

PIECEWISE POLYNOMIAL INTERPOLATION IN MUCKENHOUPHT WEIGHTED SOBOLEV SPACES AND APPLICATIONS

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ABSTRACT. We develop a constructive piecewise polynomial approximation theory in weighted Sobolev spaces with Muckenhoupt weights for any polynomial degree. The main ingredients to derive optimal error estimates for an averaged Taylor polynomial are a suitable weighted Poincaré inequality, a cancellation property and a simple induction argument. We also construct a quasi-interpolation operator, built on local averages over stars, which is well defined for functions in L^1 . We derive optimal error estimates for any polynomial degree on simplicial shape regular meshes. On rectangular meshes, these estimates are valid under the condition that neighboring elements have comparable size, which yields optimal anisotropic error estimates over n -rectangular domains. The interpolation theory extends to cases when the error and function regularity require different weights. We conclude with three applications: nonuniform elliptic boundary value problems, elliptic problems with singular sources, and fractional powers of elliptic operators.

1. INTRODUCTION

A fundamental tool in analysis, with both practical and theoretical relevance, is the approximation of a function by a simpler one. For continuous functions a foundational result in this direction was given by K. Weierstrass in 1885: continuous functions defined on a compact interval can be uniformly approximated as closely as desired by polynomials. Mollifiers, interpolants, splines and even Nevanlinna-Pick theory can be regarded as instances of this program; see, for instance, [2, 54]. For weakly differentiable functions, the approximation by polynomials is very useful when trying to understand their behavior. In fact, this idea goes back to S.L. Sobolev [68], who used a sort of averaged Taylor polynomial to discuss equivalent norms in Sobolev spaces.

The role of polynomial approximation and error estimation is crucial in numerical analysis: it is the basis of discretization techniques for partial differential equations (PDE), particularly the finite element method. For the latter, several constructions for standard Sobolev spaces W_p^1 , with $1 \leq p \leq \infty$, and their properties are well studied; see [24, 28, 29, 31, 65].

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On the other hand, many applications lead to boundary value problems for nonuniformly elliptic equations. The ellipticity distortion can be caused by degenerate/singular behavior of the coefficients of the differential operator or by singularities in the domain. For such equations it is natural to look for solutions in weighted Sobolev spaces [3, 10, 14, 15, 25, 33, 36, 37, 51, 70] and to study the regularity properties of the solution in weighted spaces as well [53]. Of particular importance are weighted Sobolev spaces with a weight belonging to the so-called Muckenhoupt class A_p [58]; see also [36, 49, 70]. However, the literature focusing on polynomial approximation in this type of Sobolev spaces is rather scarce; we refer the reader to [3, 4, 6, 10, 25, 39, 42, 56] for some partial results. Most of these results focus on a particular nonuniformly elliptic equation and exploit the special structure of the coefficient to derive polynomial interpolation results.

To fix ideas, consider the following nonuniformly elliptic boundary value problem: let Ω be an open and bounded subset of \mathbb{R}^n ($n \geq 1$) with boundary $\partial\Omega$. Given a function f , find u that solves

$$(1.1) \quad \begin{cases} -\operatorname{div}(\mathcal{A}(x)\nabla u) = f, & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \end{cases}$$

where $\mathcal{A} : \Omega \rightarrow \mathbb{R}^{n \times n}$ is symmetric and satisfies the following nonuniform ellipticity condition

$$(1.2) \quad \omega(x)|\xi|^2 \lesssim \xi^\top \mathcal{A}(x)\xi \lesssim \omega(x)|\xi|^2, \quad \forall \xi \in \mathbb{R}^n, \quad a.e. \ \Omega.$$

Here the relation $a \lesssim b$ indicates that $a \leq Cb$, with a constant C and ω is a weight function, i.e., a nonnegative and locally integrable measurable function, which might vanish, blow up, and possess singularities. Examples of this type of equations are the harmonic extension problem related with the fractional Laplace operator [14, 15, 60], elliptic problems involving measures [3, 25], elliptic PDE in an axisymmetric three dimensional domain with axisymmetric data [10, 42], and equations modeling the motion of particles in a central potential field in quantum mechanics [6]. Due to the nature of the coefficient \mathcal{A} , the classical Sobolev space $H^1(\Omega)$ is not appropriate for the analysis and approximation of this problem.

Nonuniformly elliptic equations of the type (1.1)–(1.2), with ω in the so-called Muckenhoupt class A_2 , have been studied in [36]: for $f \in L^2(\omega^{-1}, \Omega)$, there exists a unique solution in $H_0^1(\omega, \Omega)$ [36, Theorem 2.2] (see § 2.2 for notation). Consider the discretization of (1.1) with the finite element method. Let \mathcal{T} be a conforming triangulation of Ω and let $\mathbb{V}(\mathcal{T})$ be a finite element space. The Galerkin approximation of the solution to (1.1) is given by the unique function $U_{\mathcal{T}} \in \mathbb{V}(\mathcal{T})$ that solves

$$(1.3) \quad \int_{\Omega} \mathcal{A} \nabla U_{\mathcal{T}} \cdot \nabla W = \int_{\Omega} f W, \quad \forall W \in \mathbb{V}(\mathcal{T}).$$

Invoking Galerkin orthogonality, we deduce

$$(1.4) \quad \|u - U_{\mathcal{T}}\|_{H_0^1(\omega, \Omega)} \lesssim \inf_{W \in \mathbb{V}(\mathcal{T})} \|u - W\|_{H_0^1(\omega, \Omega)}.$$

In other words, the numerical analysis of this boundary value problem reduces to a result in approximation theory: the distance between the exact solution u and its approximation $U_{\mathcal{T}}$ in a finite element space is bounded by the best approximation error in the finite element space with respect to an appropriate weighted Sobolev

norm. A standard way of obtaining bounds for the approximation error is by considering $W = \Pi_{\mathcal{T}}v$ in (1.4), where $\Pi_{\mathcal{T}}$ is a suitable interpolation operator.

The purpose of this work is twofold. We first go back to the basics, and develop an elementary constructive approach to piecewise polynomial interpolation in weighted Sobolev spaces with Muckenhoupt weights. We consider an averaged version of the Taylor polynomial and, upon using an appropriate weighted Poincaré inequality and a cancellation property, we derive optimal approximation estimates for constant and linear approximations. We extend these results to any polynomial degree m ($m \geq 0$), by a simple induction argument.

The functional framework considered is weighted Sobolev spaces with weights in the Muckenhoupt class $A_p(\mathbb{R}^n)$, thereby extending the classical polynomial approximation theory in Sobolev spaces [13, 23, 24, 65]. In addition, we point out that the results about interpolation in Orlicz spaces of [26, 30] do not apply to our situation since, for weighted spaces, the Young function used to define the modular depends on the point in space as well. In this respect, our results can be regarded as a first step in the development of an approximation theory in Orlicz-Musiela spaces and in Sobolev spaces in metric measure spaces [46].

The second main contribution of this work is the construction of a quasi-interpolation operator $\Pi_{\mathcal{T}}$, built on local averages over stars and thus well defined for functions in $L^1(\Omega)$ as those in [24, 65]. The ensuing polynomial approximation theory in weighted Sobolev spaces with Muckenhoupt weights allows us to obtain optimal and local interpolation estimates for the quasi-interpolant $\Pi_{\mathcal{T}}$. On simplicial discretizations, these results hold true for any polynomial degree $m \geq 0$, and they are derived in the weighted W_p^k -seminorm ($0 \leq k \leq m+1$). The key ingredient is an invariance property of the quasi-interpolant $\Pi_{\mathcal{T}}$ over the finite element space. On the other hand, on rectangular discretizations, we only assume that neighboring cells in \mathcal{T} have comparable size, as in [31, 60]. This mild assumption enables us also to obtain anisotropic error estimates for domains that can be decomposed into n -rectangles. These estimates are derived in the weighted W_p^1 -semi-norm and the weighted L^p -norm, the latter being a new result even for the unweighted setting. For $m = 0, 1$, we also derive interpolation estimates in the space $W_q^m(\rho, \Omega)$ when the smoothness is measured in the space $W_p^{m+1}(\omega, \Omega)$, with different weights $\omega \neq \rho$ and Lebesgue exponents $1 < p \leq q$, provided $W_p^{m+1}(\omega, \Omega) \hookrightarrow W_q^m(\rho, \Omega)$.

The outline of this paper is as follows. In § 2.1 we introduce some terminology used throughout this work. In § 2.2, we recall the definition of a Muckenhoupt class, weighted Sobolev spaces and some of their properties. Section 3 is dedicated to an important weighted L^p -based Poincaré inequality over star-shaped domains and domains that can be written as the finite union of star-shaped domains. In section 4, we consider an averaged version of the Taylor polynomial, and we develop a constructive theory of piecewise polynomial interpolation in weighted Sobolev spaces with Muckenhoupt weights. We discuss the quasi-interpolation operator $\Pi_{\mathcal{T}}$ and its properties in section 5. We derive optimal approximation properties in the weighted W_p^k -seminorm for simplicial triangulations in § 5.1. In § 5.2 we derive anisotropic error estimates on rectangular discretizations for a \mathbb{Q}_1 quasi-interpolant operator assuming that Ω is an n -rectangle. Section 6 is devoted to derive optimal and local interpolation estimates for different metrics (i.e., $p \leq q$, $\omega \neq \rho$). Finally, in section 7 we present applications of our interpolation theory to

nonuniformly elliptic equations (1.1), elliptic equations with singular sources, and fractional powers of elliptic operators.

2. NOTATION AND PRELIMINARIES

2.1. Notation. Throughout this work, Ω is an open, bounded and connected subset of \mathbb{R}^n , with $n \geq 1$. The boundary of Ω is denoted by $\partial\Omega$. Unless specified otherwise, we will assume that $\partial\Omega$ is Lipschitz.

The set of locally integrable functions on Ω is denoted by $L^1_{\text{loc}}(\Omega)$. The Lebesgue measure of a measurable subset $E \subset \mathbb{R}^n$ is denoted by $|E|$. The mean value of a locally integrable function f over a set E is

$$\int_E f \, dx = \frac{1}{|E|} \int_E f \, dx.$$

For a multi-index $\kappa = (\kappa_1, \dots, \kappa_n) \in \mathbb{N}^n$ we denote its length by $|\kappa| = \kappa_1 + \dots + \kappa_n$, and, if $x \in \mathbb{R}^n$, we set $x^\kappa = x_1^{\kappa_1} \dots x_n^{\kappa_n} \in \mathbb{R}$, and

$$D^\kappa = \frac{\partial^{\kappa_1}}{\partial x_1^{\kappa_1}} \dots \frac{\partial^{\kappa_n}}{\partial x_n^{\kappa_n}}.$$

Given $p \in (1, \infty)$, we denote by p' the real number such that $1/p + 1/p' = 1$, i.e., $p' = p/(p-1)$.

Let $\gamma, z \in \mathbb{R}^n$, the binary operation $\circ : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$ is defined by

$$(2.1) \quad \gamma \circ z = (\gamma_1 z_1, \gamma_2 z_2, \dots, \gamma_n z_n) \in \mathbb{R}^n.$$

If X and Y are topological vector spaces, we write $X \hookrightarrow Y$ to denote that X is continuously embedded in Y . We denote by X' the dual of X . If X is normed, we denote by $\|\cdot\|_X$ its norm. The relation $a \lesssim b$ indicates that $a \leq Cb$, with a constant C that does not depend on either a or b , the value of C might change at each occurrence.

2.2. Weighted Sobolev spaces. We now introduce the class of Muckenhoupt weighted Sobolev spaces and refer to [27, 36, 50, 51, 70] for details. We start with the definition of a weight.

Definition 2.1 (weight). A weight is a function $\omega \in L^1_{\text{loc}}(\mathbb{R}^n)$ such that $\omega(x) > 0$ for a.e. $x \in \mathbb{R}^n$.

Every weight induces a measure, with density $\omega \, dx$, over the Borel sets of \mathbb{R}^n . For simplicity, this measure will also be denoted by ω . For a Borel set $E \subset \mathbb{R}^n$ we define $\omega(E) = \int_E \omega \, dx$.

We recall the definition of Muckenhoupt classes; see [27, 36, 58, 70].

Definition 2.2 (Muckenhoupt class A_p). Let ω be a weight and $1 < p < \infty$. We say $\omega \in A_p(\mathbb{R}^n)$ if there exists a positive constant $C_{p,\omega}$ such that

$$(2.2) \quad \sup_B \left(\int_B \omega \right) \left(\int_B \omega^{1/(1-p)} \right)^{p-1} = C_{p,\omega} < \infty,$$

where the supremum is taken over all balls B in \mathbb{R}^n . In addition,

$$A_\infty(\mathbb{R}^n) = \bigcup_{p>1} A_p(\mathbb{R}^n), \quad A_1(\mathbb{R}^n) = \bigcap_{p>1} A_p(\mathbb{R}^n).$$

If ω belongs to the Muckenhoupt class $A_p(\mathbb{R}^n)$, we say that ω is an A_p -weight, and we call the constant $C_{p,\omega}$ in (2.2) the A_p -constant of ω .

A classical example is the function $|x|^\gamma$, which is an A_p -weight if and only if $-n < \gamma < n(p-1)$. Another important example is $d(x) = d(x, \partial\Omega)^\alpha$, where for $x \in \Omega$, $d(x, \partial\Omega)$ denotes the distance from the point x to the boundary $\partial\Omega$. The function d belongs to $A_2(\mathbb{R}^n)$ if and only if $-n < \alpha < n$. This function is used to define weighted Sobolev spaces which are important to study Poisson problems with singular sources; see [3, 25].

Throughout this work, we shall use some properties of the A_p -weights which, for completeness, we state and prove below.

Proposition 2.1 (properties of the A_p -class). *Let $1 < p < \infty$, and $\omega \in A_p(\mathbb{R}^n)$. Then, we have the following properties:*

- (i) $\omega^{-1/(p-1)} \in L_{\text{loc}}^1(\mathbb{R}^n)$.
- (ii) $C_{p,\omega} \geq 1$.
- (iii) If $1 < p < r < \infty$, then $A_p(\mathbb{R}^n) \subset A_r(\mathbb{R}^n)$, and $C_{r,\omega} \leq C_{p,\omega}$.
- (iv) $\omega^{-1/(p-1)} \in A_{p'}(\mathbb{R}^n)$ and, conversely, $\omega^{-1/(p'-1)} \in A_p(\mathbb{R}^n)$. Moreover,

$$C_{p',\omega^{-1/(p-1)}} = C_{p,\omega}^{1/(p-1)}.$$

- (v) The A_p -condition is invariant under translations and isotropic dilations, i.e., the weights $x \mapsto \omega(x + \mathbf{b})$ and $x \mapsto \omega(\mathbf{A}x)$, with $\mathbf{b} \in \mathbb{R}^n$ and $\mathbf{A} = a \cdot \mathbf{I}$ with $a \in \mathbb{R}$, both belong to $A_p(\mathbb{R}^n)$ with the same A_p -constant as ω .

Proof. Properties (i) and (iv) follow directly from the definition of the Muckenhoupt class $A_p(\mathbb{R}^n)$ given in (2.2). By writing $1 = \omega^{1/p}\omega^{-1/p}$ and the Hölder inequality, we obtain that for every ball $B \subset \mathbb{R}^n$,

$$1 = \int_B \omega^{1/p}\omega^{-1/p} \leq \left(\int_B \omega \right)^{1/p} \left(\int_B \omega^{-1/(p-1)} \right)^{(p-1)/p},$$

which proves (ii). Using the Hölder inequality again, we obtain

$$\left(\int_B \omega^{1/(1-r)} \right)^{r-1} \leq \left(\int_B \omega^{1/(1-p)} \right)^{p-1},$$

which implies (iii). Finally, to prove property (v) we denote $\bar{\omega}(x) = \omega(\mathbf{A}x + \mathbf{b})$, and let B_r be a ball of radius r in \mathbb{R}^n . Using the change of variables $y = \mathbf{A}x + \mathbf{b}$, we obtain

$$(2.3) \quad \int_{B_r} \bar{\omega}(x) dx = \frac{1}{a^n |B_r|} \int_{B_{ar}} \omega(y) dy,$$

which, since $a^n |B_r| = |B_{ar}|$, proves (v). \square

From the A_p -condition and Hölder's inequality follows that an A_p -weight satisfies the so-called *strong doubling property*. The proof of this fact is standard and presented here for completeness; see [70, Proposition 1.2.7] for more details.

Proposition 2.2 (strong doubling property). *Let $\omega \in A_p(\mathbb{R}^n)$ with $1 < p < \infty$ and let $E \subset \mathbb{R}^n$ be a measurable subset of a ball $B \subset \mathbb{R}^n$. Then*

$$(2.4) \quad \omega(B) \leq C_{p,\omega} \left(\frac{|B|}{|E|} \right)^p \omega(E).$$

Proof. Since $E \subset \mathbb{R}^n$ is measurable, we have that

$$\begin{aligned} |E| &\leq \left(\int_E \omega \, dx \right)^{1/p} \left(\int_E \omega^{-p'/p} \, dx \right)^{1/p'} \leq \omega(E)^{1/p} |B|^{1/p'} \left(\int_B \omega^{-p'/p} \right)^{1/p'} \\ &\leq C_{p,\omega}^{1/p} \omega(E)^{1/p} |B|^{1/p'} \left(\int_B \omega \right)^{-1/p} = C_{p,\omega}^{1/p} \left(\frac{\omega(E)}{\omega(B)} \right)^{1/p} |B|. \end{aligned}$$

This completes the proof. \square

In particular, every A_p -weight satisfies a *doubling property*, i.e., there exists a positive constant C such that

$$(2.5) \quad \omega(B_{2r}) \leq C\omega(B_r).$$

for every ball $B_r \subset \mathbb{R}^n$. The infimum over all constants C , for which (2.5) holds, is called the *doubling constant* of ω . The class of A_p -weights was introduced by B. Muckenhoupt [58], who proved that the A_p -weights are precisely those for which the Hardy-Littlewood maximal operator is bounded from $L^p(\omega, \mathbb{R}^n)$ to $L^p(\omega, \mathbb{R}^n)$, when $1 < p < \infty$. We now define weighted Lebesgue spaces as follows.

Definition 2.3 (weighted Lebesgue spaces). Let $\omega \in A_p$, and let $\Omega \subset \mathbb{R}^n$ be an open and bounded domain. For $1 < p < \infty$, we define the weighted Lebesgue space $L^p(\omega, \Omega)$ as the set of measurable functions u on Ω equipped with the norm

$$(2.6) \quad \|u\|_{L^p(\omega, \Omega)} = \left(\int_{\Omega} |u|^p \omega \right)^{1/p}.$$

An immediate consequence of $\omega \in A_p(\mathbb{R}^n)$ is that functions in $L^p(\omega, \Omega)$ are locally summable which, in fact, only requires that $\omega^{-1/(p-1)} \in L^1_{\text{loc}}(\mathbb{R}^n)$.

Proposition 2.3 ($L^p(\omega, \Omega) \subset L^1_{\text{loc}}(\Omega)$). *Let Ω be an open set, $1 < p < \infty$ and ω be a weight such that $\omega^{-1/(p-1)} \in L^1_{\text{loc}}(\Omega)$. Then, $L^p(\omega, \Omega) \subset L^1_{\text{loc}}(\Omega)$.*

Proof. Let $u \in L^p(\omega, \Omega)$, and let $B \subset \Omega$ be a ball. By Hölder's inequality, we have

$$\int_B |u| = \int_B |u| \omega^{1/p} \omega^{-1/p} \leq \left(\int_B |u|^p \omega \right)^{1/p} \left(\int_B \omega^{-1/(p-1)} \right)^{(p-1)/p} \lesssim \|u\|_{L^p(\omega, \Omega)},$$

which concludes the proof. \square

Notice that when Ω is bounded we have $L^p(\omega, \Omega) \hookrightarrow L^1(\Omega)$. In particular, Proposition 2.3 shows that it makes sense to talk about weak derivatives of functions in $L^p(\omega, \Omega)$. We define weighted Sobolev spaces as follows.

Definition 2.4 (weighted Sobolev spaces). Let ω be an A_p -weight with $1 < p < \infty$, $\Omega \subset \mathbb{R}^n$ be an open and bounded domain and $m \in \mathbb{N}$. The weighted Sobolev space $W_p^m(\omega, \Omega)$ is the set of functions $u \in L^p(\omega, \Omega)$ such that for any multi-index κ with $|\kappa| \leq m$, the weak derivatives $D^\kappa u \in L^p(\omega, \Omega)$, with seminorm and norm

$$|u|_{W_p^m(\omega, \Omega)} = \left(\sum_{|\kappa|=m} \|D^\kappa u\|_{L^p(\omega, \Omega)}^p \right)^{1/p}, \quad \|u\|_{W_p^m(\omega, \Omega)} = \left(\sum_{j \leq m} |u|_{W_p^j(\omega, \Omega)}^p \right)^{1/p},$$

respectively. We also define $\mathring{W}_p^m(\omega, \Omega)$ as the closure of $C_0^\infty(\Omega)$ in $W_p^m(\omega, \Omega)$.

Without any restriction on the weight ω , the space $W_p^m(\omega, \Omega)$ may not be complete. However, when $\omega^{-1/(p-1)}$ is locally integrable in \mathbb{R}^n , $W_p^m(\omega, \Omega)$ is a Banach space; see [52]. Properties of weighted Sobolev spaces can be found in classical references like [50, 51, 70]. It is remarkable that most of the properties of classical Sobolev spaces have a weighted counterpart and it is more so that this is not because of the specific form of the weight but rather due to the fact that the weight ω belongs to the Muckenhoupt class A_p ; see [36, 41, 58]. In particular, we have the following results (cf. [70, Proposition 2.1.2, Corollary 2.1.6] and [41, Theorem 1]).

Proposition 2.4 (properties of weighted Sobolev spaces). *Let $\Omega \subset \mathbb{R}^n$ be an open and bounded domain, $1 < p < \infty$, $\omega \in A_p(\mathbb{R}^n)$ and $m \in \mathbb{N}$. The spaces $W_p^m(\omega, \Omega)$ and $\mathring{W}_p^m(\omega, \Omega)$ are complete, and $W_p^m(\omega, \Omega) \cap C^\infty(\Omega)$ is dense in $W_p^m(\omega, \Omega)$.*

3. A WEIGHTED POINCARÉ INEQUALITY

In order to obtain interpolation error estimates in $L^p(\omega, \Omega)$ and $W_p^1(\omega, \Omega)$, it is instrumental to have a weighted Poincaré-like inequality [31, 60]. A pioneering reference is the work by Fabes, Kenig and Serapioni [36], which shows that, when the domain is a ball and the weight belongs to A_p with $1 < p < \infty$, a weighted Poincaré inequality holds [36, Theorem 1.3 and Theorem 1.5]. For generalizations of this result see [38, 47]. For a star-shaped domain, and a specific A_2 -weight, we have proved a weighted Poincaré inequality [60, Lemma 4.3]. In this section we extend this result to a general exponent p and a general weight $\omega \in A_p(\mathbb{R}^n)$. Our proof is constructive and not based on a compactness argument. This allows us to trace the dependence of the stability constant on the domain geometry.

Lemma 3.1 (weighted Poincaré inequality I). *Let $S \subset \mathbb{R}^n$ be bounded, star-shaped with respect to a ball \hat{B} , with $\text{diam } S \approx 1$. Let χ be a continuous function on S with $\|\chi\|_{L^1(S)} = 1$. Given $\omega \in A_p(\mathbb{R}^n)$, we define $\mu(x) = \omega(\mathbf{A}x + \mathbf{b})$, for $\mathbf{b} \in \mathbb{R}^n$ and $\mathbf{A} = a \cdot \mathbf{I}$, with $a \in \mathbb{R}$. If $v \in W_p^1(\mu, S)$ is such that $\int_S \chi v = 0$, then*

$$(3.1) \quad \|v\|_{L^p(\mu, S)} \lesssim \|\nabla v\|_{L^p(\mu, S)},$$

where the hidden constant depends only on χ , $C_{p, \omega}$ and the radius \hat{r} of \hat{B} , but is independent of \mathbf{A} and \mathbf{b} .

Proof. Property (v) of Proposition 2.1 shows that $\mu \in A_p(\mathbb{R}^n)$ and $C_{\mu, p} = C_{\omega, p}$. Given $v \in W_p^1(\mu, S)$, we define

$$\tilde{v} = \text{sign}(v)|v|^{p-1}\mu - \left(\int_S \text{sign}(v)|v|^{p-1}\mu \right) \chi.$$

Hölder's inequality yields

$$(3.2) \quad \int_S \mu |v|^{p-1} = \int_S \mu^{1/p'} |v|^{p-1} \mu^{1/p} \leq \left(\int_S \mu |v|^p \right)^{1/p'} \left(\int_S \mu \right)^{1/p} \lesssim \|v\|_{L^p(\mu, S)}^{p-1},$$

which implies that $\tilde{v} \in L^1(S)$ and $\|\tilde{v}\|_{L^1(S)} \lesssim \|v\|_{L^p(\mu, S)}^{p-1}$. Notice, in addition, that since $\int_S \chi = 1$, the function \tilde{v} has vanishing mean value.

Given $1 < p < \infty$, we define $q = -p'/p$, and we notice that $q + p' = 1$ and $p'(p-1) = p$. We estimate $\|\tilde{v}\|_{L^{p'}(\mu^q, S)}$ as follows:

$$\begin{aligned} \left(\int_S \mu^q |\tilde{v}|^{p'} \right)^{1/p'} &= \left(\int_S \mu^q \left| \text{sign}(v) |v|^{p-1} \mu - \left(\int_S \text{sign}(v) |v|^{p-1} \mu \right) \chi \right|^{p'} \right)^{1/p'} \\ &\leq \left(\int_S \mu^{q+p'} |v|^{p'(p-1)} \right)^{1/p'} + \left(\int_S |v|^{p-1} \mu \right) \|\chi\|_{L^{p'}(\mu^q, S)} \\ &\lesssim \|v\|_{L^p(\mu, S)}^{p-1}, \end{aligned}$$

where we have used (3.2) together with the fact that $\mu \in A_p(\mathbb{R}^n)$ implies $\mu^q \in L_{\text{loc}}^1(\mathbb{R}^n)$ (see Proposition 2.1 (i)), whence $\|\chi\|_{L^{p'}(\mu^q, S)} \leq \|\chi\|_{L^\infty(S)} \mu^q(S)^{1/p'} \lesssim 1$.

Properties $\mu^q \in A_{p'}(\mathbb{R}^n)$, that S is star-shaped with respect to \hat{B} and $\tilde{v} \in L^{p'}(\mu^q, S)$ has vanishing mean value, suffice for the existence of a vector field $\mathbf{u} \in \mathring{W}_{p'}^1(\mu^q, S)$ satisfying

$$\text{div } \mathbf{u} = \tilde{v},$$

and,

$$(3.3) \quad \|\nabla \mathbf{u}\|_{L^{p'}(\mu^q, S)} \lesssim \|\tilde{v}\|_{L^{p'}(\mu^q, S)},$$

where the hidden constant depends on C_{p', μ^q} and the radius r of \hat{B} ; see [33, Theorem 3.1].

Finally, since $\int_S \chi v = 0$, the definition of \tilde{v} implies

$$\|v\|_{L^p(\mu, S)}^p = \int_S v \tilde{v} + \left(\int_S \text{sign}(v) |v|^{p-1} \mu \right) \int_S \chi v = \int_S v \tilde{v}.$$

Replacing \tilde{v} by $-\text{div } \mathbf{u}$, integrating by parts and using (3.3), we conclude

$$\begin{aligned} \|v\|_{L^p(\mu, S)}^p &= \int_S \nabla v \cdot \mathbf{u} \leq \left(\int_S \mu |\nabla v|^p \right)^{1/p} \left(\int_S \mu^q |\mathbf{u}|^{p'} \right)^{1/p'} \\ &\lesssim \|\nabla v\|_{L^p(\mu, S)} \|\tilde{v}\|_{L^{p'}(\mu^q, S)}. \end{aligned}$$

Invoking $\|\tilde{v}\|_{L^{p'}(\mu^q, S)} \lesssim \|v\|_{L^p(\mu, S)}^{p-1}$ yields the desired inequality. \square

In section 5 we construct an interpolation operator based on local averages. Consequently, the error estimates on an element T depend on the behavior of the function over a so-called *patch* of T , which is not necessarily star shaped. Then, we need to relax the geometric assumptions on the domain S and let the vanishing mean property hold just in a subdomain. The following result is an adaptation of [60, Corollary 4.4].

Corollary 3.2 (weighted Poincaré inequality II). *Let $S = \cup_{i=1}^N S_i \subset \mathbb{R}^n$ be a connected domain and each S_i be star-shaped with respect to a ball B_i . Let $\chi_i \in C^0(\bar{S}_i)$ and μ be as in Lemma 3.1. If $v \in W_p^1(\mu, S)$ and $v_i = \int_{S_i} v \chi_i$, then*

$$(3.4) \quad \|v - v_i\|_{L^p(\mu, S)} \lesssim \|\nabla v\|_{L^p(\mu, S)} \quad \forall 1 \leq i \leq N,$$

where the hidden constant depends on $\{\chi_i\}_{i=1}^N$, the radii r_i of B_i , and the amount of overlap between the subdomains $\{S_i\}_{i=1}^N$, but is independent of \mathbf{A} and \mathbf{b} .

Proof. This is an easy consequence of Lemma 3.1 and [28, Theorem 7.1]. For completeness, we sketch the proof. It suffices to deal with two subdomains S_1, S_2 and the overlapping region $D = S_1 \cap S_2$. We start from

$$\|v - v_1\|_{L^p(\mu, S_2)} \leq \|v - v_2\|_{L^p(\mu, S_2)} + \|v_1 - v_2\|_{L^p(\mu, S_2)}.$$

Since v_1 and v_2 are constant

$$\|v_1 - v_2\|_{L^p(\mu, S_2)} = \left(\frac{\mu(S_2)}{\mu(D)} \right)^{1/p} \|v_1 - v_2\|_{L^p(\mu, D)},$$

which together with

$$\|v - v_2\|_{L^p(\mu, D)} \leq \|v - v_1\|_{L^p(\mu, S_1)} + \|v - v_2\|_{L^p(\mu, S_2)},$$

and (3.1) imply $\|v - v_1\|_{L^p(\mu, S_2)} \lesssim \|\nabla v\|_{L^p(\mu, S_1 \cup S_2)}$. This and (3.1) give (3.4) for $i = 1$, with a stability constant depending on the ratio $\frac{\mu(S_2)}{\mu(D)}$. \square

4. APPROXIMATION THEORY IN WEIGHTED SOBOLEV SPACES

In this section, we introduce an averaged version of the Taylor polynomial and study its approximation properties in Muckenhoupt weighted Sobolev spaces. Our results are optimal and are used to obtain error estimates for the quasi-interpolation operator defined in section 5 on simplicial and rectangular discretizations. The interpolation operator is built on local averages over stars, and so is similar to the one introduced in [28]. The main difference is that it is directly defined on the given mesh instead of using a reference element. This idea is fundamental in order to relax the regularity assumptions on the elements, which is what allows us to derive the anisotropic estimates on rectangular elements presented in § 5.2.

4.1. Discretization. We start with some terminology and describe the construction of the underlying finite element spaces. In order to avoid technical difficulties we shall assume $\partial\Omega$ is polyhedral. We denote by $\mathcal{T} = \{T\}$ a partition, or mesh, of Ω into elements T (simplices or cubes) such that

$$\bar{\Omega} = \bigcup_{T \in \mathcal{T}} T, \quad |\Omega| = \sum_{T \in \mathcal{T}} |T|.$$

The mesh \mathcal{T} is assumed to be conforming or compatible: the intersection of any two elements is either empty or a common lower dimensional element. We denote by \mathbb{T} a collection of conforming meshes, which are *shape regular* i.e., there exists a constant $\sigma > 1$ such that, for all $\mathcal{T} \in \mathbb{T}$,

$$(4.1) \quad \max \{ \sigma_T : T \in \mathcal{T} \} \leq \sigma,$$

where $\sigma_T = h_T/\rho_T$ is the shape coefficient of T . In the case of simplices, $h_T = \text{diam}(T)$ and ρ_T is the diameter of the sphere inscribed in T ; see, for instance, [13]. For the definition of h_T and ρ_T in the case of n -rectangles see [23].

In § 5.2, we consider rectangular discretizations of the domain $\Omega = (0, 1)^n$ which satisfy a weaker regularity assumption and thus allow for anisotropy in each coordinate direction (cf. [31]).

Given a mesh $\mathcal{T} \in \mathbb{T}$, we define the finite element space of continuous piecewise polynomials of degree $m \geq 1$

$$(4.2) \quad \mathbb{V}(\mathcal{T}) = \{W \in C^0(\bar{\Omega}) : W|_T \in \mathcal{P}(T) \forall T \in \mathcal{T}, W|_{\partial\Omega} = 0\},$$

where, for a simplicial element T , $\mathcal{P}(T)$ corresponds to \mathbb{P}_m — the space of polynomials of total degree at most m . If T is an n -rectangle, then $\mathcal{P}(T)$ stands for \mathbb{Q}_m — the space of polynomials of degree not larger than m in each variable.

Given an element $T \in \mathcal{T}$, we denote by $\mathcal{N}(T)$ and $\mathring{\mathcal{N}}(T)$ the set of nodes and interior nodes of T , respectively. We set $\mathcal{N}(\mathcal{T}) := \cup_{T \in \mathcal{T}} \mathcal{N}(T)$ and $\mathring{\mathcal{N}}(\mathcal{T}) := \mathcal{N}(\mathcal{T}) \cap \partial\Omega$. Then, any discrete function $V \in \mathbb{V}(\mathcal{T})$ is characterized by its nodal values on the set $\mathring{\mathcal{N}}(\mathcal{T})$. Moreover, the functions $\phi_z \in \mathbb{V}(\mathcal{T})$, $z \in \mathring{\mathcal{N}}(\mathcal{T})$, such that $\phi_z(y) = \delta_{yz}$ for all $y \in \mathcal{N}(\mathcal{T})$ are the canonical basis of $\mathbb{V}(\mathcal{T})$, and

$$V = \sum_{z \in \mathring{\mathcal{N}}(\mathcal{T})} V(z) \phi_z.$$

The functions $\{\phi_z\}_{z \in \mathring{\mathcal{N}}(\mathcal{T})}$ are the so called *shape functions*.

Given $z \in \mathcal{N}(\mathcal{T})$, the *star* or *patch* around z is $S_z := \cup_{z \in T} T$, and, for $T \in \mathcal{T}$, its *patch* is $S_T := \cup_{z \in T} S_z$. For each $z \in \mathcal{N}(\mathcal{T})$, we define $h_z := \min\{h_T : z \in T\}$.

4.2. The averaged interpolation operator. We now develop an approximation theory in Muckenhoupt weighted Sobolev spaces, which is instrumental in section 5. We define an averaged Taylor polynomial, built on local averages over stars and thus well defined for $L^p(\omega, \Omega)$ -functions. Exploiting the weighted Poincaré inequality derived in section 3, we show optimal error estimates for constant and linear approximations. These results are the basis to extend these estimates to any polynomial degree via a simple induction argument in section 4.4.

Let $\psi \in C^\infty(\mathbb{R}^n)$ be such that $\int \psi = 1$ and $\text{supp } \psi \subset B$, where B denotes the ball in \mathbb{R}^n of radius $r = r(\sigma)$ and centered at zero. For $z \in \mathring{\mathcal{N}}(\mathcal{T})$, we define the rescaled smooth functions

$$(4.3) \quad \psi_z(x) = \frac{(m+1)^n}{h_z^n} \psi\left(\frac{(m+1)(z-x)}{h_z}\right),$$

where $m \geq 0$ is the polynomial degree. The scaling of ψ_z involving the factor $m+1$ guarantees the property

$$\text{supp } \psi_z \subset S_z$$

for all nodes $z \in \mathring{\mathcal{N}}(\mathcal{T})$ (not just the interior vertices of \mathcal{T}) provided r is suitable chosen. This is because the distance from z to ∂S_z is proportional to $h_z/(m+1)$ for shape regular meshes.

Given a smooth function v , we denote by $P^m v(x, y)$ the Taylor polynomial of order m in the variable y about the point x , i.e.,

$$(4.4) \quad P^m v(x, y) = \sum_{|\alpha| \leq m} \frac{1}{\alpha!} D^\alpha v(x) (y-x)^\alpha.$$

For $z \in \mathring{\mathcal{N}}(\mathcal{T})$, and $v \in W_p^m(\omega, \Omega)$, we define the corresponding *averaged* Taylor polynomial of order m of v about the node z as

$$(4.5) \quad Q_z^m v(y) = \int P^m v(x, y) \psi_z(x) \, dx.$$

Integration by parts shows that $Q_z^m v$ is well-defined for functions in $L^1(\Omega)$ [13, Proposition 4.1.12]. Proposition 2.3 then allows us to conclude that (4.5) is well defined for $v \in L^p(\omega, \Omega)$. Since $\text{supp } \psi_z \subset S_z$, the integral appearing in (4.5) can be also written over S_z . Moreover, we have the following properties of $Q_z^m v$:

- $Q_z^m v$ is a polynomial of degree less or equal than m in the variable y (cf. [13, Proposition 4.1.9]).
- $Q_z^m v = Q_z^m Q_z^m v$, i.e., Q_z^m is invariant over \mathbb{P}_m .
- For any α such that $|\alpha| \leq m$,

$$(4.6) \quad D^\alpha Q_z^m v = Q_z^{m-|\alpha|} D^\alpha v \quad \forall v \in W_1^{|\alpha|}(B),$$

(cf. [13, Proposition 4.1.17]). As a consequence of $\omega \in A_p(\mathbb{R}^n)$, together with Proposition 2.3, we have that (4.6) holds for v in $W_1^{|\alpha|}(\omega, B)$.

The following stability result is important in the subsequent analysis.

Lemma 4.1 (stability of Q_z^m). *Let $\omega \in A_p(\mathbb{R}^n)$ and $z \in \mathring{\mathcal{X}}(\mathcal{T})$. If $v \in W_p^k(\omega, S_z)$, with $0 \leq k \leq m$, we have the following stability result*

$$(4.7) \quad \|Q_z^m v\|_{L^\infty(S_z)} \lesssim h_z^{-n} \|1\|_{L^{p'}(\omega^{-p'/p}, S_z)} \sum_{l=0}^k h_z^l \|v\|_{W_p^l(\omega, S_z)}.$$

Proof. Using the definition of the averaged Taylor polynomial (4.5), we arrive at

$$\|Q_z^m v\|_{L^\infty(S_z)} \lesssim \sum_{|\alpha| \leq m} \left\| \int_{S_z} D^\alpha v(x) (y-x)^\alpha \psi_z(x) dx \right\|_{L^\infty(S_z)}.$$

This implies estimate (4.7) if $k = m$. Otherwise, integration by parts on the higher derivatives $D^\alpha v$ with $k < |\alpha| \leq m$, $\psi_z = 0$ on ∂S_z , the fact that $D^\alpha \psi$ is uniformly bounded on \mathbb{R}^n , the estimate $|y-x| \lesssim h_z$ for all $x, y \in S_z$, together with Hölder's inequality, yield (4.7). \square

Given $\omega \in A_p(\mathbb{R}^n)$ and $v \in W_p^{m+1}(\omega, \Omega)$ with $m \geq 0$, in the next section we derive approximation properties of the averaged Taylor polynomial $Q_z^m v$ in the weighted $W_p^k(\omega, \Omega)$ -norm, with $0 \leq k \leq m$, via a weighted Poincaré inequality and a simple induction argument. Consequently, we must first study the approximation properties of $Q_z^0 v$, the weighted average of $v \in L^p(\omega, \Omega)$, which for $z \in \mathring{\mathcal{X}}(\mathcal{T})$ reads

$$(4.8) \quad Q_z^0 v = \int_{S_z} v(x) \psi_z(x) dx.$$

4.3. Weighted L^p -based error estimates. We start by adapting the proofs of [31, Lemma 2.3] and [60, Lemma 4.5] to obtain local approximation estimates in the weighted L^p -norm for the polynomials $Q_z^0 v$ and $Q_z^1 v$.

Lemma 4.2 (weighted L^p -based error estimates). *Let $z \in \mathring{\mathcal{X}}(\mathcal{T})$. If $v \in W_p^1(\omega, S_z)$, then we have*

$$(4.9) \quad \|v - Q_z^0 v\|_{L^p(\omega, S_z)} \lesssim h_z \|\nabla v\|_{L^p(\omega, S_z)}.$$

If $v \in W_p^2(\omega, S_z)$ instead, the following estimate holds

$$(4.10) \quad \|\partial_{x_j}(v - Q_z^1 v)\|_{L^p(\omega, S_z)} \lesssim h_z \|\partial_{x_j} \nabla v\|_{L^p(\omega, S_z)},$$

for $j = 1, \dots, n$. In both inequalities, the hidden constants depend only on $C_{p,\omega}$, σ and ψ .

Proof. Define the mapping $\mathcal{F}_z : x \mapsto \bar{x}$ by

$$\bar{x} = \frac{z-x}{h_z},$$

the star $\bar{S}_z = \mathcal{F}_z(S_z)$ and the function $\bar{v}(\bar{x}) = v(x)$. Set $\bar{Q}^0 \bar{v} = \int \bar{v} \psi \, d\bar{x}$, where ψ is the smooth function introduced in section 4.2.

Notice that $\text{supp } \psi \subset \bar{S}_z$. Consequently, in the definition of $\bar{Q}^0 \bar{v}$, integration takes place over \bar{S}_z only. Using the mapping \mathcal{F}_z , we have

$$Q_z^0 v = \int_{S_z} v \psi_z \, dx = \int_{\bar{S}_z} \bar{v} \psi \, d\bar{x} = \bar{Q}^0 \bar{v},$$

and, since $\int_{\bar{S}_z} \psi \, d\bar{x} = 1$,

$$(4.11) \quad \int_{\bar{S}_z} (\bar{v} - \bar{Q}^0 \bar{v}) \psi \, d\bar{x} = \int_{\bar{S}_z} \bar{v} \psi \, d\bar{x} - \bar{Q}^0 \bar{v} = 0.$$

Define the weight $\bar{\omega}_z = \omega \circ \mathcal{F}_z^{-1}$. In light of property (v) in Proposition 2.1 we have $\bar{\omega}_z \in A_p(\mathbb{R}^n)$ and $C_{p, \bar{\omega}_z} = C_{p, \omega}$. Changing variables we get

$$(4.12) \quad \int_{S_z} \omega |v - Q_z^0 v|^p \, dx = h_z^n \int_{\bar{S}_z} \bar{\omega}_z |\bar{v} - \bar{Q}^0 \bar{v}|^p \, d\bar{x}.$$

As a consequence of the shape regularity assumption (4.1), $\text{diam } \bar{S}_z \approx 1$. Then, in view of (4.11), we can apply Lemma 3.1 to $\bar{v} - \bar{Q}^0 \bar{v}$ over $S = \bar{S}_z$, with $\mu = \bar{\omega}_z$ and $\chi = \psi$, to conclude

$$\|\bar{v} - \bar{Q}^0 \bar{v}\|_{L^p(\bar{\omega}_z, \bar{S}_z)} \lesssim \|\bar{\nabla} \bar{v}\|_{L^p(\bar{\omega}_z, \bar{S}_z)},$$

where the hidden constant depends only on σ , $C_{p, \bar{\omega}_z}$ and ψ . Inserting this estimate into (4.12) and changing variables with \mathcal{F}_z^{-1} to get back to S_z we get (4.9).

In order to prove (4.10), we modify \mathcal{F}_z and S_z appropriately and define

$$\bar{Q}^1 \bar{v}(\bar{y}) = \int_{\bar{S}_z} (\bar{v}(\bar{x}) + \bar{\nabla} \bar{v}(\bar{x}) \cdot (\bar{y} - \bar{x})) \psi(\bar{x}) \, d\bar{x},$$

We observe that $Q_z^1 v(y) = \bar{Q}^1 \bar{v}(\bar{y})$, where $Q_z^1 v$ is defined by (4.5). Since $\partial_{\bar{y}_i} \bar{Q}^1 \bar{v}(\bar{y}) = \int_{\bar{S}_z} \partial_{\bar{x}_i} \bar{v}(\bar{x}) \psi(\bar{x}) \, d\bar{x}$ is constant for $i \in \{1, \dots, n\}$, we have the vanishing mean value property

$$\int_{\bar{S}_z} \partial_{\bar{x}_i} \left(\bar{v}(\bar{x}) - \bar{Q}^1 \bar{v}(\bar{x}) \right) \psi(\bar{x}) \, d\bar{x} = 0.$$

This, together with Lemma 3.1, leads to (4.10). \square

The following result is an optimal error estimate in the L^p -weighted norm for the averaged Taylor polynomial $Q_z^1 v$, which is instrumental to study $Q_z^m v$ ($m \geq 0$).

Lemma 4.3 (weighted L^p -based error estimate for Q_z^1). *Let $z \in \hat{\mathcal{X}}(\mathcal{T})$. If $v \in W_p^2(\omega, S_z)$, then the following estimate holds*

$$(4.13) \quad \|v - Q_z^1 v\|_{L^p(\omega, S_z)} \lesssim h_z^2 |v|_{W_p^2(\omega, S_z)},$$

where the hidden constant depends only on $C_{p, \omega}$, σ and ψ .

Proof. Since

$$v - Q_z^1 v = (v - Q_z^0 v) - Q_z^0(v - Q_z^0 v) - Q_z^0(Q_z^0 v - v),$$

and $\nabla(v - Q_z^0 v) = \nabla v - Q_z^0 \nabla v$ from (4.6), we can apply (4.9) twice to obtain

$$\|(v - Q_z^0 v) - Q_z^0(v - Q_z^0 v)\|_{L^p(\omega, S_z)} \lesssim h_z \|\nabla(v - Q_z^0 v)\|_{L^p(\omega, S_z)} \lesssim h_z^2 |v|_{W_p^2(\omega, S_z)}.$$

So it remains to estimate the term $R_z^1(v) := Q_z^0(Q_z^1 v - v)$. Since $Q_z^0 v = Q_z^0 Q_z^0 v$, we notice that $R_z^1(v) = Q_z^0(Q_z^1 v - Q_z^0 v)$. Then, using the definition of the averaged Taylor polynomial given by (4.5), we have

$$R_z^1(v) = \int_{S_z} \left(\int_{S_z} \nabla v(x) \cdot (y-x) \psi_z(x) dx \right) \psi_z(y) dy.$$

We exploit the crucial *cancellation property* $R_z^1(p) = 0$ for all $p \in \mathbb{P}_1$ as follows: $R_z^1(v) = R_z^1(v - Q_z^1 v) = 0$. This yields

$$\|R_z^1(v)\|_{L^p(\omega, S_z)}^p = \int_{S_z} \omega \left| \int_{S_z} \left(\int_{S_z} \nabla(v(x) - Q_z^1 v(x)) \cdot (y-x) \psi_z(x) dx \right) \psi_z(y) dy \right|^p$$

Applying Hölder inequality to the innermost integral $I(y)$ leads to

$$|I(y)|^p \lesssim h_z^p \left(\int_{S_z} \omega |\nabla(v(x) - Q_z^1 v(x))|^p dx \right) \left(\int_{S_z} \omega^{-p'/p} \psi_z(x)^{p'} dx \right)^{p/p'}.$$

This is combined with $\int_{S_z} \psi_z(y) dy = 1$ and $\|\psi_z\|_{L^{p'}(\omega^{-p'/p}, S_z)} \|1\|_{L^p(\omega, S_z)} \lesssim 1$, which follows from the definition of ψ_z and the definition (2.2) of the A_p -class, to arrive at

$$(4.14) \quad \|R_z^1(v)\|_{L^p(\omega, S_z)}^p \lesssim h_z^{2p} \int_{S_z} \omega |D^2 v|^p.$$

This yields the desired estimate (4.13). \square

4.4. Induction argument. In order to derive approximation properties of the averaged Taylor polynomial $Q_z^m v$ for any $m \geq 0$, we apply an induction argument. We assume the following estimate as *induction hypothesis*:

$$(4.15) \quad \|v - Q_z^{m-1} v\|_{L^p(\omega, S_z)} \lesssim h_z^m |v|_{W_p^m(\omega, S_z)}.$$

Notice that, for $m = 1$, the induction hypothesis is exactly (4.10), while for $m = 2$ it is given by Lemma 4.3. We have the following general result for any $m \geq 0$.

Lemma 4.4 (weighted L^p -based error estimate for Q_z^m). *Let $z \in \mathfrak{X}(\mathcal{T})$ and $m \geq 0$. If $v \in W_p^{m+1}(\omega, S_z)$, then we have the following approximation result*

$$(4.16) \quad \|v - Q_z^m v\|_{L^p(\omega, S_z)} \lesssim h_z^{m+1} |v|_{W_p^{m+1}(\omega, S_z)},$$

where the hidden constant depends only on $C_{p,\omega}$, σ , ψ and m .

Proof. We proceed as in the proof of Lemma 4.3. Notice, first of all, that

$$v - Q_z^m v = (v - Q_z^m v) - Q_z^{m-1}(v - Q_z^m v) - Q_z^{m-1}(Q_z^m v - v).$$

The induction hypothesis (4.15) yields

$$\|(v - Q_z^m v) - Q_z^{m-1}(v - Q_z^m v)\|_{L^p(\omega, S_z)} \lesssim h_z^m |v - Q_z^m v|_{W_p^m(\omega, S_z)}.$$

Since $D^\alpha Q_z^m v = Q_z^0 D^\alpha v$ for all $|\alpha| = m$, according to property (4.6), the estimate (4.9) yields $|v - Q_z^m v|_{W_p^m(\omega, S_z)} \lesssim h_z |v|_{W_p^{m+1}(\omega, S_z)}$, and then

$$\|(v - Q_z^m v) - Q_z^{m-1}(v - Q_z^m v)\|_{L^p(\omega, S_z)} \lesssim h_z^{m+1} |v|_{W_p^{m+1}(\omega, S_z)}.$$

It thus remains to bound the term

$$R_z^m(v) := Q_z^{m-1}(Q_z^m v - v).$$

Since $Q_z^{m-1}Q_z^{m-1}v = Q_z^{m-1}v$, writing $Q_z^m = Q_z^{m-1} + \sum_{|\beta|=m} T_z^\beta$ with

$$T_z^\beta(v) = \frac{1}{\beta!} \int_{S_z} D^\beta v(\zeta)(x - \zeta)^\beta \psi_z(\zeta) d\zeta,$$

we obtain

$$R_z^m(v) = \sum_{|\beta|=m} Q_z^{m-1} T_z^\beta(v).$$

This representation allows us to write

$$R_z^m(v)(y) = \sum_{|\alpha| < m, |\beta|=m} I_{\alpha,\beta} v(y),$$

with

$$\begin{aligned} I_{\alpha,\beta} v(y) &= \frac{1}{\alpha!} \int_{S_z} \psi_z(x) D_x^\alpha T_z^\beta v(x) (y - x)^\alpha dx \\ &= \frac{1}{\alpha!} \int_{S_z} \psi_z(x) \frac{1}{(\beta - \alpha)!} \int_{S_z} D_\zeta^\beta v(\zeta) (x - \zeta)^{\beta - \alpha} \psi_z(\zeta) d\zeta (y - x)^\alpha dx. \end{aligned}$$

Finally, we notice the following *cancellation property*: $Q_z^m p = p$ for all $p \in \mathbb{P}_m$, whence $R_z^m(p) = 0$. Consequently $R_z^m(v) = R_z^m(v - Q_z^m v)$ implies

$$\|I_{\alpha,\beta} v\|_{L^p(\omega, S_z)}^p \lesssim h_z^{mp} \int_{S_z} \omega(y) \left| \int_{S_z} \psi_z(x) \int_{S_z} D_\zeta^\beta (v - Q_z^m v)(\zeta) \psi_z(\zeta) d\zeta dx \right|^p dy.$$

Combining the identity $D^\beta Q_z^m v = Q_z^0 D^\beta v$, with (4.9) and the bound

$$\|\psi_z\|_{L^{p'}(\omega^{-p'/p}, S_z)} \|1\|_{L^p(\omega, S_z)} \lesssim 1,$$

we infer that

$$\begin{aligned} \|R_z^m v\|_{L^p(\omega, S_z)}^p &\lesssim h_z^{mp} \|1\|_{L^p(\omega, S_z)}^p \|D^m v - D^m Q_z^m v\|_{L^p(\omega, S_z)}^p \|\psi_z\|_{L^p(\omega^{-p'/p}, S_z)}^p \\ &\lesssim h_z^{(m+1)p} |v|_{W_p^{m+1}(\omega, S_z)}^p. \end{aligned}$$

This concludes the proof. \square

The following corollary is a simple consequence of Lemma 4.4.

Corollary 4.5 (weighted W_p^k -based error estimate for Q_z^m). *Let $z \in \mathring{\mathcal{X}}(\mathcal{T})$. If $v \in W_p^{m+1}(\omega, S_z)$ with $m \geq 0$, then*

$$(4.17) \quad |v - Q_z^m v|_{W_p^k(\omega, S_z)} \lesssim h_z^{m+1-k} |v|_{W_p^{m+1}(\omega, S_z)}, \quad k = 0, 1, \dots, m+1,$$

where the hidden constant depends only on $C_{p,\omega}$, σ , ψ and m .

Proof. For $k = 0$, the estimate (4.17) is given by Lemma 4.4, while for $k = m+1$,

$$|v - Q_z^m v|_{W_p^{m+1}(\omega, S_z)} = |v|_{W_p^{m+1}(\omega, S_z)}.$$

For $0 < k < m+1$, we employ property (4.6) of $D^\alpha Q_z^m v$ with $|\alpha| = k$ to write

$$|v - Q_z^m v|_{W_p^k(\omega, S_z)} = \left(\sum_{|\alpha|=k} \|D^\alpha v - Q_z^{m-k} D^\alpha v\|_{L^p(\omega, S_z)}^p \right)^{1/p}.$$

Therefore, applying estimate (4.16) to $\|D^\alpha v - Q_z^{m-k} D^\alpha v\|_{L^p(\omega, S_z)}$, we obtain

$$|v - Q_z^m v|_{W_p^k(\omega, S_z)} \lesssim h_z^{m+1-k} |v|_{W_p^{m+1}(\omega, S_z)},$$

which is the asserted estimate. \square

5. WEIGHTED INTERPOLATION ERROR ESTIMATES

In this section we construct a quasi-interpolation operator $\Pi_{\mathcal{T}}$, based on local averages over stars. This construction is well defined for functions in $L^1(\Omega)$, and thus for functions in the weighted space $L^p(\omega, \Omega)$. It is well known that this type of quasi-interpolation operator is important in the approximation of nonsmooth functions without point values because the Lagrange interpolation operator is not even defined [24, 65]. Moreover, averaged interpolation has better approximation properties than the Lagrange interpolation for anisotropic elements [1]. We refer the reader to [9, 31, 60] for applications of quasi-interpolation.

The construction of $\Pi_{\mathcal{T}}$ is based on the averaged Taylor polynomial defined in (4.5). In § 5.1, using the approximation estimates derived in section 4 together with an invariance property of $\Pi_{\mathcal{T}}$ over the space of polynomials, we derive optimal error estimates for $\Pi_{\mathcal{T}}$ in Muckenhoupt weighted Sobolev norms on simplicial discretizations. The case of rectangular discretizations is considered in § 5.2.

Given $\omega \in A_p(\mathbb{R}^n)$ and $v \in L^p(\omega, \Omega)$, we recall that $Q_z^m v$ is the averaged Taylor polynomial of order m of v over the node z ; see (4.5). We define the quasi-interpolant $\Pi_{\mathcal{T}} v$ as the unique function of $\mathbb{V}(\mathcal{T})$ that satisfies $\Pi_{\mathcal{T}} v(z) = Q_z^m v(z)$ if $z \in \overset{\circ}{\mathcal{N}}(\mathcal{T})$, and $\Pi_{\mathcal{T}} v(z) = 0$ if $z \in \mathcal{N}(\mathcal{T}) \cap \partial\Omega$, i.e.,

$$(5.1) \quad \Pi_{\mathcal{T}} v = \sum_{z \in \overset{\circ}{\mathcal{N}}(\mathcal{T})} Q_z^m v(z) \phi_z.$$

Optimal error estimates for $\Pi_{\mathcal{T}}$ rely on its stability, which follows from the stability of Q_z^m obtained in Lemma 4.1.

Lemma 5.1 (stability of $\Pi_{\mathcal{T}}$). *Let $v \in W_p^k(\omega, S_T)$ with $0 \leq k \leq m+1$ and $T \in \mathcal{T}$. Then, the quasi-interpolant operator $\Pi_{\mathcal{T}}$ defined by (5.1) satisfies the following local stability bound*

$$(5.2) \quad |\Pi_{\mathcal{T}} v|_{W_p^k(\omega, T)} \lesssim \sum_{l=0}^k h_T^{l-k} |v|_{W_p^l(\omega, S_T)}.$$

Proof. Using the definition of $\Pi_{\mathcal{T}}$ given by (5.1), we have

$$|\Pi_{\mathcal{T}} v|_{W_p^k(\omega, T)} \leq \sum_{z \in \overset{\circ}{\mathcal{N}}(T)} \|Q_z^m v\|_{L^\infty(S_z)} |\phi_z|_{W_p^k(\omega, T)}.$$

We resort to Lemma 4.1 to derive

$$|\Pi_{\mathcal{T}} v|_{W_p^k(\omega, T)} \lesssim \sum_{z \in \overset{\circ}{\mathcal{N}}(T)} h_z^{-n} |\phi_z|_{W_p^k(\omega, T)} \|1\|_{L^{p'}(\omega^{-p'/p}, S_z)} \sum_{l=0}^k h_z^l |v|_{W_p^l(\omega, S_z)}.$$

Since $|D^k \phi_z| \lesssim h_z^{-k}$ on S_T and $\omega \in A_p(\mathbb{R}^n)$, we obtain

$$h_z^{-n} |\phi_z|_{W_p^k(\omega, T)} \|1\|_{L^{p'}(\omega^{-p'/p}, S_z)} \lesssim \frac{h_z^{-k}}{h_z^n} \left(\int_{S_z} \omega \right)^{1/p} \left(\int_{S_z} \omega^{-p'/p} \right)^{1/p'} \lesssim h_z^{-k},$$

which, given the definition of S_T , the shape regularity of \mathcal{T} , and the finite overlapping property of stars imply (5.2). \square

5.1. Interpolation error estimates on simplicial discretizations. The quasi-interpolant operator $\Pi_{\mathcal{T}}$ is invariant over the space of polynomials of degree m on simplicial meshes: $\Pi_{\mathcal{T}}v|_{S_z} = v$ for $v \in \mathbb{P}_m(S_z)$ and $z \in \mathring{\mathcal{N}}(\mathcal{T})$ such that $\partial S_z \cap \partial\Omega = \emptyset$. Consequently,

$$(5.3) \quad \Pi_{\mathcal{T}}Q_z^m\phi = Q_z^m\phi. \quad \forall \phi \in L^1(\omega, S_z).$$

This property, together with (4.5), yields optimal interpolation estimates for $\Pi_{\mathcal{T}}$.

Theorem 5.2 (interpolation estimate on interior simplices). *Given $T \in \mathcal{T}$ such that $\partial T \cap \partial\Omega = \emptyset$ and $v \in W_p^{m+1}(\omega, S_T)$, we have the following interpolation error estimate*

$$(5.4) \quad |v - \Pi_{\mathcal{T}}v|_{W_p^k(\omega, T)} \lesssim h_T^{m+1-k} |v|_{W_p^{m+1}(\omega, S_T)}, \quad k = 0, 1, \dots, m+1,$$

where the hidden constant depends only on $C_{p,\omega}$, σ , ψ and m .

Proof. Given $T \in \mathcal{T}$, choose a node $z \in \mathring{\mathcal{N}}(T)$. Property (5.3) yields,

$$|v - \Pi_{\mathcal{T}}v|_{W_p^k(\omega, T)} \leq |v - Q_z^m v|_{W_p^k(\omega, T)} + |\Pi_{\mathcal{T}}(Q_z^m v - v)|_{W_p^k(\omega, T)}.$$

Combining the stability of $\Pi_{\mathcal{T}}$ given by (5.2) together with (4.17) implies

$$|v - \Pi_{\mathcal{T}}v|_{W_p^k(\omega, T)} \lesssim \sum_{l=0}^k h_T^{l-k} |v - Q_z^m v|_{W_p^l(\omega, S_T)} \lesssim h_T^{m+1-k} |v|_{W_p^{m+1}(\omega, S_T)},$$

which is exactly (5.4). \square

By using the fact that, $v \in W_p^{m+1}(\omega, \Omega) \cap \mathring{W}_p^1(\omega, \Omega)$ implies $\Pi_{\mathcal{T}}v|_{\partial\Omega} = 0$ we can extend the results of Theorem 5.2 to boundary elements. The proof is an adaption of standard techniques and, in order to deal with the weight, those of the aforementioned Theorem 5.2. See also Theorem 5.10 below.

Theorem 5.3 (interpolation estimates on Dirichlet simplices). *Let $v \in \mathring{W}_p^1(\omega, \Omega) \cap W_p^{m+1}(\omega, \Omega)$. If $T \in \mathcal{T}$ is a boundary simplex, then (5.4) holds with a constant that depends only on $C_{p,\omega}$, σ and ψ .*

We are now in the position to write a global interpolation estimate.

Theorem 5.4 (global interpolation estimate over simplicial meshes). *Given $\mathcal{T} \in \mathbb{T}$ and $v \in W_p^{m+1}(\omega, \Omega)$, we have the following global interpolation error estimate*

$$(5.5) \quad \left(\sum_{T \in \mathcal{T}} h_T^{-(m+1-k)p} |v - \Pi_{\mathcal{T}}v|_{W_p^k(\omega, T)}^p \right)^{1/p} \lesssim |v|_{W_p^{m+1}(\omega, \Omega)},$$

for $k = 0, \dots, m+1$, where the hidden constant depends only on $C_{p,\omega}$, σ , ψ and m .

Proof. Raise (5.4) to the p -th power and add over all $T \in \mathcal{T}$. The finite overlapping property of stars of \mathcal{T} yields the result. \square

5.2. Anisotropic interpolation estimates on rectangular meshes. Narrow or anisotropic elements are those with disparate sizes in each direction. They are necessary, for instance, for the optimal approximation of functions with a strong directional-dependent behavior such as line and edge singularities, boundary layers, and shocks (see [31, 32, 60]).

Inspired by [31], here we derive interpolation error estimates assuming only that neighboring elements have comparable sizes, thus obtaining results which are valid

for a rather general family of anisotropic meshes. Since symmetry is essential, we assume that $\Omega = (0, 1)^n$, or that Ω is any domain which can be decomposed into n -rectangles. We use below the notation introduced in [31].

We assume that the mesh \mathcal{T} is composed of rectangular elements R , with sides parallel to the coordinate axes. By $\mathbf{v} \in \mathcal{N}(\mathcal{T})$ we denote a node or vertex of the triangulation \mathcal{T} and by $S_{\mathbf{v}}, S_R$ the associated patches; see § 4.1. Given $R \in \mathcal{T}$, we define h_R^i as the length of R in the i -th direction and, if $\mathbf{v} \in \mathcal{N}(\mathcal{T})$, we define $h_{\mathbf{v}}^i = \min\{h_R^i : \mathbf{v} \in R\}$ for $i = 1, \dots, n$. The finite element space is defined by (4.2) with $\mathcal{P} = \mathbb{Q}_1$.

We assume the following weak shape regularity condition: there exists a constant $\sigma > 1$, such that if $R, S \in \mathcal{T}$ are neighboring elements, we have

$$(5.6) \quad \frac{h_R^i}{h_S^i} \leq \sigma, \quad i = 1, \dots, n.$$

Whenever \mathbf{v} is a vertex of R the shape regularity assumption (5.6) implies that $h_{\mathbf{v}}^i$ and h_R^i are equivalent up to a constant that depends only on σ . We define

$$\psi_{\mathbf{v}}(x) = \frac{1}{h_{\mathbf{v}}^1 \dots h_{\mathbf{v}}^n} \psi \left(\frac{\mathbf{v}_1 - x_1}{h_{\mathbf{v}}^1}, \dots, \frac{\mathbf{v}_n - x_n}{h_{\mathbf{v}}^n} \right),$$

which, owing to (5.6) and $r \leq 1/\sigma$, satisfies $\text{supp } \psi_{\mathbf{v}} \subset S_{\mathbf{v}}$. Notice that this function incorporates a different length scale on each direction x_i , which will prove useful in the study of anisotropic estimates.

Given $\omega \in A_p(\mathbb{R}^n)$, and $v \in L^p(\omega, \Omega)$, we define $Q_{\mathbf{v}}^1 v$, the first degree regularized Taylor polynomial of v about the vertex \mathbf{v} as in (4.5). We also define the quasi-interpolation operator $\Pi_{\mathcal{T}}$ as in (5.1), i.e., upon denoting by $\lambda_{\mathbf{v}}$ the Lagrange nodal basis function of $\mathbb{V}(\mathcal{T})$, $\Pi_{\mathcal{T}} v$ reads

$$(5.7) \quad \Pi_{\mathcal{T}} v := \sum_{\mathbf{v} \in \mathcal{N}(\mathcal{T})} Q_{\mathbf{v}}^1 v(\mathbf{v}) \lambda_{\mathbf{v}}.$$

The finite element space $\mathbb{V}(\mathcal{T})$ is not invariant under the operator defined in (5.7). Consequently, we cannot use the techniques for simplicial meshes developed in § 5.1. This, as the results below show, is not a limitation to obtain interpolation error estimates.

Lemma 5.5 (anisotropic L^p -weighted error estimates I). *Let $\mathbf{v} \in \mathcal{N}(\mathcal{T})$. If $v \in W_p^1(\omega, S_{\mathbf{v}})$, then we have*

$$(5.8) \quad \|v - Q_{\mathbf{v}}^0 v\|_{L^p(\omega, S_{\mathbf{v}})} \lesssim \sum_{i=1}^n h_{\mathbf{v}}^i \|\partial_{x_i} v\|_{L^p(\omega, S_{\mathbf{v}})}.$$

If $v \in W_p^2(\omega, S_{\mathbf{v}})$ instead, then the following estimate holds

$$(5.9) \quad \|\partial_{x_j}(v - Q_{\mathbf{v}}^1 v)\|_{L^p(\omega, S_{\mathbf{v}})} \lesssim \sum_{i=1}^n h_{\mathbf{v}}^i \|\partial_{x_i} \partial_{x_j} v\|_{L^p(\omega, S_{\mathbf{v}})},$$

for $j = 1, \dots, n$. In both inequalities, the hidden constants depend only on $C_{p,\omega}$, σ and ψ .

Proof. To exploit the symmetry of the elements we define the map

$$(5.10) \quad \mathcal{F}_{\mathbf{v}} : x \mapsto \bar{x}, \quad \bar{x}_i = \frac{\mathbf{v}_i - x_i}{h_{\mathbf{v}}^i}, \quad i = 1, \dots, n,$$

and proceed exactly as in the proof of Lemma 4.2. \square

Lemma 5.5, in conjunction with the techniques developed in Lemma 4.3 give rise the second order anisotropic error estimates in the weighted L^p -norm.

Lemma 5.6 (anisotropic L^p -weighted error estimate II). *Let $\mathbf{v} \in \hat{\mathcal{R}}(\mathcal{T})$. If $v \in W_p^2(\omega, S_{\mathbf{v}})$, then we have*

$$(5.11) \quad \|v - Q_{\mathbf{v}}^1 v\|_{L^p(\omega, S_{\mathbf{v}})} \lesssim \sum_{i,j=1}^n h_{\mathbf{v}}^i h_{\mathbf{v}}^j \|\partial_{x_i} \partial_{x_j} v\|_{L^p(\omega, S_{\mathbf{v}})},$$

where the hidden constant in the inequality above depends only on $C_{p,\omega}$, σ and ψ .

Proof. Recall that, if $R_{\mathbf{v}}^1(v) = Q_{\mathbf{v}}^0(Q_{\mathbf{v}}^1 v - v)$, then we can write

$$v - Q_{\mathbf{v}}^1 v = (v - Q_{\mathbf{v}}^1 v) - Q_{\mathbf{v}}^0(v - Q_{\mathbf{v}}^1 v) - R_{\mathbf{v}}^1(v).$$

Applying estimates (5.8) and (5.9) successively, we see that

$$\begin{aligned} \|(v - Q_{\mathbf{v}}^1 v) - Q_{\mathbf{v}}^0(v - Q_{\mathbf{v}}^1 v)\|_{L^p(\omega, S_{\mathbf{v}})} &\lesssim \sum_{i=1}^n h_{\mathbf{v}}^i \|\partial_{x_i}(v - Q_{\mathbf{v}}^1 v)\|_{L^p(\omega, S_{\mathbf{v}})} \\ &\lesssim \sum_{i,j=1}^n h_{\mathbf{v}}^i h_{\mathbf{v}}^j \|\partial_{x_i} \partial_{x_j} v\|_{L^p(\omega, S_{\mathbf{v}})}. \end{aligned}$$

It remains then to bound $R_{\mathbf{v}}^1(v)$. We proceed as in the proof of (4.14) in Lemma 4.3. The definition (4.5) of the averaged Taylor polynomial, together with the cancellation property $R_{\mathbf{v}}^1(v) = R_{\mathbf{v}}^1(v - Q_{\mathbf{v}}^1 v)$, implies

$$\|R_{\mathbf{v}}^1(v)\|_{L^p(\omega, S_{\mathbf{v}})}^p \lesssim \sum_{i=1}^n (h_{\mathbf{v}}^i)^p \|\partial_{x_i}(v - Q_{\mathbf{v}}^1 v)\|_{L^p(\omega, S_{\mathbf{v}})}^p \|1\|_{L^p(\omega, S_{\mathbf{v}})}^p \|\psi_{\mathbf{v}}\|_{L^{p'}(\omega^{-p'/p}, S_{\mathbf{v}})}^p$$

Combining (5.9) with the inequality $\|\psi_{\mathbf{v}}\|_{L^{p'}(\omega^{-p'/p}, S_{\mathbf{v}})} \|1\|_{L^p(\omega, S_{\mathbf{v}})} \lesssim 1$, which follows from the the definition of $\psi_{\mathbf{v}}$ and the definition (2.2) of the A_p -class, yields

$$\|R_{\mathbf{v}}^1(v)\|_{L^p(\omega, S_{\mathbf{v}})} \lesssim \sum_{i,j=1}^n h_{\mathbf{v}}^i h_{\mathbf{v}}^j \|\partial_{x_i} \partial_{x_j} v\|_{L^p(\omega, S_{\mathbf{v}})},$$

and leads to the asserted estimate (5.11). \square

The anisotropic error estimate (5.8) together with the weighted L^p stability of the interpolation operator $\Pi_{\mathcal{T}}$, enables us to obtain anisotropic weighted L^p interpolation estimates, as shown in the following Theorem.

Theorem 5.7 (anisotropic L^p -weighted interpolation estimate I). *Let \mathcal{T} satisfy (5.6) and $R \in \mathcal{T}$. If $v \in L^p(\omega, S_R)$, we have*

$$(5.12) \quad \|\Pi_{\mathcal{T}} v\|_{L^p(\omega, R)} \lesssim \|v\|_{L^p(\omega, S_R)}.$$

If, in addition, $w \in W_p^1(\omega, S_R)$ and $\partial R \cap \partial\Omega = \emptyset$, then

$$(5.13) \quad \|v - \Pi_{\mathcal{T}} v\|_{L^p(\omega, R)} \lesssim \sum_{i=1}^n h_R^i \|\partial_{x_i} v\|_{L^p(\omega, S_R)}.$$

The hidden constants in both inequalities depend only on $C_{p,\omega}$, σ and ψ .

Proof. The local stability (5.12) of $\Pi_{\mathcal{T}}$ follows from Lemma 5.1 with $k = 0$. Let us now prove (5.13). Choose a node $\mathbf{v} \in \mathcal{X}(R)$. Since $Q_{\mathbf{v}}^0 v$ is constant, and $\partial R \cap \partial \Omega = \emptyset$, $\Pi_{\mathcal{T}} Q_{\mathbf{v}}^0 v = Q_{\mathbf{v}}^0 v$ over R . This, in conjunction with estimate (5.12), allows us to write

$$\|v - \Pi_{\mathcal{T}} v\|_{L^p(\omega, R)} = \|(I - \Pi_{\mathcal{T}})(v - Q_{\mathbf{v}}^0 v)\|_{L^p(\omega, R)} \lesssim \|v - Q_{\mathbf{v}}^0 v\|_{L^p(\omega, S_R)}.$$

The desired estimate (5.13) now follows from Corollary 3.2. \square

To prove interpolation error estimates on the first derivatives for interior elements we follow [31, Theorem 2.6] and use the symmetries of a cube, thus handling the anisotropy in every direction separately. We start by studying the case of *interior elements*.

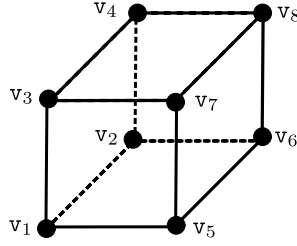


FIGURE 1. An anisotropic cube with sides parallel to the coordinate axes and the labeling of its vertices. The numbering of the vertices proceeds recursively as follows: a cube in dimension m is obtained as the Cartesian product of an $(m - 1)$ -dimensional cube with vertices $\{\mathbf{v}_i\}_{i=1}^{2^{m-1}}$ and an interval, and the new vertices are $\{\mathbf{v}_{i+2^{m-1}}\}_{i=1}^{2^{m-1}}$.

Theorem 5.8 (anisotropic W_p^1 -weighted interpolation estimates). *Let $R \in \mathcal{T}$ be such that $\partial R \cap \partial \Omega = \emptyset$. If $v \in W_p^1(\omega, S_R)$ we have the stability bound*

$$(5.14) \quad \|\nabla \Pi_{\mathcal{T}} v\|_{L^p(\omega, R)} \lesssim \|\nabla v\|_{L^p(\omega, S_R)}.$$

If, in addition, $v \in W_p^2(\omega, S_R)$ we have, for $j = 1, \dots, n$,

$$(5.15) \quad \|\partial_{x_j}(v - \Pi_{\mathcal{T}} v)\|_{L^p(\omega, R)} \lesssim \sum_{i=1}^n h_R^i \|\partial_{x_j} \partial_{x_i} v\|_{L^p(\omega, S_R)}.$$

The hidden constants in the inequalities above depend only on $C_{p, \omega}$, σ and ψ .

Proof. Let us bound the derivative with respect to the first argument x_1 . The other ones follow from similar considerations. As in [31, Theorem 2.5], to exploit the geometry of R , we label its vertices in an appropriate way: vertices that differ only in the first component are denoted \mathbf{v}_i and $\mathbf{v}_{i+2^{n-1}}$ for $i = 1, \dots, 2^{n-1}$; see Figure 1 for the three-dimensional case.

Clearly $v - \Pi_{\mathcal{T}} v = (v - Q_{\mathbf{v}_1}^1 v) + (Q_{\mathbf{v}_1}^1 v - \Pi_{\mathcal{T}} v)$, and the difference $v - Q_{\mathbf{v}_1}^1 v$ is estimated by Lemma 5.5. Consequently, it suffices to consider $q = Q_{\mathbf{v}_1}^1 v - \Pi_{\mathcal{T}} v \in \mathbb{Q}_1(R)$. Thanks to the special labeling of the vertices we have that $\partial_{x_1} \lambda_{\mathbf{v}_{i+2^{n-1}}} = -\partial_{x_1} \lambda_{\mathbf{v}_i}$. Therefore

$$\partial_{x_1} q = \sum_{i=1}^{2^n} q(\mathbf{v}_i) \partial_{x_1} \lambda_{\mathbf{v}_i} = \sum_{i=1}^{2^{n-1}} (q(\mathbf{v}_i) - q(\mathbf{v}_{i+2^{n-1}})) \partial_{x_1} \lambda_{\mathbf{v}_i},$$

so that

$$(5.16) \quad \|\partial_{x_1} q\|_{L^p(\omega, R)} \leq \sum_{i=1}^{2^{n-1}} |q(\mathbf{v}_i) - q(\mathbf{v}_{i+2^{n-1}})| \|\partial_{x_1} \lambda_{\mathbf{v}_i}\|_{L^p(\omega, R)}.$$

This shows that it suffices to estimate $\delta q(\mathbf{v}_1) = q(\mathbf{v}_1) - q(\mathbf{v}_{1+2^{n-1}})$. The definitions of $\Pi_{\mathcal{J}}$, q , and the averaged Taylor polynomial (4.5), imply that

$$(5.17) \quad \delta q(\mathbf{v}_1) = \int P^1 v(x, \mathbf{v}_{1+2^{n-1}}) \psi_{\mathbf{v}_{1+2^{n-1}}}(x) dx - \int P^1 v(x, \mathbf{v}_1) \psi_{\mathbf{v}_1}(x) dx,$$

whence employing the operation \circ defined in (2.1) and changing variables, we get

$$\begin{aligned} \delta q(\mathbf{v}_1) = \int \left(P^1 v(\mathbf{v}_{1+2^{n-1}} - h_{\mathbf{v}_{1+2^{n-1}}} \circ z, \mathbf{v}_{1+2^{n-1}}) \right. \\ \left. - P^1 v(\mathbf{v}_1 - h_{\mathbf{v}_1} \circ z, \mathbf{v}_{1+2^{n-1}}) \right) \psi(z) dz. \end{aligned}$$

Define

$$\theta_1 = \mathbf{v}_{1+2^{n-1}}^1 - \mathbf{v}_1^1 + (h_{\mathbf{v}_1}^1 - h_{\mathbf{v}_{1+2^{n-1}}}^1) z_1,$$

$\theta = (\theta_1, 0, \dots, 0)$ and, for $t \in [0, 1]$, the function $F_z(t) = P^1 v(\mathbf{v}_1 - h_{\mathbf{v}_1} \circ z + t\theta, \mathbf{v}_{1+2^{n-1}})$. Since, for $i = 2, \dots, n$ we have that $h_{\mathbf{v}_1}^i = h_{\mathbf{v}_{1+2^{n-1}}}^i$ and $\mathbf{v}_1^i = \mathbf{v}_{1+2^{n-1}}^i$, by using the definition of θ we arrive at

$$P^1 v(\mathbf{v}_{1+2^{n-1}} - h_{\mathbf{v}_{1+2^{n-1}}} \circ z, \mathbf{v}_{1+2^{n-1}}) - P^1 v(\mathbf{v}_1 - h_{\mathbf{v}_1} \circ z, \mathbf{v}_{1+2^{n-1}}) = F_z(1) - F_z(0),$$

and consequently

$$\delta q(\mathbf{v}_1) = \int (F_z(1) - F_z(0)) \psi(z) dz = \int_0^1 \int F'_z(t) \psi(z) dz dt.$$

Since ψ is bounded and $B = \text{supp } \psi \subset B(0, 1)$, it suffices to bound the integral

$$I(t) = \int_B |F'_z(t)| dz.$$

Invoking the definition of F_z , we get $F'_z(t) = \nabla P^1 v(\mathbf{v}_1 - h_{\mathbf{v}_1} \circ z + t\theta, \mathbf{v}_{1+2^{n-1}}) \cdot \theta$, which, together with the definition of the polynomial $P^1 v$ given by (4.4), yields

$$\begin{aligned} I(t) &\lesssim \int_B |\partial_{x_1}^2 v(\mathbf{v}_1 - h_{\mathbf{v}_1} \circ z + t\theta)| |\mathbf{v}_{1+2^{n-1}}^1 - \mathbf{v}_1^1 + h_{\mathbf{v}_1}^1 z_1 - t\theta_1| |\theta_1| dz \\ &\quad + \sum_{i=2}^n \int_B |\partial_{x_i x_1}^2 v(\mathbf{v}_1 - h_{\mathbf{v}_1} \circ z + t\theta)| |\mathbf{v}_{1+2^{n-1}}^i - \mathbf{v}_1^i + h_{\mathbf{v}_1}^i z_i| |\theta_1| dz \end{aligned}$$

Now, using that $|z| \leq 1$, $0 \leq t \leq 1$, and the definition of θ , we easily see that $|\theta| = |\theta_1| \lesssim h_{\mathbf{v}_1}^1$ as well as $|\mathbf{v}_{1+2^{n-1}}^1 - \mathbf{v}_1^1 + h_{\mathbf{v}_1}^1 z_1 - t\theta_1| \lesssim h_{\mathbf{v}_1}^1$ and $|\mathbf{v}_{1+2^{n-1}}^i - \mathbf{v}_1^i + h_{\mathbf{v}_1}^i z_i| \lesssim h_{\mathbf{v}_1}^i$ for $i = 2, \dots, n$, whence

$$I(t) \lesssim \sum_{i=1}^n h_{\mathbf{v}_1}^1 h_{\mathbf{v}_1}^i \int_B |\partial_{x_i x_1}^2 v(\mathbf{v}_1 - h_{\mathbf{v}_1} \circ z + t\theta)| dz.$$

Changing variables via $y = \mathbf{v}_1 - h_{\mathbf{v}_1} \circ z + t\theta$, we obtain

$$I(t) \lesssim \frac{1}{h_{\mathbf{v}_1}^2 \dots h_{\mathbf{v}_1}^n} \sum_{i=1}^n h_{\mathbf{v}_1}^i \int_{S_R} |\partial_{x_i x_1}^2 v(y)| dy,$$

where we have used that the support of ψ is mapped into $S_{\mathbf{v}_1} \subset S_R$. Hölder's inequality implies

$$I(t) \lesssim \frac{1}{h_{\mathbf{v}_1}^2 \dots h_{\mathbf{v}_1}^n} \|1\|_{L^{p'}(\omega^{-p'/p}, S_R)} \sum_{i=1}^n h_{\mathbf{v}_1}^i \|\partial_{x_i x_i}^2 v\|_{L^p(\omega, S_R)},$$

which combined with $\|\partial_{x_1} \lambda_{\mathbf{v}_1}\|_{L^p(\omega, R)} \|1\|_{L^{p'}(\omega^{-p'/p}, S_R)} \lesssim h_{\mathbf{v}_1}^2 \dots h_{\mathbf{v}_1}^n$, because $\omega \in A_p(\mathbb{R}^n)$, gives the following bound for the first term in (5.16)

$$\delta q(\mathbf{v}_1) \|\partial_{x_1} \lambda_{\mathbf{v}_1}\|_{L^p(\omega, R)} \lesssim \sum_{i=1}^n h_{\mathbf{v}_1}^i \|\partial_{x_i x_i}^2 v\|_{L^p(\omega, S_R)}.$$

This readily yields (5.15).

The estimate (5.14) follows along the same arguments as in [60, Theorem 4.7]. In fact, by the triangle inequality

$$(5.18) \quad \|\nabla \Pi_{\mathcal{J}} v\|_{L^p(\omega, R)} \leq \|\nabla Q_{\mathbf{v}_1}^1 v\|_{L^p(\omega, R)} + \|\nabla(Q_{\mathbf{v}_1}^1 v - \Pi_{\mathcal{J}} v)\|_{L^p(\omega, R)}.$$

The estimate of the first term on the right hand side of (5.18) begins by noticing that the definition of $\psi_{\mathbf{v}_1}$ and the definition (2.2) of the A_p class imply

$$\|\psi_{\mathbf{v}_1}\|_{L^{p'}(\omega^{-p'/p}, S_R)} \|1\|_{L^p(\omega, S_R)} \lesssim 1.$$

This, together with the definition (4.5) of regularized Taylor polynomial $Q_{\mathbf{v}_1}^1 v$, yields

$$\begin{aligned} \|\nabla Q_{\mathbf{v}_1}^1 v\|_{L^p(\omega, R)} &\leq \|\nabla v\|_{L^p(\omega, S_R)} \|\psi_{\mathbf{v}_1}\|_{L^{p'}(\omega^{-p'/p}, S_R)} \|1\|_{L^p(\omega, S_R)} \\ &\lesssim \|\nabla v\|_{L^p(\omega, S_R)}. \end{aligned}$$

To estimate the second term of the right hand side of (5.18), we integrate by parts (5.17), using that $\psi_{\mathbf{v}_i} = 0$ on $\partial S_{\mathbf{v}_i}$ for $i = 1, \dots, n$, to get

$$\begin{aligned} \delta q(\mathbf{v}_1) &= (n+1) \left(\int v(x) \psi_{\mathbf{v}_{1+2^{n-1}}}(x) dx - \int v(x) \psi_{\mathbf{v}_1}(x) dx \right) \\ &\quad - \int v(x) (\mathbf{v}_{1+2^{n-1}} - x) \cdot \nabla \psi_{\mathbf{v}_{1+2^{n-1}}}(x) dx + \int v(x) (\mathbf{v}_1 - x) \cdot \nabla \psi_{\mathbf{v}_1}(x) dx. \end{aligned}$$

In contrast to (5.17), we have now created differences which involve $v(x)$ instead of $\nabla v(x)$. However, the same techniques used to derive (5.15) yield

$$|\delta q(\mathbf{v}_1)| \lesssim \frac{1}{h_{\mathbf{v}_1}^2 \dots h_{\mathbf{v}_1}^n} \|\nabla v\|_{L^p(\omega, S_R)} \|1\|_{L^{p'}(\omega^{-p'/p}, S_R)},$$

which, since $\|\partial_{x_1} \lambda_{\mathbf{v}_1}\|_{L^{p'}(\omega^{-p'/p}, S_R)} \|1\|_{L^p(\omega, S_R)} \lesssim h_{\mathbf{v}_1}^2 \dots h_{\mathbf{v}_1}^n$, results in

$$|\delta q(\mathbf{v}_1)| \|\partial_{x_1} \lambda_{\mathbf{v}_1}\|_{L^{p'}(\omega, R)} \lesssim \|\nabla v\|_{L^p(\omega, S_R)}^n.$$

Replacing this estimate in (5.16), we get

$$\|\nabla(Q_{\mathbf{v}_1}^1 v - \Pi_{\mathcal{J}} v)\|_{L^p(\omega, R)}^n \lesssim \|\nabla v\|_{L^p(\omega, S_R)},$$

which implies the desired result (5.14). This completes the proof. \square

Let us now derive a second order anisotropic interpolation error estimates for the weighted L^p -norm, which is novel even for unweighted norms. For the sake of simplicity, and because the arguments involved are rather technical (as in Theorem 5.8), we prove the result in two dimensions. However, analogous results can be obtained in three and more dimensions by using similar arguments.

Theorem 5.9 (anisotropic L^p -weighted interpolation estimate II). *Let \mathcal{T} satisfy (5.6) and $R \in \mathcal{T}$ such that $\partial R \cap \partial\Omega = \emptyset$. If $v \in W_p^2(\omega, S_R)$, then we have*

$$(5.19) \quad \|v - \Pi_{\mathcal{T}} v\|_{L^p(\omega, R)} \lesssim \sum_{i,j=1}^n h_R^i h_R^j \|\partial_{x_i} \partial_{x_j} v\|_{L^p(\omega, S_R)},$$

where the hidden constant in the inequality above depends only on $C_{p,\omega}$, σ and ψ .

Proof. To exploit the symmetry of R , we label its vertices of R according to Figure 1: $\mathbf{v}_2 = \mathbf{v}_1 + (a, 0)$, $\mathbf{v}_3 = \mathbf{v}_1 + (0, b)$, $\mathbf{v}_4 = \mathbf{v}_1 + (a, b)$. We write $v - \Pi_{\mathcal{T}} v = (v - Q_{\mathbf{v}_1}^1 v) + (Q_{\mathbf{v}_1}^1 v - \Pi_{\mathcal{T}} v)$. The difference $v - Q_{\mathbf{v}_1}^1 v$ is estimated by Lemma 5.6. Consequently, it suffices to estimate $q = Q_{\mathbf{v}_1}^1 v - \Pi_{\mathcal{T}} v$.

Since $q \in \mathbb{V}(\mathcal{T})$,

$$(5.20) \quad q = \sum_{i=1}^4 q(\mathbf{v}_i) \lambda_{\mathbf{v}_i} \implies \|q\|_{L^p(\omega, R)} \leq \sum_{i=1}^4 |q(\mathbf{v}_i)| \|\lambda_{\mathbf{v}_i}\|_{L^p(\omega, R)},$$

and we only need to deal with $q(\mathbf{v}_i)$ for $i = 1, \dots, 4$. Since $q(\mathbf{v}_1) = 0$, in accordance with the definition (5.7) of $\Pi_{\mathcal{T}}$, we just consider $i = 2$. Again, by (5.7), we have

$$q(\mathbf{v}_2) = Q_{\mathbf{v}_1}^1 v(\mathbf{v}_2) - Q_{\mathbf{v}_2}^1 v(\mathbf{v}_2)$$

which, together with the definition of the averaged Taylor polynomial (4.5) and a change of variables, yields

$$q(\mathbf{v}_2) = \int (P^1 v(\mathbf{v}_1 - h_{\mathbf{v}_1} \circ z, \mathbf{v}_2) - P^1 v(\mathbf{v}_2 - h_{\mathbf{v}_2} \circ z, \mathbf{v}_2)) \psi(z) dz.$$

To estimate this integral, we define $\theta = (\theta_1, 0)$, where $\theta_1 = \mathbf{v}_1^1 - \mathbf{v}_2^1 + (h_{\mathbf{v}_2}^1 - h_{\mathbf{v}_1}^1)z_1$, and the function $F_z(t) = P^1 v(\mathbf{v}_2 - h_{\mathbf{v}_2} \circ z + t\theta, \mathbf{v}_2)$. Exploiting the symmetries of R , i.e., using that $\mathbf{v}_1^2 = \mathbf{v}_2^2$ and $h_{\mathbf{v}_1}^2 = h_{\mathbf{v}_2}^2$, we arrive at

$$q(\mathbf{v}_2) = \int (F_z(1) - F_z(0)) \psi(z) dz = \int_0^1 \int F'_z(t) \psi(z) dz dt.$$

By using the definition of the Taylor polynomial $P^1 v$ given in (4.4), we obtain

$$F'_z(t) = \theta D^2 v(\mathbf{v}_2 - h_{\mathbf{v}_2} \circ z + t\theta)(h_{\mathbf{v}_2} \circ z - t\theta)$$

which, together with the definition of θ and the inequalities $|\theta_1| \lesssim h_{\mathbf{v}_2}^1$, $|h_{\mathbf{v}_2}^1 z_1 - t\theta_1| \lesssim h_{\mathbf{v}_2}^1$ and $|h_{\mathbf{v}_2}^2 z_2| \lesssim h_{\mathbf{v}_2}^2$, implies

$$\begin{aligned} \int F'_z(t) \psi(z) dz &\leq \int |\partial_{x_1 x_1} v(\mathbf{v}_2 - h_{\mathbf{v}_2} \circ z + t\theta)| |h_{\mathbf{v}_2}^1 z_1 - t\theta_1| |\theta_1| |\psi(z)| dz \\ &\quad + \int |\partial_{x_2 x_1} v(\mathbf{v}_2 - h_{\mathbf{v}_2} \circ z + t\theta)| |h_{\mathbf{v}_2}^2 z_2| |\theta_1| |\psi(z)| dz \\ &\lesssim h_{\mathbf{v}_2}^1 h_{\mathbf{v}_2}^1 \int |\partial_{x_1 x_1} v(\mathbf{v}_2 - h_{\mathbf{v}_2} \circ z + t\theta)| |\psi(z)| dz \\ &\quad + h_{\mathbf{v}_2}^2 h_{\mathbf{v}_2}^1 \int |\partial_{x_2 x_1} v(\mathbf{v}_2 - h_{\mathbf{v}_2} \circ z + t\theta)| |\psi(z)| dz. \end{aligned}$$

The change of variables $y = \mathbf{v}_2 - h_{\mathbf{v}_2} \circ z + t\theta$ yields

$$\int F'_z(t) \psi(z) dz \lesssim \left(\frac{h_{\mathbf{v}_2}^1}{h_{\mathbf{v}_2}^2} \|\partial_{x_1 x_1} v\|_{L^p(\omega, S_R)} + \|\partial_{x_2 x_1} v\|_{L^p(\omega, S_R)} \right) \|1\|_{L^{p'}(\omega^{-p'/p}, S_R)},$$

where we used Hölder inequality, that the support of ψ is mapped into S_R , and $\psi \in L^\infty(\mathbb{R}^n)$. Finally, using the A_p -condition, we conclude

$$|q(\mathbf{v}_2)| \|\lambda_{\mathbf{v}_2}\|_{L^p(\omega, R)} \lesssim (h_{\mathbf{v}_2}^1)^2 \|\partial_{x_1 x_1} v\|_{L^p(\omega, S_R)} + h_{\mathbf{v}_2}^1 h_{\mathbf{v}_2}^2 \|\partial_{x_2 x_1} v\|_{L^p(\omega, S_R)}.$$

The same arguments above apply to the remaining terms in (5.20). For the term labeled $i = 3$, we obtain

$$|q(\mathbf{v}_3)| \|\lambda_{\mathbf{v}_3}\|_{L^p(\omega, R)} \lesssim (h_{\mathbf{v}_3}^2)^2 \|\partial_{x_2 x_2} v\|_{L^p(\omega, S_R)} + h_{\mathbf{v}_3}^1 h_{\mathbf{v}_3}^2 \|\partial_{x_1 x_2} v\|_{L^p(\omega, S_R)},$$

whereas for the term labeled $i = 4$, rewritten first in the form

$$q(\mathbf{v}_4) = (Q_{\mathbf{v}_1}^1 v(\mathbf{v}_4) - Q_{\mathbf{v}_3}^1 v(\mathbf{v}_4)) + (Q_{\mathbf{v}_3}^1 v(\mathbf{v}_4) - Q_{\mathbf{v}_4}^1 v(\mathbf{v}_4)),$$

we deduce

$$|q(\mathbf{v}_4)| \|\lambda_{\mathbf{v}_4}\|_{L^p(\omega, R)} \lesssim \sum_{i,j=1}^2 h_{\mathbf{v}_4}^i h_{\mathbf{v}_4}^j \|\partial_{x_i} \partial_{x_j} v\|_{L^p(\omega, S_R)}.$$

Finally, replacing the previous estimates back into (5.20), and using the shape regularity properties $h_{\mathbf{v}_i}^j \approx h_R^j$ for $i = 1, \dots, 4$ and $j = 1, 2$, which result from (5.6), shows the desired anisotropic estimate (5.19). \square

Let us comment on the extension of the interpolation estimates of Theorem 5.8 to elements that intersect the Dirichlet boundary, where the functions to be approximated vanish. The proof is very technical and is an adaptation of the arguments of [31, Theorem 3.1] and [60, Theorem 4.8], together with the ideas involved in the proof of Theorem 5.8 to deal with the Muckenhoupt weight $\omega \in A_p(\mathbb{R}^n)$.

Theorem 5.10 (stability and local interpolation: Dirichlet elements). *Let $R \in \mathcal{T}$ be a boundary element. If $v \in W_p^1(\omega, S_R)$ and $v = 0$ on $\partial R \cap \partial\Omega$, then we have*

$$(5.21) \quad \|\nabla \Pi_{\mathcal{T}} v\|_{L^p(\omega, R)} \lesssim \|\nabla v\|_{L^p(\omega, S_R)}.$$

Moreover, if $v \in W_p^2(\omega, S_R)$, then

$$(5.22) \quad \|\partial_{x_j} (v - \Pi_{\mathcal{T}} v)\|_{L^p(\omega, R)} \lesssim \sum_{i=1}^n h_R^i \|\partial_{x_j} \partial_{x_i} v\|_{L^p(\omega, S_R)}.$$

for $j = 1, \dots, n$. The hidden constants in both inequalities depend only on $C_{p,\omega}$, σ and ψ .

6. INTERPOLATION ESTIMATES FOR DIFFERENT METRICS

Given $v \in W_p^1(\omega, S_T)$ with $\omega \in A_p(\mathbb{R}^n)$ and $p \in (1, \infty)$, the goal of this section is to derive local interpolation estimates for v in the space $L^q(\rho, T)$, with weight $\rho \neq \omega$ and Lebesgue exponent $q \neq p$. To derive such an estimate, it is necessary to ensure that the function v belongs to $L^q(\rho, T)$, that is we need to discuss embeddings between weighted Sobolev spaces with different weights and Lebesgue exponents.

Embedding results in spaces of weakly differentiable functions are fundamental in the analysis of partial differential equations. They provide some basic tools in the study of existence, uniqueness and regularity of solutions. To the best of our knowledge, the first to prove such a result was S.L. Sobolev in 1938 [67]. Since then, a great deal of effort has been devoted to studying and improving such inequalities; see, for instance, [12, 59, 71]. In the context of weighted Sobolev spaces, there is an abundant literature that studies the dependence of this result on the properties of the weight; see [38, 41, 45, 46, 47, 48, 49].

Let us first recall the embedding results in the classical case, which will help us draw an analogy for the weighted case. We recall the *Sobolev number* of $W_p^m(\Omega)$

$$\text{sob}(W_p^m) = m - \frac{n}{p},$$

which governs the scaling properties of the seminorm $|v|_{W_p^m(\Omega)}$: the change of variables $\hat{x} = x/h$ transforms Ω into $\hat{\Omega}$ and v into \hat{v} , while the seminorms scale as

$$|\hat{v}|_{W_p^m(\hat{\Omega})} = h^{\text{sob}(W_p^m)} |v|_{W_p^m(\Omega)}.$$

With this notation classical embeddings [40, Theorem 7.26] can be written in a concise way: if Ω denotes an open and bounded domain with Lipschitz boundary, $1 \leq p < n$ and $\text{sob}(W_p^1) \geq \text{sob}(L^q)$, then $\mathring{W}_p^1(\Omega) \hookrightarrow L^q(\Omega)$ and

$$(6.1) \quad \|v\|_{L^q(\Omega)} \lesssim \text{diam}(\Omega)^{\text{sob}(W_p^1) - \text{sob}(L^q)} \|\nabla v\|_{L^p(\Omega)}$$

for all $v \in \mathring{W}_p^1(\Omega)$. When $\text{sob}(W_p^1) > \text{sob}(L^q)$ the embedding is compact. Results analogous to (6.1) in the weighted setting have been studied in [19, 38, 57, 62] for $n > 1$. For $n = 1$, if $\Omega = (0, a)$, $v \in W_p^1(\omega, \Omega)$, and $\omega \in A_p(\mathbb{R}^n)$, Proposition 2.3 yields $v \in W_1^1(\Omega)$. Consequently $v \in L^\infty(\Omega)$, and then $v \in L^q(\rho, \Omega)$ for any weight ρ and $q \in (1, \infty)$. However, to gain intuition on the explicit dependence of the embedding constant in terms of the weights and the Lebesgue measure of the domain, let us consider the trivial case $n = 1$ in more detail. To simplify the discussion assume that $v(0) = v(a) = 0$. We thus have

$$\begin{aligned} \int_0^a |v(x)|^q \rho(x) \, dx &= \int_0^a \rho(x) \left| \int_0^x v'(s) \omega(s)^{1/p} \omega(s)^{-1/p} \, ds \right|^q \, dx \\ &\leq \int_0^a \rho(x) \left(\int_0^x \omega(s) |v'(s)|^p \, ds \right)^{q/p} \left(\int_0^x \omega(s)^{-p'/p} \, ds \right)^{q/p'} \, dx \end{aligned}$$

whence invoking the definition of the the Muckenhoupt class (2.2) we realize that

$$\int_0^a |v(x)|^q \rho(x) \, dx \lesssim \|v'\|_{L^p(\omega, \Omega)}^q |\Omega|^q \rho(\Omega) \omega(\Omega)^{-q/p}.$$

The extension of this result to the n -dimensional case has been studied in [19, 38, 57] and is reported in the next two theorems; see [19] for a discussion.

Theorem 6.1 (embeddings in weighted spaces). *Let $\omega \in A_p(\mathbb{R}^n)$, $p \in (1, q]$, and ρ be a weight that satisfies the strong doubling property (2.4). Let the pair (ρ, ω) satisfy the compatibility condition*

$$(6.2) \quad \frac{r}{R} \left(\frac{\rho(B(x, r))}{\rho(B(x, R))} \right)^{1/q} \leq C_{\rho, \omega} \left(\frac{\omega(B(x, r))}{\omega(B(x, R))} \right)^{1/p},$$

for all $x \in \Omega$ and $r \leq R$. If $v \in \mathring{W}_p^1(\omega, \Omega)$, then $v \in L^q(\rho, \Omega)$ and

$$(6.3) \quad \|v\|_{L^q(\rho, \Omega)} \lesssim \text{diam}(\Omega) \rho(\Omega)^{1/q} \omega(\Omega)^{-1/p} \|\nabla v\|_{L^p(\omega, \Omega)},$$

where the hidden constant depends on the quotient between the radii of the balls inscribed and circumscribed in Ω .

Proof. Given $v \in \mathring{W}_p^1(\omega, \Omega)$ we denote by \tilde{v} its extension by zero to a ball B_R of radius R containing Ω such that $R \leq 2 \operatorname{diam}(\Omega)$. We then apply [19, Theorem 1.5] if $p < q$, or [57, Corollary 2.1] if $p = q$, to conclude

$$\|\tilde{v}\|_{L^q(\rho, B_R)} \lesssim R \rho(B_R)^{1/q} \omega(B_R)^{-1/p} \|\nabla \tilde{v}\|_{L^p(\omega, B_R)}.$$

By assumption ρ satisfies the strong doubling property (2.4) and so, for $B_r \subset \Omega \subset \bar{\Omega} \subset B_R$, we have $\rho(B_R) \lesssim \rho(B_r) \leq \rho(\Omega)$ with a constant that only depends on R/r . Applying this property, together with $\omega(\Omega) \leq \omega(B_R)$, we derive (6.3). \square

Theorem 6.2 (Poincaré inequality). *Let $p \in (1, q]$, ρ be a weight that satisfies the strong doubling property (2.4), and $\omega \in A_p(\mathbb{R}^n)$, and let the pair (ρ, ω) satisfy (6.2). If $v \in W_p^1(\omega, \Omega)$, then there is a constant v_Ω such that*

$$(6.4) \quad \|v - v_\Omega\|_{L^q(\rho, \Omega)} \lesssim \operatorname{diam}(\Omega) \rho(\Omega)^{1/q} \omega(\Omega)^{-1/p} \|\nabla v\|_{L^p(\omega, \Omega)},$$

where the hidden constant depends on the quotient between the radii of the balls inscribed and circumscribed in Ω .

Proof. Since Ω is open and bounded, we can choose $0 < r < R$ such that $\bar{B}_r \subset \Omega \subset \bar{\Omega} \subset B_R$, where B_δ is a ball of radius δ . The extension theorem on weighted Sobolev spaces proved in [22, Theorem 1.1] shows that there exists $\tilde{v} \in W_p^1(\omega, B_R)$ such that $\tilde{v}|_\Omega = v$ and

$$(6.5) \quad \|\nabla \tilde{v}\|_{L^p(\omega, B_R)} \lesssim \|\nabla v\|_{L^p(\omega, \Omega)},$$

where the hidden constant does not depend on v . If $p < q$, then we invoke [38, Theorem 1] and [19, Theorem 1.3] to show that inequality (6.4) holds over B_R with v_Ω being a weighted mean of \tilde{v} in B_R . If $p = q$ instead, we appeal to [57, Remark 2.3] and arrive at the same conclusion. Consequently, we have

$$\|\tilde{v} - v_\Omega\|_{L^q(\rho, \Omega)} \leq \|\tilde{v} - v_\Omega\|_{L^q(\rho, B_R)} \lesssim R \rho(B_R)^{1/q} \omega(B_R)^{-1/p} \|\nabla \tilde{v}\|_{L^p(\omega, B_R)}.$$

The strong doubling property $\rho(B_R) \lesssim \rho(\Omega)$ and $\omega(\Omega) \leq \omega(B_R)$ yield

$$\|\tilde{v} - v_\Omega\|_{L^q(\rho, \Omega)} \lesssim \operatorname{diam}(\Omega) \rho(\Omega)^{1/q} \omega(\Omega)^{-1/p} \|\nabla \tilde{v}\|_{L^p(\omega, B_R)}.$$

Employing (6.5) we finally conclude (6.4). \square

Inequalities (6.3) and (6.4) are generalizations of several classical results. We first consider $\omega = \rho \equiv 1$, for which an easy manipulation shows that (6.2) holds if $\operatorname{sob}(W_p^1) \geq \operatorname{sob}(L^q)$, whence (6.4) reduces to (6.1). We next consider $\rho = \omega \in A_p(\mathbb{R}^n)$, for which (6.2) becomes

$$\omega(B(x, R)) \lesssim \left(\frac{R}{r}\right)^{pq/(q-p)} \omega(B(x, r)).$$

This is a consequence of the strong doubling property (2.4) for ω in conjunction with $|B_R| \approx R^n$, provided the restriction $q \leq pn/(n-1)$ between q and p is valid. Moreover, owing to the so-called *open ended property* of the Muckenhoupt classes [58]: if $\omega \in A_p(\mathbb{R}^n)$, then $\omega \in A_{p-\epsilon}(\mathbb{R}^n)$ for some $\epsilon > 0$, we conclude that $q \leq pn/(n-1) + \delta$ for some $\delta > 0$, thus recovering the embedding results proved by Fabes, Kenig and Serapioni [36, Theorem 1.3] and [36, Theorem 1.5]; see [19] for details.

The embedding result of Theorem 6.2 allows us to obtain polynomial interpolation error estimates in $L^q(\rho, T)$ for functions in $W_p^1(\omega, S_T)$.

Theorem 6.3 (interpolation estimates for different metrics I). *Let \mathcal{T} be a simplicial mesh and $\mathcal{P} = \mathbb{P}_1$ in (4.2). Let the pair $(\rho, \omega) \in A_q(\mathbb{R}^n) \times A_p(\mathbb{R}^n)$ satisfy (6.2). If $v \in W_p^1(\omega, S_T)$ for any $T \in \mathcal{T}$, then*

$$(6.6) \quad \|v - \Pi_{\mathcal{T}}v\|_{L^q(\rho, T)} \lesssim h_T \rho(S_T)^{1/q} \omega(S_T)^{-1/p} \|\nabla v\|_{L^p(\omega, S_T)},$$

where the hidden constant depends only on σ , ψ , $C_{p, \omega}$ and $C_{\rho, \omega}$.

Proof. Given an interior element $T \in \mathcal{T}$, let us denote v_T the constant such that the estimate (6.4) holds true on S_T . Since v_T is constant over S_T , we have that $\Pi_{\mathcal{T}}v_T = v_T$ in T . This, together with the stability bound (5.2) for the operator $\Pi_{\mathcal{T}}$, implies

$$\|v - \Pi_{\mathcal{T}}v\|_{L^q(\rho, T)} = \|(I - \Pi_{\mathcal{T}})(v - v_T)\|_{L^q(\rho, T)} \lesssim \|v - v_T\|_{L^q(\rho, S_T)}.$$

The Poincaré inequality (6.4) and the mesh regularity assumption (5.6) yield

$$\|v - \Pi_{\mathcal{T}}v\|_{L^q(\rho, T)} \lesssim \|v - v_T\|_{L^q(\rho, S_T)} \lesssim h_T \rho(S_T)^{1/q} \omega(S_T)^{-1/p} \|\nabla v\|_{L^p(\omega, S_T)}$$

which is (6.6). A similar argument yields (6.6) on boundary elements. \square

A trivial but important consequence of Theorem 6.3 is the standard, unweighted, interpolation error estimate in Sobolev spaces; see [23, Theorem 3.1.5].

Corollary 6.4 (L^q -based interpolation estimate). *If $p < n$ and $\text{sob}(W_p^1) > \text{sob}(L^q)$, then for all $T \in \mathcal{T}$ and $v \in W_p^1(S_T)$, we have the local error estimate*

$$(6.7) \quad \|v - \Pi_{\mathcal{T}}v\|_{L^q(T)} \lesssim h_T^{\text{sob}(W_p^1) - \text{sob}(L^q)} \|\nabla v\|_{L^p(S_T)},$$

where the hidden constant depends only on σ and ψ .

For simplicial meshes, the invariance property of $\Pi_{\mathcal{T}}$ and similar arguments to those used in § 5.1 enable us to obtain other interpolation estimates. We illustrate this in the following.

Theorem 6.5 (interpolation estimates for different metrics II). *Let \mathcal{T} be a simplicial mesh and $\mathcal{P} = \mathbb{P}_1$ in (4.2). Given $p \in (1, q]$, let the pair $(\omega, \rho) \in A_p(\mathbb{R}^n) \times A_q(\mathbb{R}^n)$ satisfy (6.2). Then, for every $T \in \mathcal{T}$ and every $v \in W_p^2(\omega, S_T)$ we have*

$$(6.8) \quad \|\nabla(v - \Pi_{\mathcal{T}}v)\|_{L^q(\rho, T)} \lesssim h_T \rho(S_T)^{1/q} \omega(S_T)^{-1/p} |v|_{W_p^2(\omega, S_T)},$$

where the hidden constant depends only on σ , ψ , $C_{p, \omega}$ and $C_{\rho, \omega}$.

Proof. Let, again, $T \in \mathcal{T}$ be an interior element, the proof for boundary elements follows from similar arguments. Denote by \mathbf{v} a vertex of T . Since the pair of weights (ω, ρ) satisfies (6.2) the embedding $W_p^2(\omega, S_T) \hookrightarrow W_q^1(\rho, S_T)$ holds and it is legitimate to write

$$\|\nabla(v - \Pi_{\mathcal{T}}v)\|_{L^q(\rho, T)} \leq \|\nabla v - \nabla Q_{\mathbf{v}}^1 v\|_{L^q(\rho, T)} + \|\nabla(Q_{\mathbf{v}}^1 v - \Pi_{\mathcal{T}}v)\|_{L^q(\rho, T)}$$

In view of (5.3) and (5.2), we have

$$\|\nabla(Q_{\mathbf{v}}^1 v - \Pi_{\mathcal{T}}v)\|_{L^q(\rho, T)} \lesssim \|\nabla v - \nabla Q_{\mathbf{v}}^1 v\|_{L^q(\rho, T)}.$$

We now recall (4.6), namely $\nabla Q_{\mathbf{v}}^1 v = Q_{\mathbf{v}}^0 \nabla v$, to end up with

$$\|\nabla(v - \Pi_{\mathcal{T}}v)\|_{L^q(\rho, T)} \lesssim \|\nabla v - Q_{\mathbf{v}}^0 \nabla v\|_{L^q(\rho, T)} \lesssim \|\nabla v - (\nabla v)_T\|_{L^q(\rho, T)},$$

because $Q_{\mathbf{v}}^0 c = c$ for any constant c and $Q_{\mathbf{v}}^0$ is continuous in $L^q(\rho, T)$. Applying (6.4) finally implies (6.8). \square

7. APPLICATIONS

We now present some immediate applications of the interpolation error estimates developed in the previous sections. We recall that $\mathbb{V}(\mathcal{T})$ denotes the finite element space over the mesh \mathcal{T} , $\Pi_{\mathcal{T}}$ the quasi-interpolation operator defined in (5.1), and $U_{\mathcal{T}}$ the Galerkin solution to (1.3).

7.1. Nonuniformly elliptic boundary value problems. We first derive novel error estimates for the finite element approximation of solutions of a *nonuniformly* elliptic boundary value problem. Let Ω be a polyhedral domain in \mathbb{R}^n with Lipschitz boundary, $\omega \in A_2(\mathbb{R}^n)$ and f be a function in $L^2(\omega^{-1}, \Omega)$. Consider problem (1.1) with \mathcal{A} as in (1.2). The natural space to seek a solution u of problem (1.1) is the weighted Sobolev space $H_0^1(\omega, \Omega)$.

Since Ω is bounded and $\omega \in A_2(\mathbb{R}^n)$, Proposition 2.4 shows that $H_0^1(\omega, \Omega)$ is Hilbert. The Poincaré inequality proved in [36, Theorem 1.3] and the Lax-Milgram lemma then imply the existence and uniqueness of a solution to (1.1) as well as (1.3). The following result establishes a connection between u and $U_{\mathcal{T}}$.

Corollary 7.1 (error estimates for nonuniformly elliptic PDE). *Let $\omega \in A_2(\mathbb{R}^n)$ and $\mathbb{V}(\mathcal{T})$ consist of simplicial elements of degree $m \geq 1$ or rectangular elements of degree $m = 1$. If the solution u of (1.1) satisfies $u \in H_0^1(\omega, \Omega) \cap H^{k+1}(\omega, \Omega)$ for some $1 \leq k \leq m$, then we have the following global error estimate*

$$(7.1) \quad \|\nabla(u - U_{\mathcal{T}})\|_{L^2(\omega, \Omega)} \lesssim \|h^k D^{k+1} u\|_{L^2(\omega, \Omega)},$$

where h denotes the local mesh-size function of \mathcal{T} .

Proof. By Galerkin orthogonality we have

$$\|\nabla(u - U_{\mathcal{T}})\|_{L^2(\omega, \Omega)} \lesssim \inf_{V \in \mathbb{V}(\mathcal{T})} \|\nabla(u - V)\|_{L^2(\omega, \Omega)}.$$

Consider $V = \Pi_{\mathcal{T}} u$ and use the local estimates of either Theorem 5.4 or Theorems 5.8 and 5.10, depending on the discretization. This concludes the proof. \square

Remark 7.2 (regularity assumption). We assumed that $u \in H^{m+1}(\omega, \Omega)$ in Corollary 7.1. Since the coefficient matrix \mathcal{A} is not smooth but rather satisfies (1.2), it is natural to ponder whether $u \in H^{m+1}(\omega, \Omega)$ holds. References [18, 21] provide sufficient conditions on \mathcal{A} , Ω and f for this result to be true for $m = 1$.

Remark 7.3 (multilevel methods). Multilevel methods are known to exhibit linear complexity for the solution of the ensuing algebraic systems. We refer to [43] for weights of class A_1 and [20] for weights of class A_2 (including fractional diffusion).

7.2. Elliptic problems with Dirac sources. Dirac sources arise in applications as diverse as modeling of pollutant transport, degradation in an aquatic medium [5] and problems in fractured domains [25]. The analysis of the finite element method applied to such problems is not standard, since in general the solution does not belong to $H^1(\Omega)$ for $n \geq 1$. A priori error estimates in the $L^2(\Omega)$ -norm have been derived in the literature using different techniques. In a two dimensional setting and assuming that the domain is smooth, Babuška [7] derived almost optimal a priori error estimates of order $\mathcal{O}(h^{1-\epsilon})$, for an arbitrary $\epsilon > 0$. Scott [64] improved these estimates by removing the ϵ and thus obtaining an optimal error estimate of order $\mathcal{O}(h^{2-n/2})$ for $n = 2, 3$. It is important to notice, as pointed out in [66, Remark 3.1], that these results leave a “regularity gap”. In other words, the results

of [64] require a C^∞ domain yet the triangulation is assumed to consist of simplices. Using a different technique, Casas [17] obtained the same result for polygonal or polyhedral domains and general regular Borel measures on the right-hand side. Estimates in other norms are also available in the literature [34, 63].

In the context of weighted Sobolev spaces, interpolation estimates and a priori error estimates have been developed in [3, 25] for such problems. We now show how to apply our polynomial interpolation theory to obtain similar results.

Let Ω be a convex polyhedral domain in \mathbb{R}^n with Lipschitz boundary, and x_0 be an interior point of Ω . Consider the following elliptic boundary value problem:

$$(7.2) \quad \begin{cases} -\nabla \cdot (\mathcal{A}\nabla u) + \mathbf{b} \cdot \nabla u + cu = \delta_{x_0}, & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \end{cases}$$

where $\mathcal{A} \in L^\infty(\Omega)$ is a piecewise smooth and uniformly symmetric positive definite matrix, $\mathbf{b} \in W^{1,\infty}(\Omega)^n$, $c \in L^\infty(\Omega)$, and δ_{x_0} denotes the Dirac delta supported at $x_0 \in \Omega$. Existence and uniqueness of u in weighted Sobolev spaces follows from [3, Theorem 1.3] and Lemma 7.7 below, and its asymptotic behavior near x_0 is dictated by that of the Laplacian

$$(7.3) \quad \nabla u(x) \approx |x - x_0|^{1-n}.$$

Denote by $d = \text{diam}(\Omega)$ the diameter of Ω and by $\mathbf{d}_{x_0}(x)$ the scaled Euclidean distance $\mathbf{d}_{x_0}(x) = |x - x_0|/(2d)$ to x_0 . Define the weight

$$(7.4) \quad \varpi(x) = \begin{cases} \frac{\mathbf{d}_{x_0}(x)^{n-2}}{\log^2 \mathbf{d}_{x_0}(x)}, & 0 < \mathbf{d}_{x_0}(x) < \frac{1}{2}, \\ \frac{2^{2-n}}{\log^2 2}, & \mathbf{d}_{x_0}(x) \geq \frac{1}{2}. \end{cases}$$

We now study two important properties of ϖ : $\nabla u \in L^2(\varpi, \Omega)$ and $\varpi \in A_2(\mathbb{R}^n)$.

Lemma 7.4 (regularity of ∇u). *The solution u of (7.2) satisfies $\nabla u \in L^2(\varpi, \Omega)$.*

Proof. Since $\Omega \subset B$, the ball of radius d centered at x_0 , we readily have from (7.3)

$$\int_{\Omega} |\nabla u|^2 \varpi \lesssim \int_B \mathbf{d}_{x_0}(x)^{2(1-n)} \frac{\mathbf{d}_{x_0}(x)^{n-2}}{\log^2 \mathbf{d}_{x_0}(x)} dx \lesssim \int_0^{\frac{1}{2}} \frac{1}{r \log^2 r} dr = \frac{1}{\log 2},$$

which is the asserted result. \square

Lemma 7.5 ($\varpi \in A_2(\mathbb{R}^n)$). *The weight ϖ belongs to the Muckenhoupt class $A_2(\mathbb{R}^n)$ with constant $C_{2,\varpi}$ only depending on d .*

Proof. Let $x_0 = 0$ for simplicity, let $B_r = B_r(y)$ be a ball in \mathbb{R}^n of radius r and center y , and denote $\varpi(B_r) = \int_{B_r} \varpi$ and $\varpi^{-1}(B_r) = \int_{B_r} \varpi^{-1}$. We must show

$$(7.5) \quad \varpi(B_r) \varpi^{-1}(B_r) \lesssim r^{2n} \quad \forall r > 0,$$

with a hidden constant depending solely on d . We split the proof into two cases.

1. Case $|y| < 2r$: Since $B_r(y) \subset B_{3r}(0)$ we infer that

$$\varpi(B_r) \lesssim \int_{B_{3r}(0)} \frac{\left(\frac{|x|}{2d}\right)^{n-2}}{\log^2 \frac{|x|}{2d}} dx \lesssim \int_0^{\frac{3r}{2d}} \frac{s^{2n-3}}{\log^2 s} ds \approx \frac{\left(\frac{3r}{2d}\right)^{2n-2}}{\log^2 \frac{3r}{2d}}$$

and

$$\varpi^{-1}(B_r) \lesssim \int_{B_{3r}(0)} \left(\frac{|x|}{2d}\right)^{2-n} \log^2 \left(\frac{|x|}{2d}\right) dx \lesssim \int_0^{\frac{3r}{2d}} s \log^2 s ds \approx \left(\frac{3r}{2d}\right)^2 \log^2 \frac{3r}{2d},$$

provided $3r < d$. The equivalences \approx can be checked via L'Hôpital's rule for $r \rightarrow 0$. If $3r \geq d$, then both $\varpi(B_r)$ and $\varpi^{-1}(B_r)$ are bounded by constants depending only on d . Therefore, this yields (7.5).

2. Case $|y| \geq 2r$: Since all $x \in B_r(y)$ satisfy $\frac{1}{2}|y| \leq |x| \leq \frac{3}{2}|y|$ we deduce

$$\varpi \leq \min \left\{ \frac{\left(\frac{3|y|}{4d}\right)^{n-2}}{\log^2 \frac{3|y|}{4d}}, \frac{2^{2-n}}{\log^2 2} \right\}, \quad \varpi^{-1} \leq \max \left\{ \left(\frac{|y|}{4d}\right)^{2-n} \log^2 \frac{|y|}{4d}, 2^{n-2} \log^2 2 \right\},$$

whence $\varpi(B_r) \varpi^{-1}(B_r)$ satisfies again (7.5).

This completes the proof. \square

The fact that the weight $\varpi \in A_2(\mathbb{R}^n)$ is the key property for the analysis of discretizations of problem (7.2). Let us apply the results of Theorem 6.1 to this particular weight.

Lemma 7.6 ($H^1(\Omega) \hookrightarrow L^2(\varpi^{-1}, \Omega)$). *Let ϖ be defined in (7.4). If $n < 4$, then the following embedding holds:*

$$H^1(\Omega) \hookrightarrow L^2(\varpi^{-1}, \Omega).$$

Proof. This is an application of Theorem 6.1. We must show when condition (6.2) holds with $p = q = 2$, $\omega = 1$ and $\rho = \varpi^{-1}$. In other words, we need to verify

$$\Lambda(r, R) := \frac{r^{2-n} \varpi^{-1}(B_r)}{R^{2-n} \varpi^{-1}(B_R)} \lesssim 1, \quad \forall r \in (0, R],$$

where both B_r and B_R are centered at $y \in \mathbb{R}^n$. We proceed as in Lemma 7.5 and consider now three cases.

1. $|y| < 2r$. We know from Lemma 7.5 that $\varpi^{-1}(B_r) \lesssim \left(\frac{3r}{2d}\right)^2 \log^2 \left(\frac{3r}{2d}\right)$. Moreover, every $x \in B_R(y)$ satisfies $|x| < |y| + R \leq 3R$ whence

$$\varpi^{-1}(B_R) \geq \int_{B_R} \left(\frac{3|x|}{2d}\right)^{2-n} \log^2 \left(\frac{3|x|}{2d}\right) dx \approx \int_0^{\frac{3R}{2d}} s \log^2 s ds \approx \left(\frac{3R}{2d}\right)^2 \log^2 \left(\frac{3R}{2d}\right).$$

If $n < 4$, then this shows

$$\Lambda(r, R) \lesssim \frac{r^{4-n} \log^2 \left(\frac{3r}{2d}\right)}{R^{4-n} \log^2 \left(\frac{3R}{2d}\right)} \lesssim 1.$$

2. $2r \leq |y| < 2R$. We learn from Lemma 7.5 that

$$\varpi^{-1}(B_r) \lesssim |B_r| \left(\frac{|y|}{4d}\right)^{2-n} \log^2 \left(\frac{|y|}{4d}\right) \lesssim \left(\frac{r}{2d}\right)^2 \log^2 \left(\frac{r}{2d}\right).$$

In addition, any $x \in B_R$ satisfies $|x| \leq |y| + R \leq 3R$ and the same bound as in Case 1 holds for $\varpi^{-1}(B_R)$. Consequently, $\Lambda(r, R) \lesssim 1$ again for $n < 4$.

3. $|y| \geq 2R$. Since still $|y| > 2r$ we have for $\varpi^{-1}(B_r)$ the same upper bound as in Case 2. On the other hand, for all $x \in B_R$ we realize that $|x| \leq |y| + R \leq \frac{3}{2}|y|$ and $\varpi^{-1}(x) \geq \varpi^{-1}\left(\frac{3}{2}y\right)$. Therefore, we deduce

$$\left(\frac{3R}{d}\right)^2 \log^2 \frac{3R}{d} \lesssim R^n \left(\frac{3|y|}{2d}\right)^{2-n} \log^2 \left(\frac{3|y|}{2d}\right) \lesssim \varpi^{-1}(B_R),$$

which again leads to $\Lambda(r, R) \lesssim 1$ for $n < 4$.

This concludes the proof. \square

The embedding of Lemma 7.6 allows us to develop a general theory for equations of the form (7.2) on weighted spaces. To achieve this, define

$$(7.6) \quad a(w, v) = \int_{\Omega} \mathcal{A} \nabla w \cdot \nabla v + \mathbf{b} \cdot \nabla w v + c w v.$$

The following results follow [3, 25].

Lemma 7.7 (inf-sup conditions). *The bilinear form a , defined in (7.6), satisfies*

$$(7.7) \quad 1 \lesssim \inf_{w \in H_0^1(\varpi, \Omega)} \sup_{v \in H_0^1(\varpi^{-1}, \Omega)} \frac{a(w, v)}{\|\nabla w\|_{L^2(\varpi, \Omega)} \|\nabla v\|_{L^2(\varpi^{-1}, \Omega)}},$$

$$(7.8) \quad 1 \lesssim \inf_{v \in H_0^1(\varpi^{-1}, \Omega)} \sup_{w \in H_0^1(\varpi, \Omega)} \frac{a(w, v)}{\|\nabla w\|_{L^2(\varpi, \Omega)} \|\nabla v\|_{L^2(\varpi^{-1}, \Omega)}}.$$

Proof. We divide the proof into several steps:

1. We first obtain an orthogonal decomposition of $L^2(\varpi^{-1}, \Omega)$ [25, Lemma 2.1]: for every $\mathbf{q} \in L^2(\varpi^{-1}, \Omega)$ there is a unique couple $(\boldsymbol{\sigma}, v) \in \mathbb{X} := L^2(\varpi^{-1}, \Omega) \times H_0^1(\varpi^{-1}, \Omega)$ such that

$$(7.9) \quad \mathbf{q} = \boldsymbol{\sigma} + \nabla v, \quad \int_{\Omega} \mathcal{A} \boldsymbol{\sigma} \cdot \nabla w = 0, \quad \forall w \in H_0^1(\varpi, \Omega),$$

$$(7.10) \quad \|\boldsymbol{\sigma}\|_{L^2(\varpi^{-1}, \Omega)} + \|\nabla v\|_{L^2(\varpi^{-1}, \Omega)} \lesssim \|\mathbf{q}\|_{L^2(\varpi^{-1}, \Omega)}.$$

To see this, we let $\mathbb{Y} := L^2(\varpi^{-1}, \Omega) \times H_0^1(\varpi, \Omega)$, write (7.9) in mixed form

$$\mathcal{B}[(\boldsymbol{\sigma}, v), (\boldsymbol{\tau}, w)] := \int_{\Omega} \boldsymbol{\sigma} \cdot \boldsymbol{\tau} + \int_{\Omega} \nabla v \cdot \boldsymbol{\tau} + \int_{\Omega} \mathcal{A} \boldsymbol{\sigma} \cdot \nabla w = \int_{\Omega} \mathbf{q} \cdot \boldsymbol{\tau} \quad \forall (\boldsymbol{\tau}, w) \in \mathbb{Y},$$

and apply the generalized Babuška-Brezzi inf-sup theory [11, Theorem 2.1], [25, Lemma 2.1]. This requires only that \mathcal{A} be positive definite along with the trivial fact that $\phi \in L^2(\varpi^{-1}, \Omega)$ implies $\varpi^{-1}\phi \in L^2(\varpi, \Omega)$.

2. Set $|\mathbf{b}| = c = 0$ and let $w \in H_0^1(\varpi, \Omega)$ be given. According to Step 1 we can decompose $\mathbf{q} = \varpi \nabla w \in L^2(\varpi^{-1}, \Omega)$ into $\mathbf{q} = \boldsymbol{\sigma} + \nabla v$. Invoking (7.9), as in [25, Corollary 2.2] and [3, Proposition 1.1], we infer that

$$\int_{\Omega} \mathcal{A} \nabla w \cdot \nabla v = \int_{\Omega} \mathcal{A} \nabla w \cdot \mathbf{q} - \int_{\Omega} \mathcal{A} \nabla w \cdot \boldsymbol{\sigma} = \int_{\Omega} \varpi \mathcal{A} \nabla w \cdot \nabla w \approx \int_{\Omega} \varpi |\nabla w|^2,$$

whence, using (7.10) in the form $\|\nabla v\|_{L^2(\varpi^{-1}, \Omega)} \lesssim \|\nabla w\|_{L^2(\varpi, \Omega)}$, we deduce the inf-sup condition (7.7).

3. As in [3], we show that for every $F \in H_0^1(\varpi^{-1}, \Omega)'$ the problem

$$w \in H_0^1(\varpi, \Omega) : \quad a(w, v) = \langle F, v \rangle, \quad \forall v \in H_0^1(\varpi^{-1}, \Omega),$$

is well posed. To this end, we decompose $w = w_1 + w_2 \in H_0^1(\varpi, \Omega)$, with

$$(7.11) \quad w_1 \in H_0^1(\varpi, \Omega) : \quad \int_{\Omega} \mathcal{A} \nabla w_1 \cdot \nabla v = \langle F, v \rangle, \quad \forall v \in H_0^1(\varpi^{-1}, \Omega),$$

$$(7.12) \quad w_2 \in H_0^1(\Omega) : \quad a(w_2, v) = - \int_{\Omega} (\mathbf{b} \cdot \nabla w_1 + c w_1) v, \quad \forall v \in H_0^1(\Omega).$$

In fact, if problems (7.11) and (7.12) have a unique solution, then we obtain

$$\begin{aligned} a(w, v) &= a(w_1 + w_2, v) \\ &= \int_{\Omega} \mathcal{A} \nabla w_1 \cdot \nabla v + \int_{\Omega} (\mathbf{b} \cdot \nabla w_1 + c w_1) v + a(w_2, v) = \langle F, v \rangle, \end{aligned}$$

for any $v \in H_0^1(\varpi^{-1}, \Omega) \subset H_0^1(\Omega)$. The conclusion of Step 2 shows that (7.11) is well posed. The Cauchy-Schwarz inequality and Lemma 7.6 yield

$$\int_{\Omega} (\mathbf{b} \cdot \nabla w_1 + c w_1) v \lesssim \|w_1\|_{H^1(\varpi, \Omega)} \|v\|_{L^2(\varpi^{-1}, \Omega)} \lesssim \|F\|_{H_0^1(\varpi^{-1}, \Omega)} \|\nabla v\|_{L^2(\varpi^{-1}, \Omega)},$$

which combines with the fact that $a(\cdot, \cdot)$ satisfies the inf-sup condition in $H_0^1(\Omega)$ [8, Theorem 5.3.2 - Part I] to show that (7.12) is well posed as well.

Finally, the general inf-sup theory [35] [61, Theorem 2] guarantees the validity of the two inf-sup conditions (7.7) and (7.8). This concludes the proof. \square

We also have the following discrete counterpart of Lemma 7.7. We refer to [25, Lemma 3.3] and [3, Theorem 2.1] for similar results which, however, do not exploit the Muckenhoupt structure of the weight ϖ .

Lemma 7.8 (discrete inf-sup conditions). *Let \mathcal{T} be a quasi-uniform mesh of size h consisting of simplices. If $\mathbb{V}(\mathcal{T})$ is made of piecewise linears, then the bilinear form a , defined in (7.6), satisfies:*

$$\begin{aligned} 1 &\lesssim \inf_{W \in \mathbb{V}(\mathcal{T})} \sup_{V \in \mathbb{V}(\mathcal{T})} \frac{a(W, V)}{\|\nabla W\|_{L^2(\varpi, \Omega)} \|\nabla V\|_{L^2(\varpi^{-1}, \Omega)}}, \\ 1 &\lesssim \inf_{V \in \mathbb{V}(\mathcal{T})} \sup_{W \in \mathbb{V}(\mathcal{T})} \frac{a(W, V)}{\|\nabla W\|_{L^2(\varpi, \Omega)} \|\nabla V\|_{L^2(\varpi^{-1}, \Omega)}}. \end{aligned}$$

where the hidden constants depend on $C_{2, \varpi}$ but not on h .

Proof. We proceed as in Lemma 7.7. We define the spaces of piecewise constants

$$\mathbb{V}_0(\mathcal{T}) = \mathbb{W}_0(\mathcal{T}) = \{\mathbf{Q} \in L^\infty(\Omega) : \mathbf{Q}|_T \in \mathbb{R}^n, \forall T \in \mathcal{T}\},$$

those of piecewise linears $\mathbb{V}_1(\mathcal{T}) = \mathbb{W}_1(\mathcal{T}) = \mathbb{V}(\mathcal{T})$, and endow the product spaces $\mathbb{V}_0(\mathcal{T}) \times \mathbb{V}_1(\mathcal{T})$ and $\mathbb{W}_0(\mathcal{T}) \times \mathbb{W}_1(\mathcal{T})$ with the norms of \mathbb{X} and \mathbb{Y} respectively, the latter spaces being defined in Lemma 7.7. Given $\mathbf{Q} \in \mathbb{V}_0(\mathcal{T})$, we need the following orthogonal decomposition — a discrete counterpart of (7.9)-(7.10): find $\Sigma \in \mathbb{V}_0(\mathcal{T})$, $V \in \mathbb{V}_1(\mathcal{T})$ so that

$$(7.13) \quad \mathbf{Q} = \Sigma + \nabla V, \quad \int_{\Omega} \mathcal{A} \Sigma \cdot \nabla W = 0, \quad \forall W \in \mathbb{W}_1(\mathcal{T}),$$

$$(7.14) \quad \|\Sigma\|_{L^2(\varpi^{-1}, \Omega)} + \|\nabla V\|_{L^2(\varpi^{-1}, \Omega)} \lesssim \|\mathbf{Q}\|_{L^2(\varpi^{-1}, \Omega)}.$$

We first have to verify that the bilinear form \mathcal{B} satisfies a discrete inf-sup condition, as in Step 1 of Lemma 7.7. We just prove the most problematic inf-sup

$$\|\nabla W\|_{L^2(\varpi, \Omega)} \lesssim \sup_{\mathbf{T} \in \mathbb{V}_0(\mathcal{T})} \frac{\int_{\Omega} \mathcal{A} \mathbf{T} \cdot \nabla W}{\|\mathbf{T}\|_{L^2(\varpi^{-1}, \Omega)}}.$$

We let $\mathbf{T} = \varpi_{\mathcal{T}} \nabla W \in \mathbb{V}_0(\mathcal{T})$, where $\varpi_{\mathcal{T}}$ is the piecewise constant weight defined on each element $T \in \mathcal{T}$ as $\varpi_{\mathcal{T}}|_T = |T|^{-1} \int_T \varpi$. Since $\nabla W \in \mathbb{V}_0(\mathcal{T})$, we get

$$\int_{\Omega} \mathcal{A} \mathbf{T} \cdot \nabla W = \int_{\Omega} \varpi_{\mathcal{T}} \mathcal{A} \nabla W \cdot \nabla W \approx \int_{\Omega} \varpi_{\mathcal{T}} \nabla W \cdot \nabla W = \int_{\Omega} \varpi |\nabla W|^2,$$

and

$$\int_{\Omega} \varpi^{-1} |\mathbf{T}|^2 = \sum_{T \in \mathcal{T}} \int_T |T|^{-2} \varpi^{-1} \left(\int_T \varpi \right)^2 |\nabla W|_T|^2 \leq C_{2, \varpi} \int_{\Omega} \varpi |\nabla W|^2.$$

We employ a similar calculation to perform Step 2 of Lemma 7.7, and the rest is exactly the same as in Lemma 7.7. The proof is thus complete. \square

The numerical analysis of a finite element approximation to the solution of problem (7.2) is now a consequence of the interpolation estimates developed in section 6.

Corollary 7.9 (error estimate for elliptic problems with Dirac sources). *Assume that $n < 4$ and let $u \in H_0^1(\varpi, \Omega)$ be the solution of (7.2) and $U_{\mathcal{T}} \in \mathbb{V}(\mathcal{T})$ be the finite element solution to (7.2). If \mathcal{T} is simplicial, quasi-uniform and of size h , we have the following error estimate*

$$(7.15) \quad \|u - U_{\mathcal{T}}\|_{L^2(\Omega)} \lesssim h^{2-n/2} |\log h| \|\nabla u\|_{L^2(\varpi, \Omega)}.$$

Proof. We employ a duality argument. Let $\varphi \in H_0^1(\Omega)$ be the solution of

$$(7.16) \quad a(v, \varphi) = \int_{\Omega} (u - U_{\mathcal{T}}) v \quad \forall v \in H_0^1(\Omega),$$

which is the adjoint of (7.2). Since Ω is convex and polyhedral, and the coefficients $\mathcal{A}, \mathbf{b}, c$ are sufficiently smooth, we have the standard regularity pick-up [40]:

$$(7.17) \quad \|\varphi\|_{H^2(\Omega)} \lesssim \|u - U_{\mathcal{T}}\|_{L^2(\Omega)}.$$

This, together with Lemma 7.6, allows us to conclude that, if $n < 4$,

$$\varphi \in H^2(\Omega) \cap H_0^1(\Omega) \hookrightarrow H_0^1(\varpi^{-1}, \Omega).$$

Moreover, Theorem 6.5 yields the error estimate

$$\|\nabla(\varphi - \Pi_{\mathcal{T}}\varphi)\|_{L^2(\varpi^{-1}, \Omega)} \lesssim \sigma(h) \|\varphi\|_{H^2(\Omega)}.$$

with

$$\sigma(h) = h(\varpi^{-1}(B_h))^{\frac{1}{2}} |B_h|^{-\frac{1}{2}} \lesssim h^{2-\frac{n}{2}} |\log h|.$$

Let $\Phi_{\mathcal{T}} \in \mathbb{V}(\mathcal{T})$ be the Galerkin solution to (7.16). Galerkin orthogonality and the continuity of the form a on $H_0^1(\varpi, \Omega) \times H_0^1(\varpi^{-1}, \Omega)$ yield

$$(7.18) \quad \|u - U_{\mathcal{T}}\|_{L^2(\Omega)}^2 = a(u, \varphi - \Phi_{\mathcal{T}}) \lesssim \|\nabla u\|_{L^2(\varpi, \Omega)} \|\nabla(\varphi - \Phi_{\mathcal{T}})\|_{L^2(\varpi^{-1}, \Omega)}.$$

The discrete inf-sup conditions of Lemma 7.8 and the continuity of the form a allow us to conclude that

$$\|\nabla(\varphi - \Phi_{\mathcal{T}})\|_{L^2(\varpi^{-1}, \Omega)} \lesssim \|\nabla(\varphi - \Pi_{\mathcal{T}}\varphi)\|_{L^2(\varpi^{-1}, \Omega)}.$$

Combining this bound with (7.17) and (7.18) results in

$$\|u - U_{\mathcal{T}}\|_{L^2(\Omega)}^2 \lesssim \sigma(h) \|\nabla u\|_{L^2(\varpi, \Omega)} \|u - U_{\mathcal{T}}\|_{L^2(\Omega)},$$

which is the asserted estimate (7.15) in disguise. \square

Remark 7.10 (an interpolation result). For any $\beta \in (-n, n)$ we can consider the weight $\mathbf{d}_{x_0}(x)^\beta$, which belongs to the $A_2(\mathbb{R}^n)$ Muckenhoupt class. Theorem 5.4 and Theorems 5.8 and 5.10 show that

$$\|u - \Pi_{\mathcal{T}}u\|_{L^2(\mathbf{d}_{x_0}^\beta, \Omega)} \lesssim \|h\nabla u\|_{L^2(\mathbf{d}_{x_0}^\beta, \Omega)}.$$

This extends the interpolation error estimates of [3, Proposition 4.6], which are valid for $\beta \in (-n, 0)$ only.

7.3. Fractional powers of uniformly elliptic operators. We finally examine finite element approximations of solutions to fractional differential equations; we refer the reader to [60] for further details. Let Ω be a polyhedral domain in \mathbb{R}^n ($n \geq 1$), with boundary $\partial\Omega$. Given a piecewise smooth and uniformly symmetric positive definite matrix $\mathcal{A} \in L^\infty(\Omega)$ and a nonnegative function $c \in L^\infty(\Omega)$, define the differential operator

$$\mathcal{L}w = -\operatorname{div}(\mathcal{A}\nabla w) + cw.$$

Given $f \in H^{-1}(\Omega)$, the problem of finding $u \in H_0^1(\Omega)$ such that $\mathcal{L}u = f$ has a unique solution. Moreover, the operator $\mathcal{L} : \mathcal{D}(\mathcal{L}) \subset L^2(\Omega) \rightarrow L^2(\Omega)$ with domain $\mathcal{D}(\mathcal{L}) = H^2(\Omega) \cap H_0^1(\Omega)$ has a compact inverse [44, Theorem 2.4.2.6]. Therefore, there exists a sequence of eigenpairs $\{\lambda_k, \varphi_k\}_{k=1}^\infty$, with $\lambda_k > 0$, such that

$$\mathcal{L}\varphi_k = \lambda_k\varphi_k, \quad \text{in } \Omega \quad \varphi_k|_{\partial\Omega} = 0.$$

The sequence $\{\varphi_k\}_{k=1}^\infty$ is an orthonormal basis of $L^2(\Omega)$.

In this case, for $s \in (0, 1)$, we define the fractional powers of \mathcal{L}_0 (where the sub-index is used to indicate the homogeneous Dirichlet boundary conditions) by

$$w = \sum_k w_k \varphi_k \quad \implies \quad \mathcal{L}_0^s w = \sum_k \lambda_k^s w_k \varphi_k.$$

It is possible also to show that $\mathcal{L}_0^s : \mathbb{H}^s(\Omega) \rightarrow \mathbb{H}^{-s}(\Omega)$ is an isomorphism, where

$$(7.19) \quad \mathbb{H}^s(\Omega) = \begin{cases} H^s(\Omega), & s \in (0, \frac{1}{2}), \\ H_{00}^{1/2}(\Omega), & s = \frac{1}{2}, \\ H_0^s(\Omega), & s \in (\frac{1}{2}, 1), \end{cases}$$

and $\mathbb{H}^{-s}(\Omega)$ denotes its dual space. We are interested in finding numerical solutions to the following fractional differential equation: given $s \in (0, 1)$ and a function $f \in \mathbb{H}^{-s}(\Omega)$, find u such that

$$(7.20) \quad \mathcal{L}_0^s u = f.$$

The fractional operator \mathcal{L}_0^s is *nonlocal* (see [55, 15, 14]). To localize it, Caffarelli and Silvestre showed in [15] that any power of the fractional Laplacian in \mathbb{R}^n can be determined as a Dirichlet-to-Neumann operator via an extension problem on the upper half-space \mathbb{R}_+^{n+1} . For a bounded domain Ω and more general operators, this result has been extended and adapted in [16] and [69], respectively. This way the nonlocal problem (7.20) is replaced by the local one

$$-\operatorname{div}(y^\alpha \mathbf{A} \nabla \mathcal{U}) + y^\alpha c \mathcal{U} = 0$$

with $\alpha := 1 - 2s$, $\mathbf{A} = \operatorname{diag}\{\mathcal{A}, 1\} \in \mathbb{R}^{(n+1) \times (n+1)}$, posed in the semi-infinite cylinder

$$\mathcal{C} = \{(x', y) : x' \in \Omega, y \in (0, \infty)\},$$

and subject to a Neumann condition at $y = 0$ involving f . Since \mathcal{C} is an unbounded domain, this problem cannot be directly approximated with finite-element-like techniques. However, as [60, Proposition 3.1] shows, the solution to this problem decays exponentially in the extended variable y so that, by truncating the cylinder \mathcal{C} to

$$\mathcal{C}_\mathcal{Y} = \Omega \times (0, \mathcal{Y}),$$

and setting a vanishing Dirichlet condition on the upper boundary $y = \mathcal{Y}$, we only incur in an exponentially small error in terms of \mathcal{Y} [60, Theorem 3.5].

Define

$$\mathring{H}_L^1(y^\alpha, \mathcal{C}_\mathcal{Y}) = \{v \in H^1(y^\alpha, \mathcal{C}_\mathcal{Y}) : v = 0 \text{ on } \partial_L \mathcal{C}_\mathcal{Y} \cup \Omega \times \{\mathcal{Y}\}\},$$

where $\partial_L \mathcal{C}_\mathcal{Y} = \partial\Omega \times (0, \mathcal{Y})$ is the lateral boundary. As [60, Proposition 2.5] shows, the trace operator $\mathring{H}_L^1(y^\alpha, \mathcal{C}_\mathcal{Y}) \ni w \mapsto \text{tr}_\Omega w \in \mathbb{H}^s(\Omega)$ is well defined. The aforementioned problem then reads: find $\mathcal{U} \in \mathring{H}_L^1(y^\alpha, \mathcal{C}_\mathcal{Y})$ such that for all $v \in \mathring{H}_L^1(y^\alpha, \mathcal{C}_\mathcal{Y})$

$$(7.21) \quad \int_{\mathcal{C}_\mathcal{Y}} y^\alpha ((\mathbf{A}\nabla \mathcal{U}) \cdot \nabla v + c\mathcal{U}v) = d_s \langle f, \text{tr}_\Omega v \rangle_{\mathbb{H}^{-s}(\Omega) \times \mathbb{H}^s(\Omega)},$$

where $\langle \cdot, \cdot \rangle_{\mathbb{H}^s(\Omega) \times \mathbb{H}^{-s}(\Omega)}$ denotes the duality pairing between $\mathbb{H}^s(\Omega)$ and $\mathbb{H}^{-s}(\Omega)$ and d_s is a positive normalization constant which depends only on s .

The second order regularity of the solution \mathcal{U} of (7.21), with $\mathcal{C}_\mathcal{Y}$ being replaced by \mathcal{C} , is much worse in the pure y direction as the following estimates from [60, Theorem 2.6] reveal

$$(7.22) \quad \|\mathcal{L}_{x'} \mathcal{U}\|_{L^2(y^\alpha, \mathcal{C})} + \|\partial_y \nabla_{x'} \mathcal{U}\|_{L^2(y^\alpha, \mathcal{C})} \lesssim \|f\|_{\mathbb{H}^{1-s}(\Omega)},$$

$$(7.23) \quad \|\mathcal{U}_{yy}\|_{L^2(y^\beta, \mathcal{C})} \lesssim \|f\|_{L^2(\Omega)},$$

where $\beta > 2\alpha + 1$. This suggests that *graded* meshes in the extended variable y play a fundamental role.

We construct a mesh over $\mathcal{C}_\mathcal{Y}$ with cells of the form $T = K \times I$ with $K \subset \Omega$ being an element that is isoparametrically equivalent either to $[0, 1]^n$ or the unit simplex in \mathbb{R}^n and $I \subset \mathbb{R}$ is an interval. Exploiting the Cartesian structure of the mesh it is possible to handle anisotropy in the extended variable and, much as in § 5.2, obtain estimates of the form

$$\begin{aligned} \|v - \Pi_{\mathcal{T}} v\|_{L^2(y^\alpha, T)} &\lesssim h_{\mathbf{v}'} \|\nabla_{x'} v\|_{L^2(y^\alpha, S_T)} + h_{\mathbf{v}''} \|\partial_y v\|_{L^2(y^\alpha, S_T)}, \\ \|\partial_{x_j}(v - \Pi_{\mathcal{T}} v)\|_{L^2(y^\alpha, T)} &\lesssim h_{\mathbf{v}'} \|\nabla_{x'} \partial_{x_j} v\|_{L^2(y^\alpha, S_T)} + h_{\mathbf{v}''} \|\partial_y \partial_{x_j} v\|_{L^2(y^\alpha, S_T)}, \end{aligned}$$

with $j = 1, \dots, n+1$ and where $h_{\mathbf{v}'} = \min\{h_K : \mathbf{v}' \text{ is a vertex of } K\}$, and $h_{\mathbf{v}''} = \min\{h_I : \mathbf{v}'' \text{ is a vertex of } I\}$; see [60, Theorems 4.6–4.9] for details. However, since $\mathcal{U}_{yy} \approx y^{-\alpha-1}$ as $y \approx 0$, we realize that $\mathcal{U} \notin H^2(y^\alpha, \mathcal{C}_\mathcal{Y})$ and the second estimate is not meaningful for $j = n+1$. In view of the regularity estimate (7.23) it is necessary to measure the regularity of \mathcal{U}_{yy} with a stronger weight and thus compensate with a graded mesh in the extended dimension. This makes anisotropic estimates essential.

We consider the graded partition of the interval $[0, \mathcal{Y}]$ with mesh points

$$(7.24) \quad y_k = \left(\frac{k}{M}\right)^\gamma \mathcal{Y}, \quad k = 0, \dots, M,$$

where $\gamma > 3/(1-\alpha)$, along with a quasi-uniform triangulation \mathcal{T}_Ω of the domain Ω . We construct the mesh $\mathcal{T}_\mathcal{Y}$ as the tensor product of \mathcal{T}_Ω and the partition given in (7.24); hence $\#\mathcal{T} = M \#\mathcal{T}_\Omega$. Assuming that $\#\mathcal{T}_\Omega \approx M^n$ we have $\#\mathcal{T}_\mathcal{Y} \approx M^{n+1}$. Finally, since \mathcal{T}_Ω is shape regular and quasi-uniform, $h_{\mathcal{T}_\Omega} \approx (\#\mathcal{T}_\Omega)^{-1/n}$. All these considerations allow us to obtain the following result.

Corollary 7.11 (error estimate for fractional powers of elliptic operators). *Let \mathcal{T} be a graded tensor product grid, which is quasi-uniform in Ω and graded in the extended variable so that (7.24) hold. If $\mathbb{V}(\mathcal{T})$ is made of bilinear elements, then the solution of (7.21) and its Galerkin approximation $U_\mathcal{T} \in \mathbb{V}(\mathcal{T})$ satisfy*

$$\|\mathcal{U} - U_\mathcal{T}\|_{\mathring{H}_L^1(y^\alpha, \mathcal{C})} \lesssim |\log(\#\mathcal{T}_\mathcal{Y})|^s (\#\mathcal{T}_\mathcal{Y})^{-1/(n+1)} \|f\|_{\mathbb{H}^{1-s}(\Omega)},$$

where $\mathcal{Y} \approx \log(\#\mathcal{T}_{\mathcal{Y}})$. Alternatively, if u denotes the solution of (7.20), then

$$\|u - U_{\mathcal{T}}(\cdot, 0)\|_{\mathbb{H}^s(\Omega)} \lesssim |\log(\#\mathcal{T}_{\mathcal{Y}})|^s (\#\mathcal{T}_{\mathcal{Y}})^{-1/(n+1)} \|f\|_{\mathbb{H}^{1-s}(\Omega)}$$

Proof. First of all, notice that $y^\alpha \in A_2(\mathbb{R}^{n+1})$ for $\alpha \in (-1, 1)$. Owing to the exponential decay of \mathcal{U} , and the choice of the parameter \mathcal{Y} , it suffices to estimate $\mathcal{U} - \Pi_{\mathcal{T}_{\mathcal{Y}}}\mathcal{U}$ on the mesh $\mathcal{T}_{\mathcal{Y}}$; see [60, § 4.1]. To do so, we notice that if I_1 and I_2 are neighboring cells on the partition of $[0, \mathcal{Y}]$, then the weak regularity condition (5.6) holds. Thus, we decompose the mesh $\mathcal{T}_{\mathcal{Y}}$ into the sets

$$\mathcal{T}_0 = \{T \in \mathcal{T}_{\mathcal{Y}} : S_T \cap (\bar{\Omega} \times \{0\}) = \emptyset\}, \quad \mathcal{T}_1 = \{T \in \mathcal{T}_{\mathcal{Y}} : S_T \cap (\bar{\Omega} \times \{0\}) \neq \emptyset\},$$

and apply our interpolation theory developed in Theorems 5.8 and 5.10 for interior and boundary elements respectively, together with the local regularity estimates for the function \mathcal{U} derived in [60, Theorem 2.9]. \square

The error estimates with graded meshes are quasi-optimal in both regularity and order. Error estimates for quasi-uniform meshes are suboptimal in terms of order [60, Section 5]. Mesh anisotropy is thus able to capture the singular behavior of the solution \mathcal{U} and restore optimal decay rates.

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