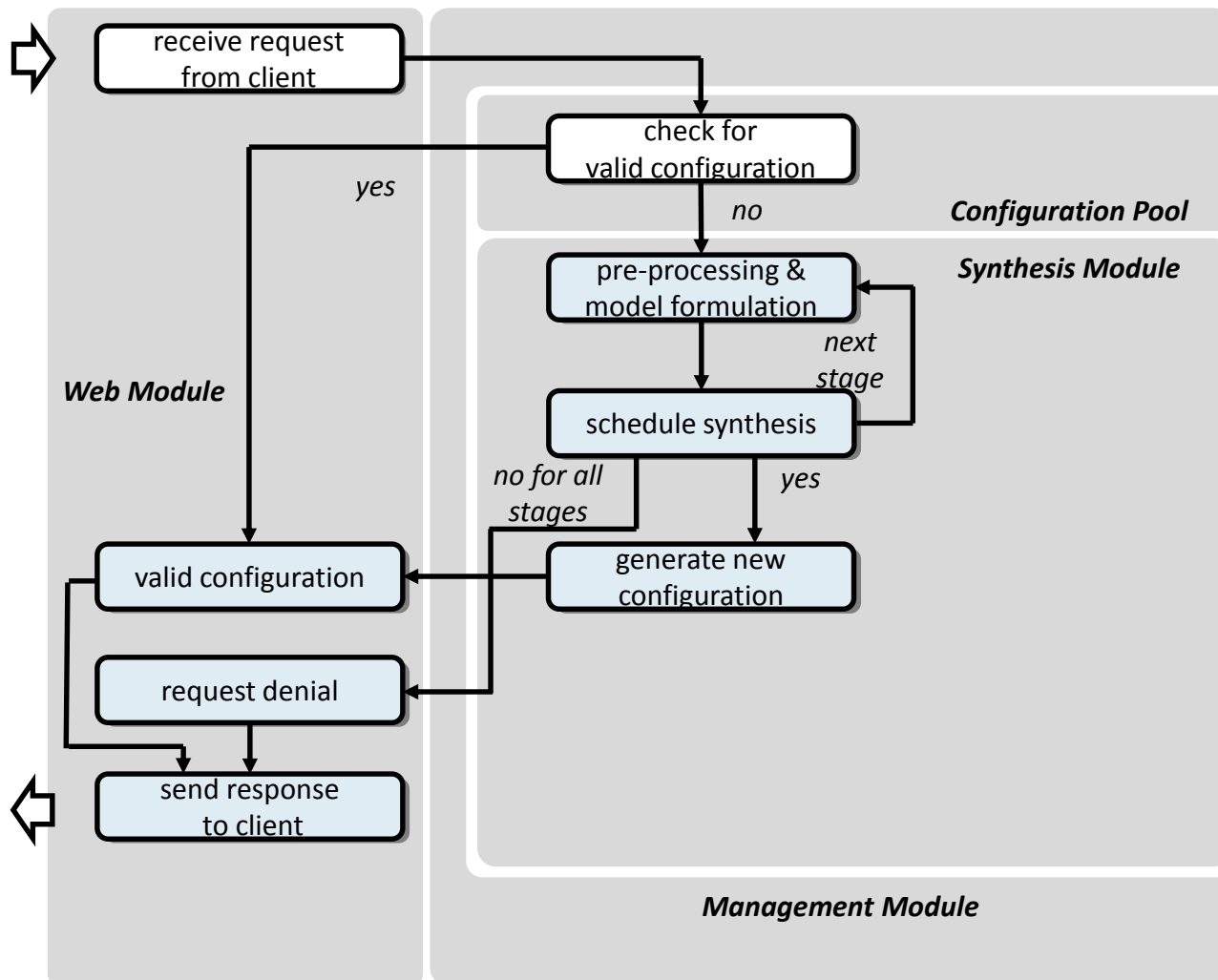
# Schedule Management Framework

- Management module –server side



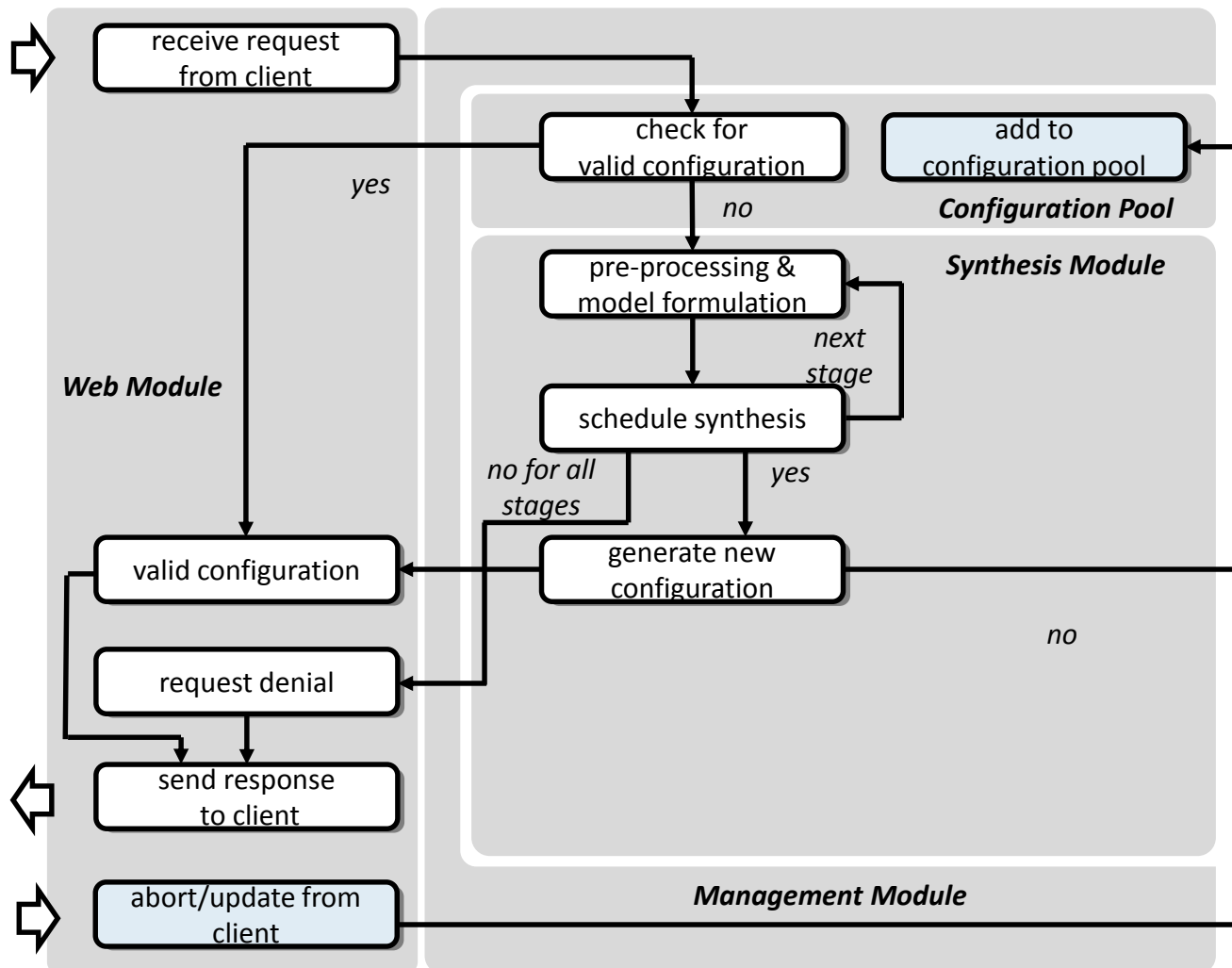
# Schedule Management Framework

- Management module –server side



# Schedule Management Framework

- Management module –server side

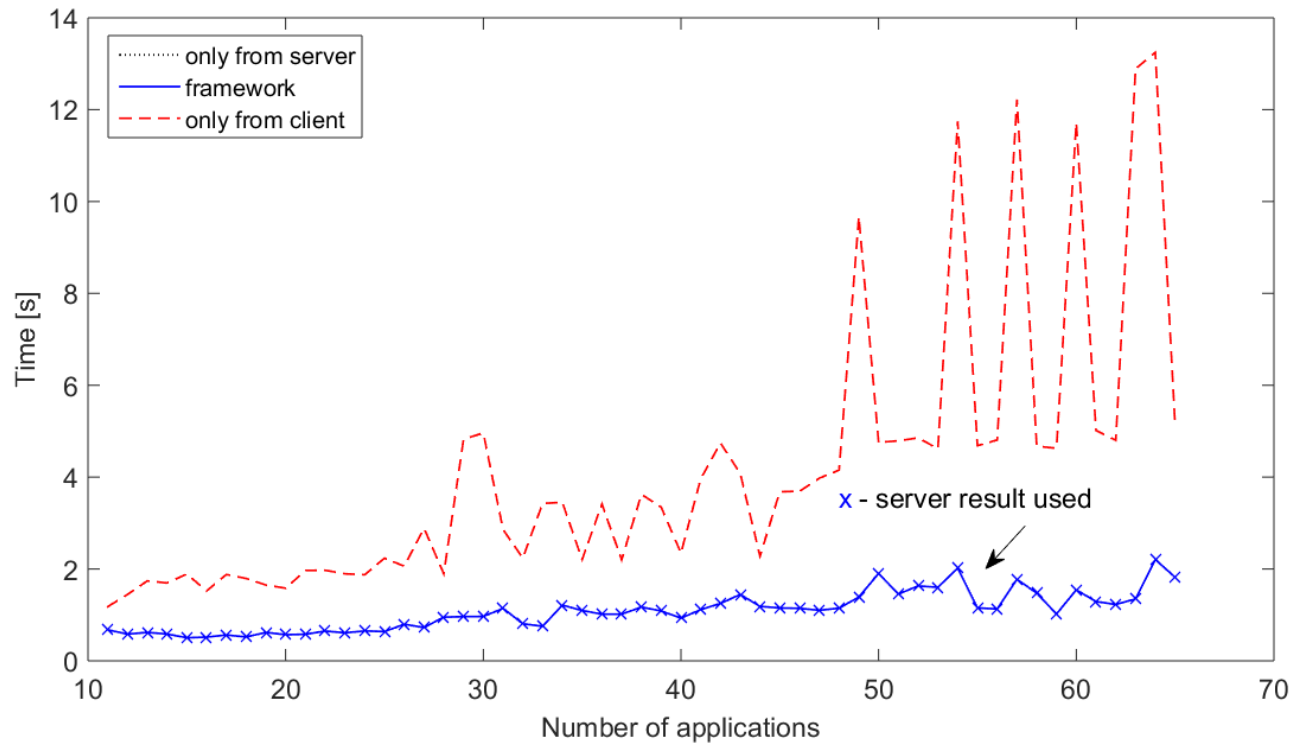


# Results

- **Implementation**
  - Client on a Raspberry PI 2 Model B
  - Server on a PC
  - Connection through WLAN
  
- **Case study**
  - Hardware architecture: 10 ECUs connected by 4 switches
  - 100 applications are randomly generated (10 basic applications, 90 plug-in applications)
  - 20 request series of incrementally adding applications
  - Different overhead provision for possible authentication and security process on server

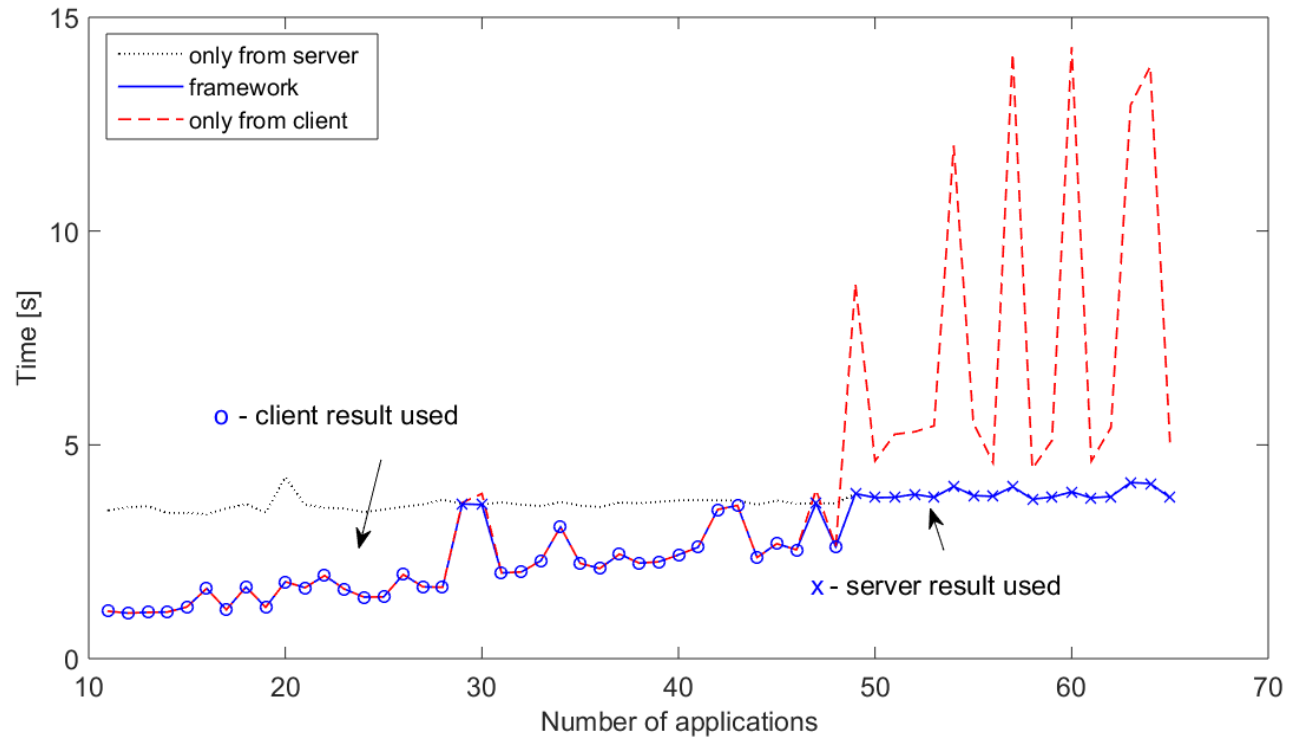
# Results

- **Synthesis time**
  - Case 0 s overhead provision for server



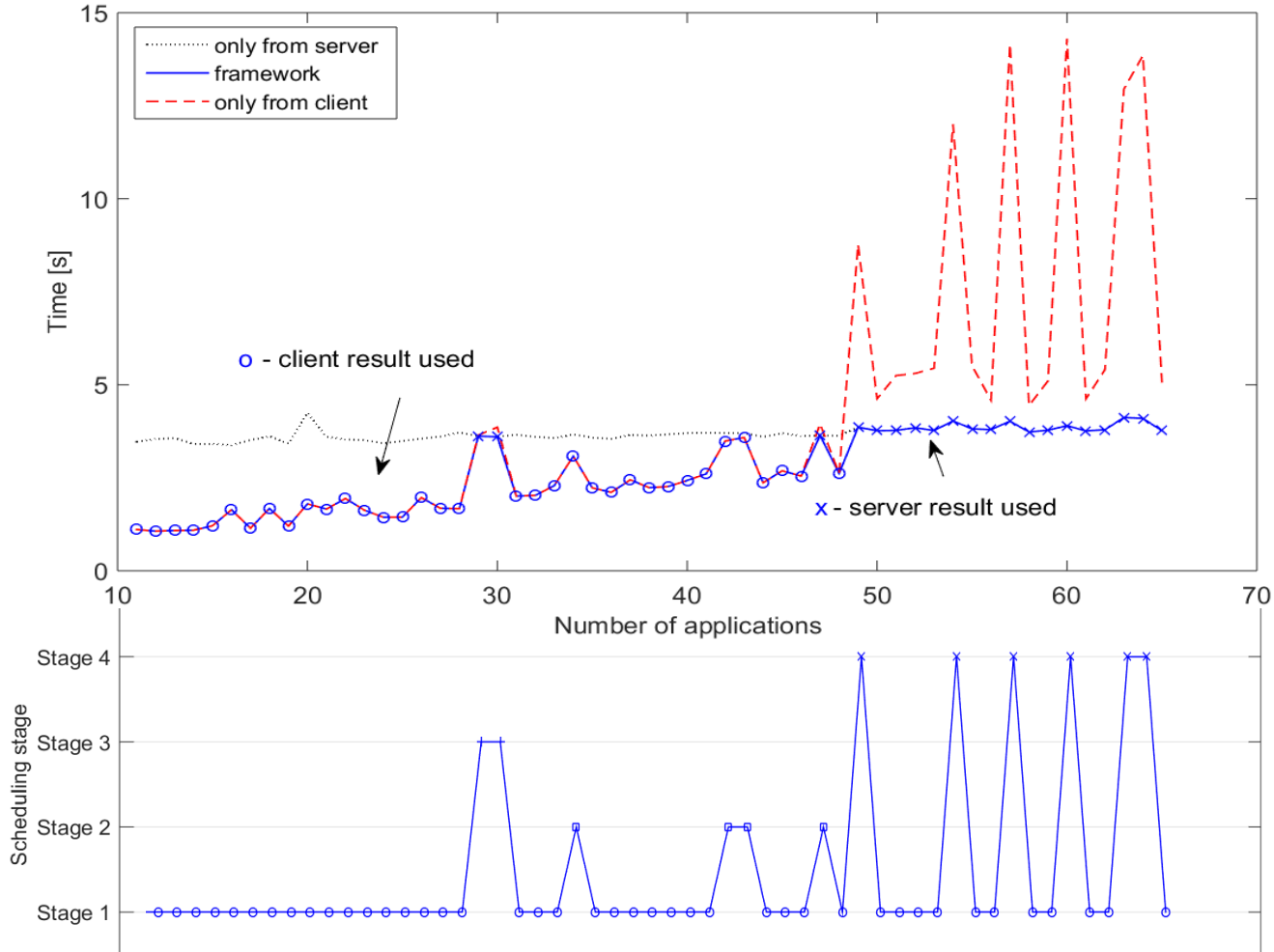
# Results

- **Synthesis time**
  - Case 3 s overhead provision for server



# Results

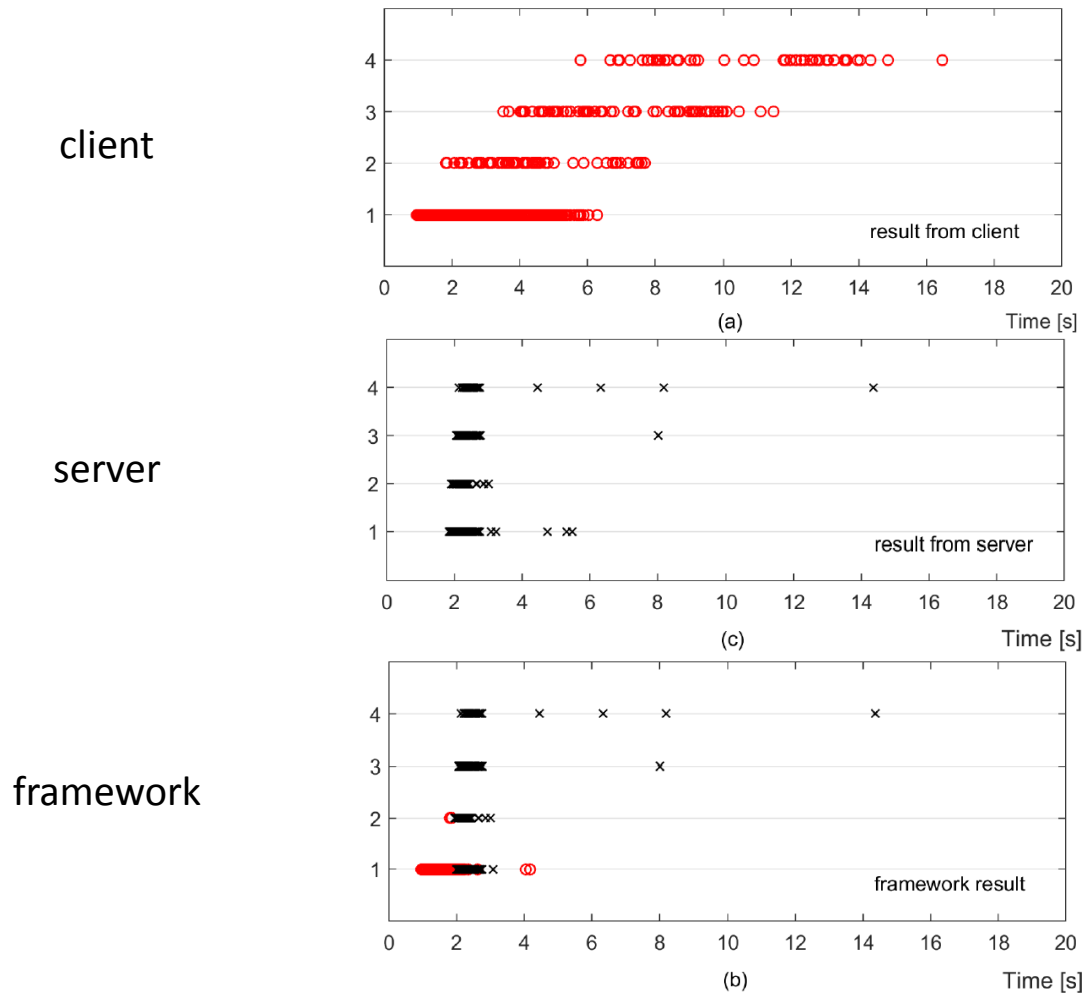
## ▪ Scheduling stages





# Results

- Comparison of synthesis time for client, server and proposed framework
  - Case 1.5 s overhead provision for server



# Concluding Remarks

- **Problem**
  - Ethernet-based time-triggered automotive system
  - Resource reallocation for accommodating new software applications in a Plug-and-Play manner

# Concluding Remarks

- **Problem**
  - Ethernet-based time-triggered automotive system
  - Resource reallocation for accommodating new software applications in a Plug-and-Play manner
  
- **Approach**
  - Client-server based software framework for schedule management
  - Use of local computation and cloud-computing for online schedule synthesis and management
  - Four-stage scheduling strategy for trade-off between synthesis time, disturbance to existing applications and the chances of accommodating new ones

# Concluding Remarks

- **Problem**
  - Ethernet-based time-triggered automotive system
  - Resource reallocation for accommodating new software applications in a Plug-and-Play manner
  
- **Approach**
  - Client-server based software framework for schedule management
  - Use of local computation and cloud-computing for online schedule synthesis and management
  - Four-stage scheduling strategy for trade-off between synthesis time, disturbance to existing applications and the chances of accommodating new ones
  
- **Future work**
  - Utilize the multi-core architecture to parallelize synthesis methods to reduce synthesis time
  - Explore extensibility-aware scheduling to provision resources for future applications so more applications can be accommodated using incremental design

# References

- [1] M. Di Natale, and A. Sangiovanni-Vincentelli, "Moving from federated to integrated architectures in automotive: the role of standards, methods and tools," Proc. of the IEEE, 2010.
- [2] J. Yoo, Y. Lee, D. Kim, and K. Park, "An Android-based automotive middleware architecture for Plug-and-Play of applications," ICOS, 2012.
- [3] H. Martorell, J. Fabre, M. Roy, and R. Valentin, "Towards Dynamic Updates in AUTOSAR," Workshop, International Conference on Computer Safety, Reliability and Security, 2013.
- [4] S. Sommer, A. Camek, K. Becker, C. Buckl, A. Zirkler, L. Fiege, M. Armbruster, G. Spiegelberg, and A. Knoll, "RACE: A centralized platform computer based architecture for automotive applications," IEVC, 2013.
- [5] J. Frtunikj, V. Rupanov, A. Camek, C. Buckl, and A. Knoll, "A safety aware run-time environment for adaptive automotive control systems," ERTS2, 2014.
- [6] C. Buckl, M. Geisinger, D. Gulati, F. Ruiz-Bertol, and A. Knoll, "CHROMOSOME: A run-time environment for plug\&play-capable embedded real-time system," APRES, 2014.
- [7] A. Zeeb, "Plug and play solution for Autosar software components," ATZelektronik worldwide, 2012.
- [8] AS6802: Time-triggered Ethernet. SAE International, 2011.
- [9] IEEE 802.1 Time-Sensitive Networking Task Group: <http://www.ieee802.org/1/pages/tsn.html>.
- [10] W. Steiner, "An evaluation of SMT-based schedule synthesis for time-triggered multi-hop networks," RTSS 2010.
- [11] W. Steiner, "Synthesis of static communication schedules for mixed-criticality systems," ISORCW, 2011.
- [12] P. Pop, P. Eles, Z. Peng, and T. Pop, "Scheduling and mapping in an incremental design methodology for distributed real-time embedded systems," IEEE Transactions on VLSI Systems, 2004.

# References

- [13] D. Tamas-Selicean, P. Pop, and W. Steiner, "Synthesis of communication schedules for TTEthernet-based mixed-criticality systems," CODES+ISSS, 2012.
- [14] R. S. Oliver, S. S. Craciunas, and G. Stoger, "Analysis of deterministic Ethernet scheduling for the industrial Internet of Things," CAMAD, 2014.
- [15] L. Zhang, D. Goswami, R. Schneider, and S. Chakraborty, "Task- and network-level schedule co-synthesis of Ethernet-based time-triggered systems," ASP-DAC, 2014.
- [16] S. S. Craciunas and R. S. Oliver, "SMT-based task- and network-level static schedule generation for time-triggered networked systems," RTNS, 2014.
- [17] F. Sagstetter, P. Waszecki, S. Steinhorst, M. Lukasiewicz, and S. Chakraborty, "Multischedule synthesis for variant management in automotive time-triggered systems," TCAD, 2015.
- [18] M. Gutierrez, W. Steiner, R. Dobrin, and S. Punnekkat, "A configuration agent based on the time-triggered paradigm for real-time networks," WFCS, 2015.
- [19] M. Gutierrez, W. Steiner, R. Dobrin, and S. Punnekkat, "Learning the parameters of periodic traffic based on network measurements," IEEE International Workshop on Measurements & Networking, 2015, pp 1-6.
- [20] W. Steiner, M. Gutierrez, Z. Matyas, F. Pozo, and G. Rodriguez-Navas, "Current techniques, trends and new horizons in avionics networks configuration," DASC, 2015.
- [21] Gecode: <http://www.gecode.org>.
- [22] <https://github.com/eidheim>.
- [23] G. C. Necula, "Proof-carrying code," POPL, 1997.

**Thanks for your attention!**

**Q/A**